

x3pdy (3-Phase Delta-to-Y Transformer)

Associated Symbols:	x3pdy
License Requirements:	OPT_TEMPLATE_LIB
Part Category:	Magnetic Templates
Related Topics:	Introduction to Magnetic Templates

Functional Description

The **x3pdy** model is a linear, three-phase, two-winding transformer in a delta-to-Y configuration. You can specify either electrical arguments (*lp*, *ls*) or magnetic arguments (*np*, *ns*, *len*, *area*, *ur*). Values for electrical arguments override those for magnetic arguments. The *k*, *rp*, and *rs* arguments are used with both electrical and magnetic arguments.

Template Description Sections

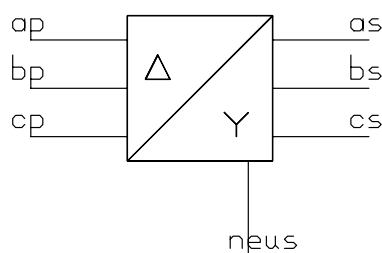
[Connection Points](#)

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x3pdy Connection Points

Name	Type	Description
ap	electrical	phase a, primary winding
bp	electrical	phase b, primary winding
cp	electrical	phase c, primary winding
as	electrical	phase a, secondary winding
bs	electrical	phase b, secondary winding
cs	electrical	phase c, secondary winding
neus	electrical	neutral secondary connection



Three-phase delta-to-Y transformer (x3pdy)

x3pdy Symbol Properties

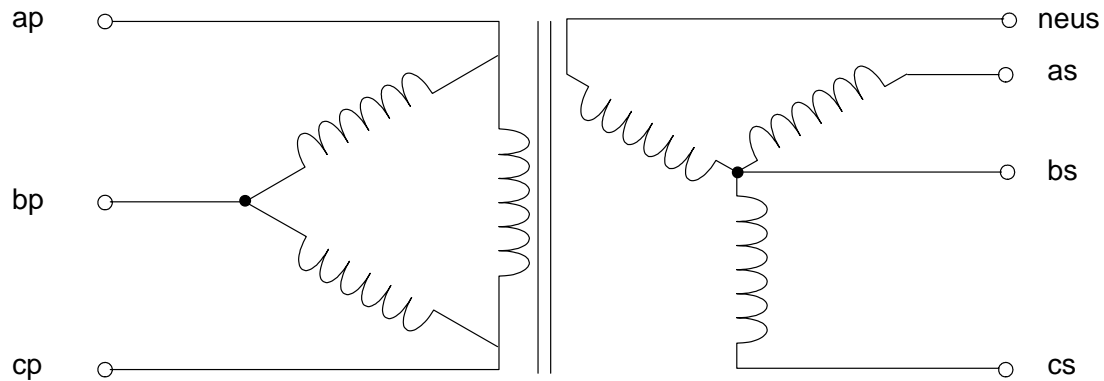
Property

primitive	Description:	This symbol calls the template x3pdy , which models a 2-winding transformer in the three-phase delta to y configuration template that allows you to specify electrical arguments (<i>lp</i> , <i>ls</i>) or magnetic arguments (<i>np</i> , <i>ns</i> , <i>len</i> , <i>area</i> , <i>ur</i>). Specifying electrical arguments overrides the magnetic arguments.
ref	Description:	Suffix appended to a template name that uniquely identifies a part in a schematic.
	Default:	If not specified, is assigned by the schematic capture tool
	Example Input:	Can be any alpha_numeric string
lp	Description:	Inductance of primary winding. Specifying <i>lp</i> and <i>ls</i> overrides the magnetic arguments (<i>np</i> , <i>ns</i> , <i>len</i> , <i>area</i> , <i>ur</i>).
	Default (units):	undef (H)
	Example Input:	3e-2
ls	Description:	Inductance of secondary winding. Specifying <i>lp</i> and <i>ls</i> overrides the magnetic arguments (<i>np</i> , <i>ns</i> , <i>len</i> , <i>area</i> , <i>ur</i>).
	Default (units):	undef (H)
	Example Input:	2e-3
np	Description:	Number of winding turns in primary winding
	Default (units):	undef (turns)
	Example Input:	60
ns	Description:	Number of winding turns in secondary winding
	Default (units):	undef (turns)
	Example Input:	4
len	Description:	Magnetic path length of core
	Default (units):	undef (m)
	Example Input:	3e-2
area	Description:	Cross-sectional area of magnetic path
	Default (units):	undef (m ²)
	Example Input:	6e-5
ur	Description:	Relative permeability of linear core
	Default (units):	1 (—)
	Example Input:	1
k	Description:	Coupling coefficient (see Usage Notes).
	Default (units):	1 (—)
	Example Input:	0.98
rp	Description:	Winding resistance of primary winding
	Default (units):	0 (Ω)
	Example Input:	1m
rs	Description:	Winding resistance of secondary winding

Default (units): 0
(Ω)
Example Input: 1m

x3pdy Usage Notes

The **x3pdy** model constructs a delta-to-Y, three-transformer configuration using the **xfr** model (linear, two-winding transformer). This configuration of three primary windings and three secondary windings is shown in the following figure.



Three-phase delta-to-Y transformer

Each instance of the **xfr** transformer uses the same argument values from **x3pdy** (i.e., each primary winding has the same specifications as the other two primaries; each secondary winding has the same specifications as the other two secondaries).

You can specify a value for the coupling coefficient (k) in the following range:

$$-1 \leq k \leq +1$$

For an iron core, the value of k is nearly 1. For an air core, k assumes a very small positive value. If k is specified less than zero, it reverses the polarity of the transformer.