

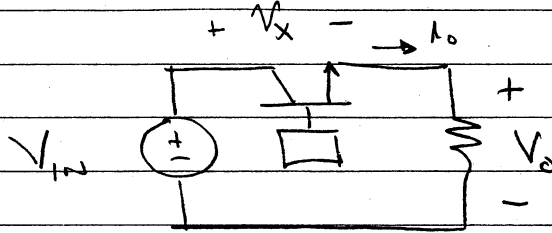
# Power Electronics Notes - D. Perreault



## Introduction: Switching power electronics

Read KSV Ch 1

Linear regulator



Control  $V_x$  such that  $V_o = V_{o,REF}$

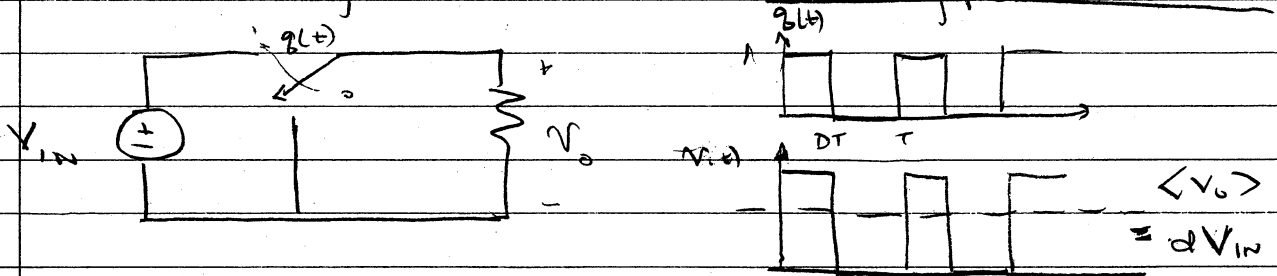
→ simple, accurate, high-bandwidth

but  $P_{diss} = \langle V_x I_o \rangle > 0$

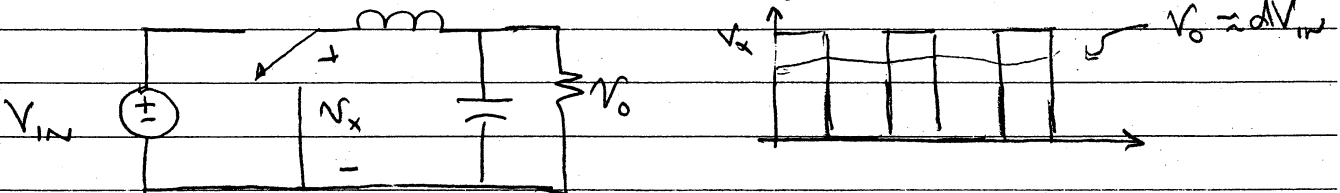
$$\eta = \frac{P_{out}}{P_{in}} = \frac{V_o I_o}{V_{in} I_o} = \frac{V_o}{V_{in}}$$

(@  $V_{in} = 15V, V_o = 5V \rightarrow \eta = 33\%$ )

For Efficiency we will consider switching power converters

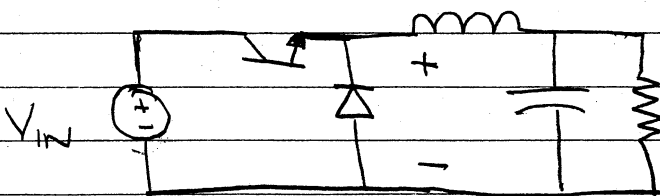


Add Filtering



NOTE: ONLY LOSSLESS ELEMENTS

L, C energy storage



Switches } block V carry I NOT at same time!!

★ Use semiconductors as switches

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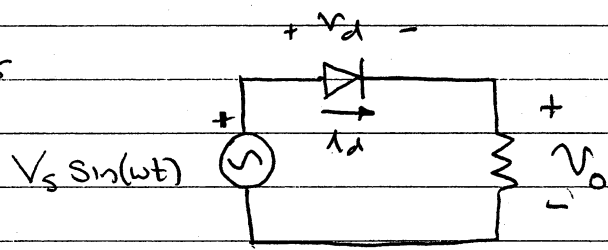
★★

## Introduction to analysis techniques

### ★ Method of assumed states

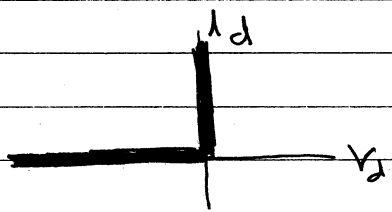
Semiconductor switches are typically not fully controllable. Lets consider how to analyze a switching circuit in time domain:

#### Simple Rectifiers



Diodes: Uncontrolled

- Cannot sustain positive voltage (will turn on)
- Cannot sustain negative current (will turn off)



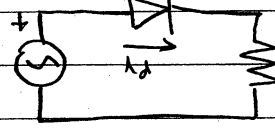
The method of assumed states allows us to figure out which un/semi-controlled switches are on as a function of time.

1. Assume a state (on/off) for all semi/un controlled switches
2. Calculate voltages + currents in the system (Linear circuit theory)
3. See if any switch conditions are violated  
 e.g. "on" diode has negative current  
 "off" diode has positive voltages
4. IF no violations → done  
 IF violation assume a new set of states

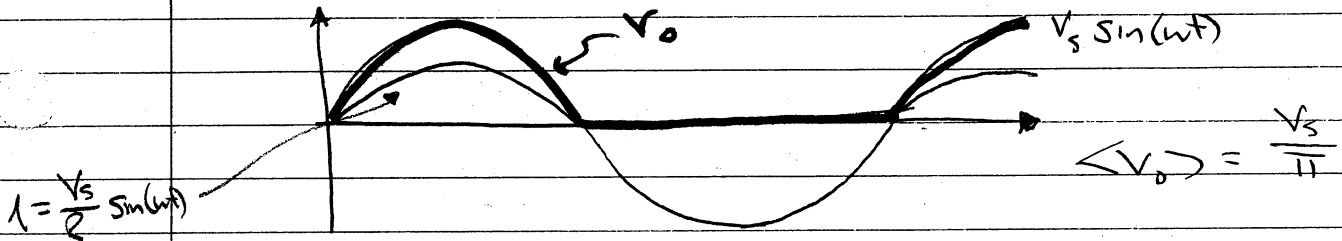
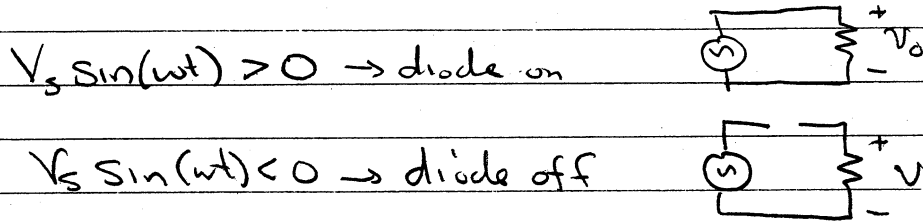
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Simple Rectifier

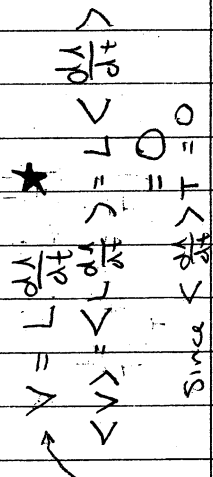
Example:  $V_s \sin(\omega t)$   
(Trivial but fundamental)



- IF  $V_s \sin(\omega t) > 0$  and we assume diode off:  $v_d > 0$   
since this is not possible diode must be on during this condit.
- IF  $V_s \sin(\omega t) < 0$  and we assume diode on:  $i_d < 0$   
since this is not possible diode must be off during this condit.



Very simple example but principle works in general



In power electronics we are often interested in the periodic steady state.

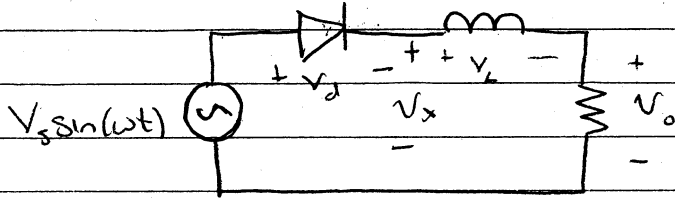
In periodic steady state the system returns to the same point at the end of every cycle (beginning matches end) so things are operating cyclicly.

IN P.S.S. inductor  $\langle v_L \rangle = 0 \rightarrow$  average  $\frac{dv_L}{dt} = 0$

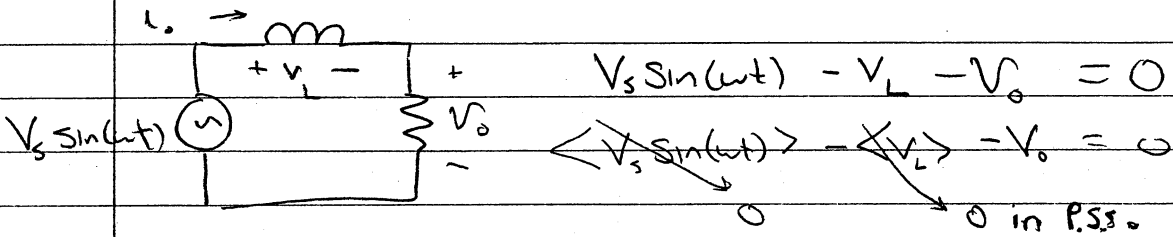
capacitor  $\langle v_C \rangle = 0 \rightarrow$  average  $\frac{dv_C}{dt} = 0$

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The P.S.S. conditions are useful for analysis. Consider adding a filter to smooth the ripple current in our simple rectifier

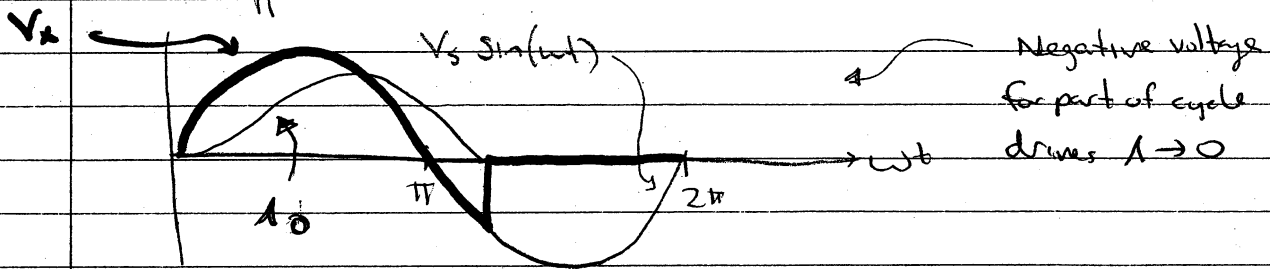


If we assume diode is always on in P.S.S. Then



If diode were always on  $\langle v_o \rangle = 0$  and  $i_o$  must be  $< 0$  part of the time.  $\therefore$  we know diode must turn off during part of cycle by math. Assumed states

what happens:



Exact analysis in KSV sect 3.2.2. Good for review of time-domain analysis.

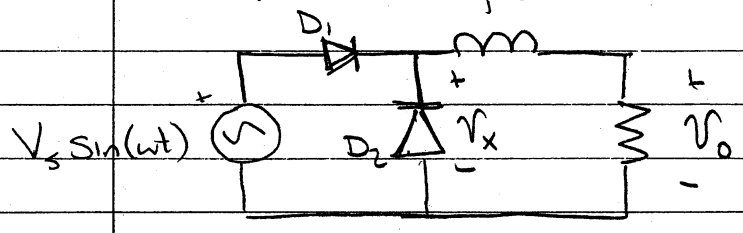
main point: Math, Ass. States + P.S.S. conditions are useful tools to determine system analysis

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Now, in P.S.S.  $\langle V_x \rangle = \langle V_o \rangle$ , since  $\langle V_L \rangle = 0$

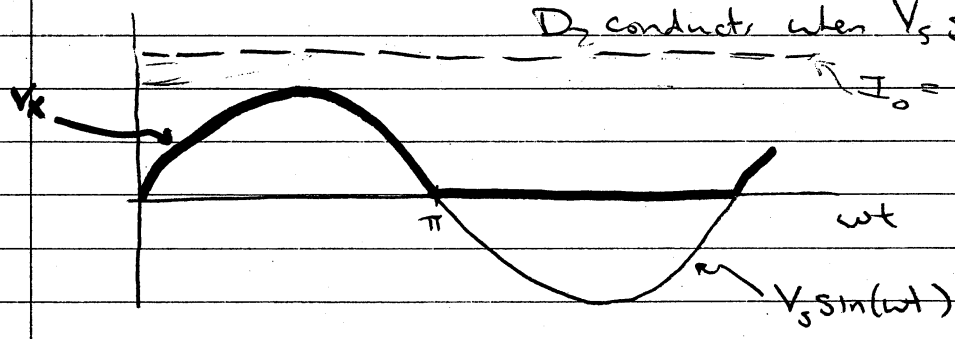
$\langle V_x \rangle$  is pos  $\frac{1}{2}$  sin plus some neg,  $\frac{1}{2}$  sin, so we lose some voltage as compared to a  $\frac{1}{2}$  sin.

Soln: Free-wheeling diode  $\rightarrow$  Half-wave Rectifier



$D_2$  clamps so that  $V_x$  never goes negative.  $\rightarrow$  "freewheels"

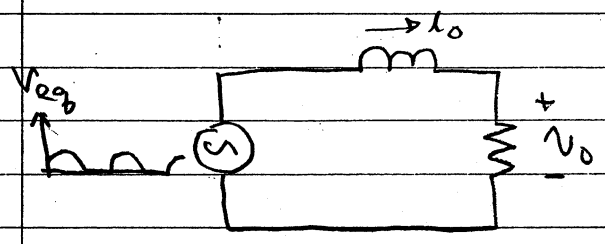
Use meth. ass. states  $D_1$  conducts when  $V_s \sin \omega t > 0$   
 $D_2$  conducts when  $V_s \sin \omega t < 0$



$\langle V_L \rangle = 0$  in p.s.s.  $\therefore \langle V_o \rangle = \langle V_x \rangle = \frac{1}{2\pi} \int_0^\pi V_s \sin(\phi) d\phi = \frac{V_s}{\pi}$

Note: This circuit is rarely used today for several reasons, but the analysis technique is the key point. Full-wave rectifier is more common.

\* Note: For analyzing output current, output voltage etc. we can do an equivalent-source replacement



linear circuit with sum of fourier sources.

$$I_{eq} = \sum_{n=0}^{\infty} A_n \cos(n\omega t + \phi_n)$$