

# ✓ General Description

The GA8512 is a voltage mode, step-down DC-DC converter that is designed to meet 2A output current and utilizes PWM control scheme that switches with 300KHz fixed frequency. This device includes a reference voltage source, error amplifier, oscillation circuit, P-channel MOSFET, and etc.

The input voltage range of GA8512 is from 3.6V to 18V, and provides adjustable output voltage range from 0.8V to  $V_{\rm IN}$  for customers in application.

The GA8512 provides an enable function that can be controlled by external logic signal and excellent regulation during line or load transient due to the internal compensation. Other features of thermal protection, current limit and short circuit protection are also included. Due to the low Drain-Source resistance of internal power MOSFET, the GA8512 provides a high efficiency step-down application. It can also operate with a maximum duty cycle of 100% for use in low drop-out conditions.

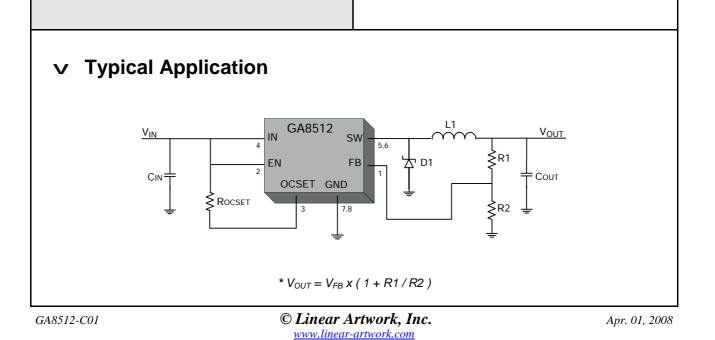
The package is available in a standard SOP-8L.

### ✓ Features

- Adjustable Output Voltage from 0.8V to  $V_{\ensuremath{\mathsf{IN}}}$
- Operating Input Voltage up to 18V
- Great Output Capability: 2A
- Oscillation Frequency: 300KHz
- Built-in P-channel MOSFET
- External ON/OFF Control Function
- Low Shutdown Current: 1uA
- Current Limit and Thermal Protection
- Short Circuit Protection
- Stable With Low ESR Output Ceramic Capacitor
- SOP-8L Package
- All Products meet Rohs Standard

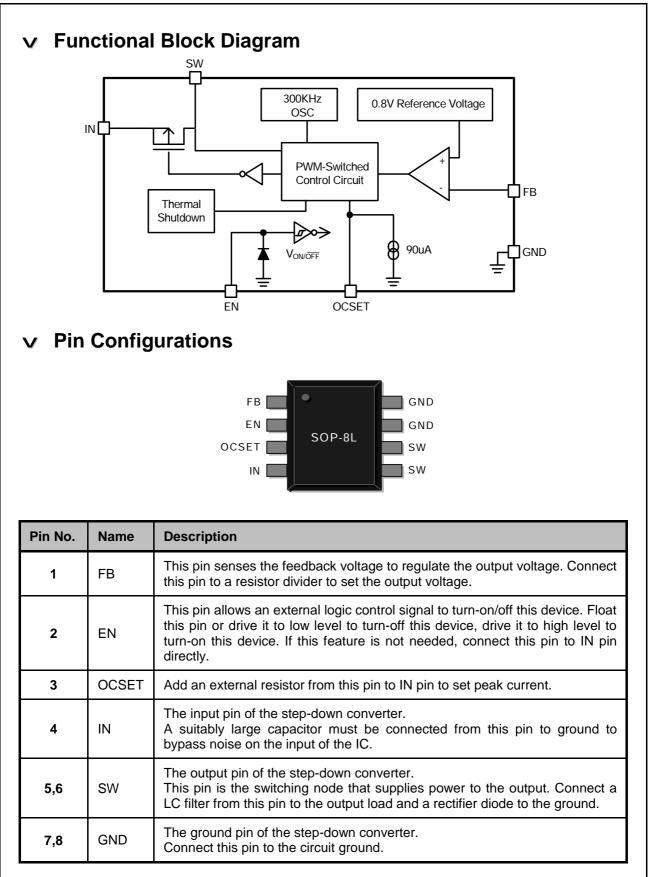
# ✓ Applications

- Broadband Communication Device
- LCD TV / Monitor
- Storage Device
- Wireless Application

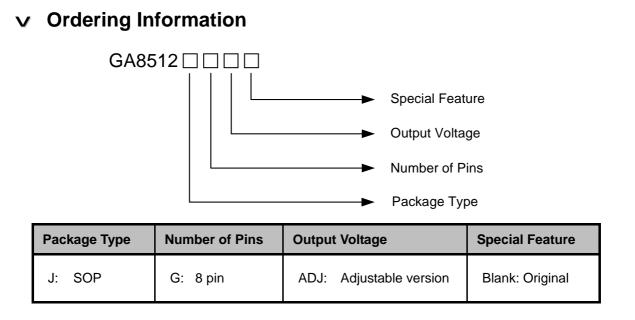


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# ✓ Marking Information



## 123 - Product Code

| Part Number | Output Voltage | Package Type | Product Code |
|-------------|----------------|--------------|--------------|
| GA8512JGADJ | ADJ            | SOP-8L       | AAA          |

### **45** - **Date Code**

| Year<br>Week | xxx0 | xxx1 | xxx2 | xxx3 | xxx4 | xxx5 | xxx6 | xxx7 | xxx8 | xxx9 |
|--------------|------|------|------|------|------|------|------|------|------|------|
| 01           | AA   | CA   | EA   | GA   | IA   | KA   | MA   | OA   | RA   | TA   |
| 02           | AB   | СВ   | EB   | GB   | IB   | KB   | MB   | OB   | RB   | ΤB   |
|              |      |      |      |      |      |      |      |      |      |      |
| -            | -    | -    | -    | -    | -    |      | -    | -    | -    |      |
| 26           | AZ   | CZ   | ΕZ   | GZ   | IZ   | ΚZ   | MZ   | OZ   | RZ   | ΤZ   |
| 27           | BA   | DA   | FA   | HA   | JA   | LA   | NA   | PA   | SA   | UA   |
|              | •    | •    | •    | •    | •    | •    | •    | •    | •    |      |
| •            | •    | •    | •    | •    | •    | •    | •    | •    | •    | •    |
| 51           | BY   | DY   | FY   | ΗY   | JY   | LY   | NY   | PY   | SY   | UY   |
| 52           | ΒZ   | DZ   | FZ   | HZ   | JZ   | LZ   | NZ   | ΡZ   | SZ   | UZ   |

GA8512-C01

| Absolute Maximum Ratings            |                               |  |  |  |
|-------------------------------------|-------------------------------|--|--|--|
| Parameter                           | Rating                        |  |  |  |
| Input Voltage                       | 20V                           |  |  |  |
| SW Pin Voltage Range                | -0.5V ~ V <sub>IN</sub> +0.5V |  |  |  |
| FB Pin Voltage Range                | -0.3V ~ V <sub>IN</sub>       |  |  |  |
| EN Pin Voltage Range                | -0.3V ~ V <sub>IN</sub> +0.3V |  |  |  |
| Storage Temperature Range           | -65°C ~ 150°C                 |  |  |  |
| Junction Temperature                | 150°C                         |  |  |  |
| Lead Soldering Temperature (10 sec) | 300°C                         |  |  |  |

These are stress ratings only and functional operation is not implied. Exposure to absolute maximum ratings for prolonged time periods may affect device reliability. All voltages are with respect to ground.

# ✓ Recommended Operating Conditions

| Parameter                  | Rating        |
|----------------------------|---------------|
| Input Voltage Range        | 3.6V ~ 18V    |
| Junction Temperature Range | -40°C ~ 125°C |

These are conditions under which the device functions but the specifications might not be guaranteed. For guaranteed specifications and test conditions, please see the *Electrical Specifications*.

# ✓ Package Information

| Parameter                                   | Package | Symbol  | Maximum | Unit   |
|---|---------|---------|---------|--------|
| Thermal Resistance<br>(Junction to Case)    |         | ο JC    | 20      | °C / W |
| Thermal Resistance<br>(Junction to Ambient) | SOP-8L  | heta ja | 60      | °C / W |

# ✓ Electrical Specifications

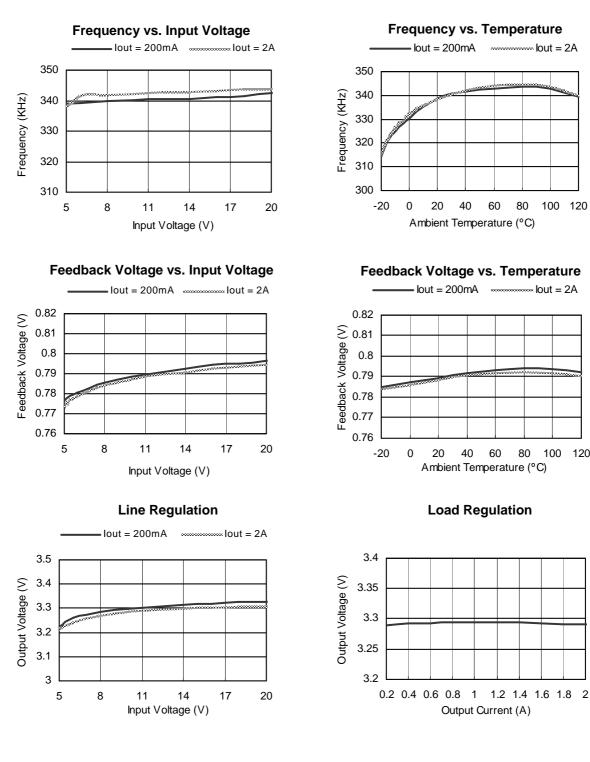
 $V_{IN}$ =12V,  $V_{OUT}$  set to 3.3V,  $T_A$ =25°C, unless otherwise noted.

| Parameter                                | Symbol              | Test Condition   | Min   | Тур | Max   | Units |  |
|--|---------------------|--|-------|-----|-------|-------|--|
| Feedback Voltage                         | Vfb                 | I <sub>LOAD</sub> =0.1A  | 0.784 | 0.8 | 0.816 | V     |  |
|  |                     | V <sub>IN</sub> =12V, V <sub>OUT</sub> =5V, I <sub>LOAD</sub> =2A  |       | 92  |       | %     |  |
| Efficiency                               | η                   | V <sub>IN</sub> =5V, V <sub>OUT</sub> =3.3V, I <sub>LOAD</sub> =2A                                       |       | 90  |       |       |  |
| Oscillation Frequency                    | Fosc                | V <sub>IN</sub> =3.6~18V, I <sub>LOAD</sub> =0.2A~2A   | 240   | 300 | 360   | KHz   |  |
| Frequency of Short<br>Circuit Protection | F <sub>SCP</sub>    | V <sub>IN</sub> =3.6~18V   | 30    | 50  | 70    | KHz   |  |
| Dute Quela                               | 50                  | V <sub>FB</sub> =0V force driver on  |       | 100 |       |       |  |
| Duty Cycle                               | DC                  | V <sub>FB</sub> =1.5V force driver off   |       | 0   |       | %     |  |
| Internal MOSFET On                       | _                   | V <sub>IN</sub> =5V, V <sub>FB</sub> =0V   |       | 80  | 90    |       |  |
| Resistance                               | R <sub>DS(ON)</sub> | V <sub>IN</sub> =12V, V <sub>FB</sub> =0V  |       | 50  | 60    | mΩ    |  |
| Quiescent Current                        | l <sub>Q</sub>      | $V_{\text{IN}}\text{=}3.6\text{V}\text{-}18\text{V},$ $V_{\text{FB}}\text{=}1.5\text{V}$ force drive off |       | 3   | 10    | mA    |  |
| Shutdown Current                         | I <sub>S</sub>      | EN pin = GND   |       | 1   | 10    | uA    |  |
| EN Pin Input                             |                     | Regulator OFF  |       | 4.0 | 0.8   | v     |  |
| Threshold Voltage                        | V <sub>EN</sub>     | Regulator ON   | 2.0   | 1.3 |       |       |  |
|  |                     | Regulator OFF  |       | 1   |       |       |  |
| EN Pin Bias Current                      | I <sub>EN</sub>     | Regulator ON   |       | 20  |       | uA    |  |
| FB Pin Bias Current                      | I <sub>FB</sub>     | I <sub>LOAD</sub> =0.2A  |       | 0.1 | 0.5   | uA    |  |
| OCSET Pin Bias<br>Current                | I <sub>OCSET</sub>  | I <sub>LOAD</sub> =0.2A  | 75    | 90  | 105   | uA    |  |
| Line Regulation                          |                     | V <sub>IN</sub> =3.6V~18V, I <sub>LOAD</sub> =0.2A   |       | 2   |       | %     |  |
| Load Regulation                          | riangle Vload       | I <sub>LOAD</sub> =0.2A~2A   |       | 0.1 |       | %     |  |
| Over Temperature<br>Shutdown             | T <sub>SD</sub>     |  |       | 150 |       | °C    |  |
| Over Temperature<br>Shutdown Hysteresis  | T <sub>HYS</sub>    |  |       | 25  |       | °C    |  |





VIN=12V, VOUT set to 3.3V, TA=25°C, unless otherwise noted.



Frequency vs. Temperature

60

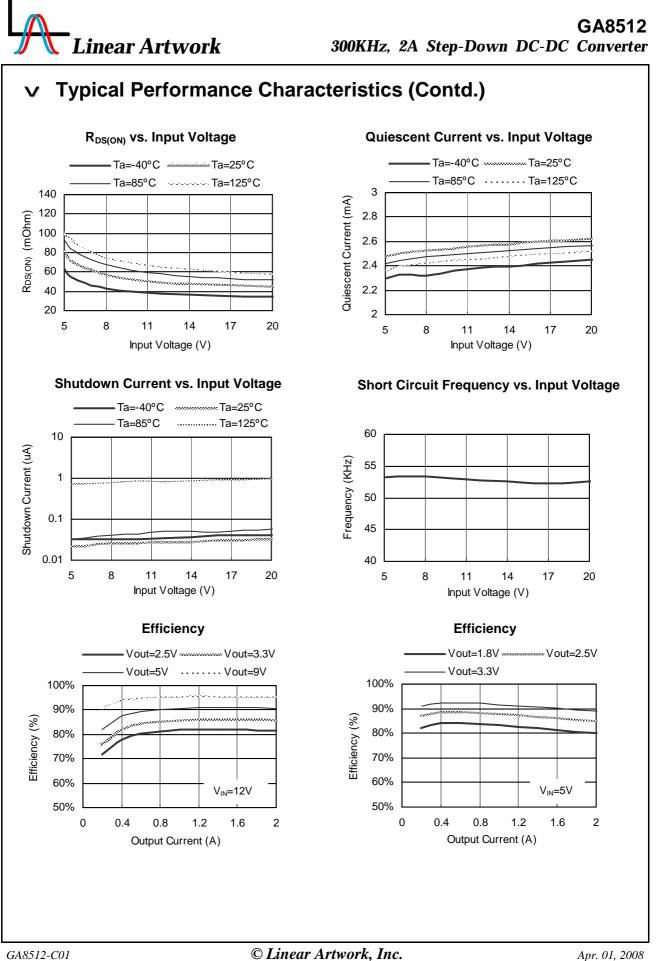
60

80

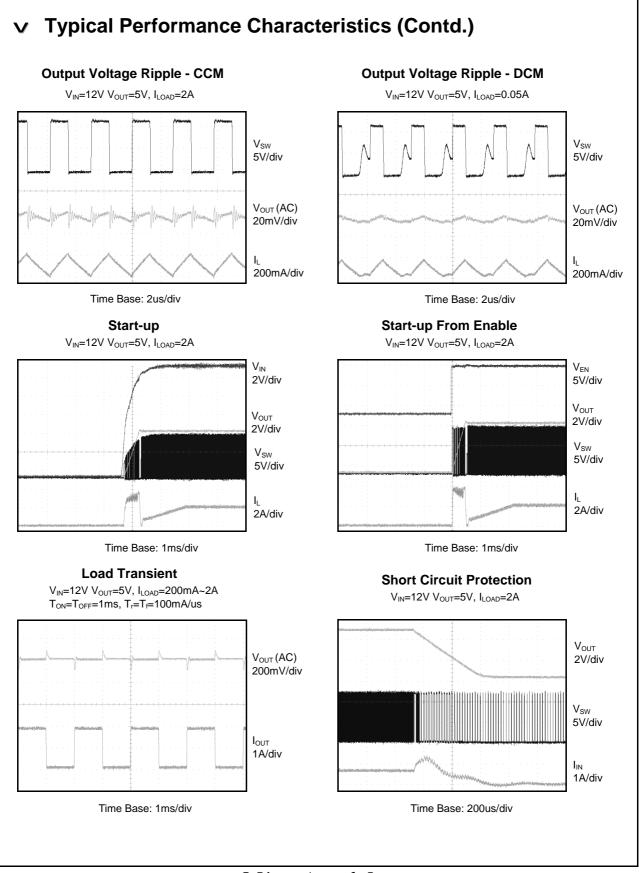
100 120

80

100 120







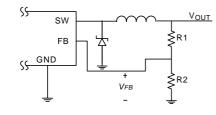
# Application Information

### **Output Voltage Programming**

This device develops a band-gap between the feedback pin and ground pin. Therefore, the output voltage can be formed by R1 and R2. Use 1% metal film resistors for the lowest temperature coefficient and the best stability. Select lower resistor value to minimize noise pickup in the sensitive feedback pin, or higher resistor value to improve efficiency.

The output voltage is given by the following formula:

 $V_{OUT} = V_{FB} x (1 + R1 / R2)$  where  $V_{FB} = 0.8V$ 

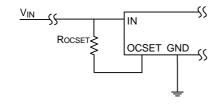


#### **Short Circuit Protection**

This device includes short circuit protection. When the output is shorted to ground, the protection circuit will be triggered and force the oscillation frequency down to approximately 50KHz. The oscillation frequency will return to the normal value once the output voltage or the feedback voltage rises above 0V.

### **Peak Current Setting**

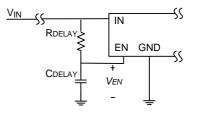
This device reserves OCSET pin to set the switching peak current. In general, the peak current must be 1.5 times of the continuous output current. It can be calculated as below:



 $I_{PK} = (I_{OCSET} \times R_{OCSET}) / R_{DS(ON)}$ 

### Where:

 $I_{PK}$ ; Peak Current  $I_{OCSET}$ ; OCSET Pin Bias Current  $R_{DS(ON)}$ ; Internal MOSFET On-Resistance The following circuit uses the EN pin to provide a time delay between the input voltage is applied and the output voltage comes up. As the instant of the input voltage rises, the charging of capacitor  $C_{\text{DELAY}}$  pulls the EN pin low, keeping the device off. Once the capacitor voltage rises above the EN pin threshold voltage, the device will start to operate.



For example, setting at  $V_{IN}$ =12V,  $R_{DELAY}$ =100K $\Omega$ ,  $C_{DELAY}$ =0.1uF. The start-up delay time can be calculated as below:

$$V_{C} = V_{IN} x (1 - e^{T/\tau}) > V_{EN}$$
  
 $T > 1.147mS$ 

Where:

V<sub>c</sub> is Capacitor Voltage

V<sub>EN</sub> = 1.3V (Typ.); EN Pin Threshold Voltage

T = Delay Time

 $\tau = \mathsf{R}_{\mathsf{DELAY}} \mathsf{x} \mathsf{C}_{\mathsf{DELAY}}$ 

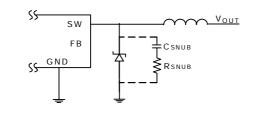
This feature is useful in situations where the input power source is limited in the amount of current it can deliver. It allows the input voltage to rise to a higher voltage before the device starts operating.

### **Snubber Circuit**

The simple RC snubber is used for voltage transient and ringing suppression. The high frequency ringing and voltage overshooting at the SW pin is caused by fast switching transition and resonating circuit parasitical elements in the power circuit. It maybe generates EMI and interferes with circuit performance.

Reserve a snubber circuit in the PC board is preferred to damp the ringing due to the parasitical capacitors and inductors of layout. The following circuit is a simple RC snubber:





Choose the value of RC network by the following procedure:

- (1) Measure the voltage ringing frequency  $(f_R)$  of the SW pin.
- (2) Find a small capacitor and place it across the SW pin and the GND pin to damp the ringing frequency by half.
- (3) The parasitical capacitance ( $C_{PAR}$ ) at the SW pin is 1/3 the value of the added capacitance above. The parasitical inductance ( $L_{PAR}$ ) at the SW pin is:

$$L_{PAR} = \frac{l}{(2\pi f_R)^2 \times C_{PAR}}$$

(4) Select the value of  $C_{SNUB}$  that should be more than 2~4 times the value of  $C_{PAR}$  but must be small enough so that the power dissipation of  $R_{SNUB}$  is kept to a minimum. The power rating of  $R_{SNUB}$  can be calculated by following formula:

$$P \_ RSNUB = CSNUB \times VIN^2 \times fs$$

(5) Calculate the value of R<sub>SNUB</sub> by the following formula and adjust the value to meet the expectative peak voltage.

$$R_{SNUB} = 2\pi \times f_R \times L_{PAR}$$

### **Thermal Considerations**

Thermal protection limits total power dissipation in this device. When the junction temperature reaches approximately  $150^{\circ}$ C, the thermal sensor signals the shutdown logic turning off this device. The thermal sensor will turn this device on again after the IC's junction temperature cools by  $25^{\circ}$ C.

For continuous operation, do not exceed the maximum operation junction temperature 125°C.

### GA8512 300KHz, 2A Step-Down DC-DC Converter

The power dissipation across this device can be calculated by the following formula:

 $P_D = (I_{LOAD})^2 x R_{DS(ON)} x D + 1/2 x V_{IN} x I_{OUT} x$ 

 $(t_r+t_f) \times f_S + Q_{Gate} \times V_{GS} \times f_S + I_Q \times V_{IN}$ 

Where:

D: Duty Cycle

f<sub>S</sub>: Switching Frequency

V<sub>GS</sub>: Power MOSFET Gate Voltage

I<sub>Q</sub>: Quiescent Current

The tr, tf, and  $Q_{Gate}$  are the rising, falling time, and gate charge of the internal power switch. The typical value of (tr+tf) is approximately 55ns, and the  $Q_{Gate}$  is approximately 22nC. The V<sub>GS</sub> is approximately equal V<sub>IN</sub>.

The maximum power dissipation of this device depends on the thermal resistance of the IC package and PCB layout, the temperature difference between the die junction and ambient air, and the rate of airflow. The maximum power dissipation can be calculated by the following formula:

$$P_{D(MAX)} = (T_J - T_A) / q_{JA}$$

Where  $T_J - T_A$  is the temperature difference between the die junction and surrounding environment,  $\theta_{JA}$  is the thermal resistance from the junction to the surrounding environment.

The value of junction to case thermal resistance  $\theta_{JC}$  is also popular to users. This thermal parameter is convenient for users to estimate the internal junction operated temperature of packages while IC operating. The operated junction temperature can be calculated by the following formula:

$$T_{J} = T_{C} + P_{D} x q_{JC}$$

 $\rm T_{\rm c}$  is the package case temperature measured by thermal sensor. Therefore it's easy to estimate the junction temperature by any condition.

There are many factors affect the thermal resistance. Some of these factors include trace width, copper thickness, total PCB copper area, and etc.



For the best thermal performance, wide copper traces and generous amounts of PCB copper should be used in the board layout. If further improve thermal characteristics are needed, double sided and multi-layer PCB with large copper areas and airflow will be recommended.

#### Layout Considerations

PC board layout is very important, especially for switching regulators of high frequencies and large peak currents. A good layout minimizes EMI on the feedback path and provides best efficiency. The following layout guides should be used to ensure proper operation of this device.

(1) The power charge path that consists of the IN trace, the SW trace, external inductor and the GND trace should be kept wide and as short as possible.

(2) The power discharge path that consists of the SW trace, external inductor, external diode and the GND trace should be kept wide and as short as possible.

(3) The feedback path of voltage divider should be close to the FB pin and keep noisy traces away; also keep them separate using grounded copper.

(4) The (+) plates of input capacitors should be close to the regulator.

(5) Keep the (-) plates of input and output capacitors as close as possible.

# ✓ Component Selection

### 1. Inductor Selection

The conduction mode of power stage depends on input voltage, output voltage, output current, and the value of the inductor. Select an inductor to maintain this device operating in continuous conduction mode (CCM). The minimum value of inductor can be determined by the following procedure.

(1) Calculate the minimum duty ratio:

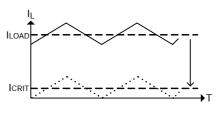
$$D_{(MIN)} = \frac{V_{OUT} + I_{LOAD} \times R_L + V_F}{V_{IN(MAX)} - I_{LOAD} \times R_{DS(ON)} + V_F} = \frac{T_{ON}}{T_S}$$

Where  $R_L$  is the DC resistance of external inductor,  $V_F$  is the forward voltage of external diode, and Ts is the switching period.

This formula can be simplified to

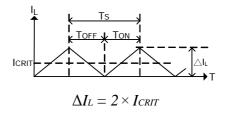
$$D_{(MIN)} = \frac{V_{OUT}}{V_{IN(MAX)}} = \frac{T_{ON}}{T_S} \quad ; \quad 0 \le D \le 1$$

(2) Define a value of minimum current that is approximately 10%~30% of full load current to maintain continuous conduction mode, usually referred to as the critical current (I<sub>CRIT</sub>).



$$I_{CRIT} = \delta \times I_{LOAD}$$
;  $\delta = 0.1 \sim 0.3$ 

(3) Calculate the inductor ripple current ( $\triangle I_L$ ). In steady state conditions, the inductor ripple current increase, ( $\triangle I_L$ +), during the ON time and the current decrease, ( $\triangle I_L$ -), during the OFF time must be equal.





(4) Calculate the minimum value of inductor use maximum input voltage. That is the worst case condition because it gives the maximum  $riangleq I_L$ .

$$L \ge \frac{[V_{IN(MAX)} - I_{LOAD} \times (R_{DS(ON)} + R_L) - V_{OUT}] \times D_{(MIN)}}{\Delta I_L \times f_S}$$

This formula can be simplified to

$$L \geq \frac{(V_{IN(MAX)} - V_{OUT}) \times D_{(MIN)}}{\Delta I_L \times fs}$$

The higher value inductor results in lower output ripple current and ripple voltage. It also reduces the conduction loss. But higher value inductor requires larger physical size and price.

(5) Calculate the inductor peak current and choose a suitable inductor to prevent saturation.

$$I_{L(PEAK)} = I_{LOAD} + \frac{\Delta I_L}{2}$$

Coil inductors and surface mount inductors are all available. The surface mount inductors can reduce the board size but they are more expensive and its larger DC resistance results in more conduction loss. The power dissipation is due to the DC resistance can be calculated as below:

$$P_{D_{-}INDUCTOR} = I_{LOAD^{2}} \times R_{L}$$

### 2. Output Rectifier Diode Selection

The rectifier diode provides a current path for the inductor current when the internal power switch of the converter turns off. The best solution is Schottky diode, and some parameters about the diode must be take care as below:

(1) The forward current rating of diode must be higher than the continuous output current.

(2) The reverse voltage rating of diode must be higher than the maximum input voltage.

(3) The lower forward voltage of diode will reduce the conduction loss.

(4) The faster reverse recovery time of diode will reduce the switching loss, but it is very small compared to conduction loss.

(5) The power dissipation can be calculated by the forward voltage and output current for the time that the diode is conducting.

## GA8512 300KHz, 2A Step-Down DC-DC Converter

 $P_{D_{-}DIODE} = I_{LOAD} \times V_F \times (1 - D)$ 

### 3. Output Capacitor Selection

The functions of the output capacitor are to store energy and maintain the output voltage. The low ESR (Equivalent Series Resistance) capacitors are preferred to reduce the output ripple voltage  $(\triangle V_{OUT})$  and conduction loss. The output ripple voltage can be calculated as below:

$$\Delta V_{OUT} = \Delta I_L \times (ESR\_cout + \frac{l}{8 \times f_s \times C_{OUT}})$$

(1) When low ESR ceramic capacitor is used as output capacitor, the output ripple voltage due to the ESR can be ignored results in all the output ripple voltage is due to the capacitance. Choose suitable capacitors must define the expectative value of output ripple voltage first.

The minimum capacitance can be determined by the switching frequency, the output ripple current, and the expectative output ripple voltage. The above formula can be simplified to:

$$C_{OUT(MIN)} \ge \frac{\Delta I_L}{8 \times f_S \times \Delta V_{OUT}}$$

Besides, the compensation components must be used to stabilize the control loop in some applications, such as using a 1nF ceramic capacitor across the high side resistor of the output voltage divider.

(2) The ESR of the aluminum electrolytic or tantalum output capacitor is an important parameter to determine the output ripple voltage. But the manufacturers usually do not specify ESR in the specifications. Assuming the capacitance is enough results in the output ripple voltage is due to the capacitance can be ignored, the ESR should be limited to achieve the expectative output ripple voltage. The maximum ESR can be calculated as below:

$$ESR\__{COUT} \leq \frac{\Delta V_{OUT}}{\Delta I_L}$$

Choose the output capacitance by the average value of the RC product as below:

$$C_{OUT} \approx \frac{50 \sim 80 \times 10^{-6}}{ESR\_COUT}$$



(3) The ESR and the ripple current results in power dissipation in the capacitor. It will increase the internal temperature. Usually, the capacitors' manufacturers specify ripple current ratings and should not be exceeded to prevent excessive temperature shorten the life time. Choose a smaller inductor causes higher ripple current which maybe result in the capacitor overstress. The RMS ripple current flowing through the output capacitor and power dissipation can be calculated as below:

$$I_{RMS}\_cout = \frac{\Delta I_L}{\sqrt{12}} = \Delta I_L \times 0.289$$

$$P_{D}$$
\_cout =  $(I_{RMS}$ \_cout  $)^{2} \times ESR$ \_cout

(4) Besides, the capacitor's ESL (Equivalent Series Inductance) maybe causes ringing in the low MHz region. Choose low ESL capacitors, limiting lead length of PCB and capacitor, and parallel connecting several smaller capacitors to replace with a larger one will reduce the ringing phenomenon.

#### 4. Input Capacitor Selection

The input capacitor is required to supply current to the regulator and maintain the DC input voltage. Low ESR capacitors are preferred those provide the better performance and the less ripple voltage.

(1) The input capacitors need an adequate RMS current rating. It can be calculated by following formula and should not be exceeded.

$$I_{RMS}$$
 \_  $CIN = I_{LOAD(MAX)} \times \sqrt{D \times (1 - D)}$ 

This formula has a maximum at  $V_{IN}=2V_{OUT}$ . That is the worst case and the above formula can be simplified to:

$$I_{RMS}$$
 \_  $CIN = \frac{I_{LOAD(MAX)}}{2}$ 

Therefore, choose a suitable capacitor at input whose ripple current rating must greater than half of the maximum load current.

(2) The input ripple voltage  $(\triangle V_{\text{IN}})$  mainly depends on the input capacitor's ESR and its capacitance. Assuming the input current of the regulator is constant, the required input capacitance for a given input ripple voltage can be calculated as below:

### GA8512 300KHz, 2A Step-Down DC-DC Converter

$$C_{IN} = \frac{I_{LOAD(MAX)} \times D \times (1 - D)}{f_{S} \times (\Delta V_{IN} - I_{LOAD(MAX)} \times ESR\__{CIN})}$$

If using aluminum electrolytic or tantalum input capacitors, parallel connecting a 0.1uF ceramic capacitor as close to the IN pin of regulator as possible. If using ceramic capacitor, make sure the capacitance is enough to prevent the excessive input ripple current.

(3) The power dissipation of input capacitor causes a small conduction loss can be calculated as below:

$$P_{D}$$
\_ $CIN = (I_{RMS}$ \_ $CIN)^2 × ESR$ \_ $CIN$ 



# ✓ Quick Design Table

For 2A output current,  $\triangle I_L$ =0.4A, continuous mode operation

- A: Inductor value
- B: High side resistor of the output voltage divider
- C: Low side resistor of the output voltage divider
- D: Peak current setting resistor (R<sub>OCSET</sub>)

The **boldface type** denotes this application can be steadied with <u>Low ESR Output Ceramic Capacitors</u>, but must connect a 1nF capacitor across the high side resistor of the voltage divider to compensate the control loop.

| V <sub>IN</sub><br>Vout | 5V         | 9V         | 12V         | 18V         |
|-------------------------|------------|------------|-------------|-------------|
|                         | A: 8.2uH   | A: 8.2uH   | A: 8.2uH    | A: 8.2uH    |
| 0.8V                    | B: 0 Ohm   | B: 0 Ohm   | B: 0 Ohm    | B: 0 Ohm    |
| 0.01                    | C: NC      | C: NC      | C: NC       | C: NC       |
|                         | D: 3.9KOhm | D: 2KOhm   | D: 1.8KOhm  | D: 1.8KOhm  |
|                         | A: 10uH    | A: 12uH    | A: 12uH     | A: 12uH     |
| 1.2V                    | B: 1.5KOhm | B: 1.5KOhm | B: 1.5KOhm  | B: 1.5KOhm  |
| 1.2 V                   | C: 3KOhm   | C: 3KOhm   | C: 3KOhm    | C: 3KOhm    |
|                         | D: 3.9KOhm | D: 2KOhm   | D: 1.8KOhm  | D: 1.8KOhm  |
|                         | A: 12uH    | A: 15uH    | A: 15uH     | A: 15uH     |
| 1.5V                    | B: 1.3KOhm | B: 1.3KOhm | B: 1.3KOhm  | B: 1.3KOhm  |
| 1.50                    | C: 1.5KOhm | C: 1.5KOhm | C: 1.5KOhm  | C: 1.5KOhm  |
|                         | D: 3.9KOhm | D: 2KOhm   | D: 1.8KOhm  | D: 1.8KOhm  |
|                         | A: 12uH    | A: 15uH    | A: 18uH     | A: 18uH     |
| 1.8V                    | B: 2.5KOhm | B: 2.5KOhm | B: 2.5KOhm  | B: 2.5KOhm  |
| 1.0V                    | C: 2KOhm   | C: 2KOhm   | C: 2KOhm    | C: 2KOhm    |
|                         | D: 3.9KOhm | D: 2.2KOhm | D: 2KOhm    | D: 2KOhm    |
|                         | A: 15uH    | A: 22uH    | A: 22uH     | A: 27uH     |
| 2.51/                   | B: 4.7KOhm | B: 4.7KOhm | B: 4.7KOhm  | B: 4.7KOhm  |
| 2.5V                    | C: 2.2KOhm | C: 2.2KOhm | C: 2.2KOhm  | C: 2.2KOhm  |
|                         | D: 3.9KOhm | D: 2KOhm   | D: 1.8KOhm  | D: 1.8KOhm  |
|                         | A: 12uH    | A: 22uH    | A: 27uH     | A: 33uH     |
| 3.3V                    | B: 4.7KOhm | B: 4.7KOhm | B: 4.7KOhm  | B: 4.7KOhm  |
| 3.37                    | C: 1.5KOhm | C: 1.5KOhm | C: 1.5KOhm  | C: 1.5KOhm  |
|                         | D: 3.3KOhm | D: 2KOhm   | D: 1.8KOhm  | D: 1.8KOhm  |
|                         |            | A: 27uH    | A: 33uH     | A: 39uH     |
| 5V                      |            | B: 6.8KOhm | B: 6.8KOhm  | B: 6.8KOhm  |
| 57                      |            | C: 1.3KOhm | C: 1.3KOhm  | C: 1.3KOhm  |
|                         |            | D: 2KOhm   | D: 1.8KOhm  | D: 1.8KOhm  |
|                         |            |            | A: 27uH     | A: 47uH     |
| 9V                      |            |            | B: 10.2KOhm | B: 10.2KOhm |
| 90                      |            |            | C: 1KOhm    | C: 1KOhm    |
|                         |            |            | D: 1.8KOhm  | D: 1.8KOhm  |
|                         |            |            |             | A: 47uH     |
| 12V                     |            |            |             | B: 18.2KOhm |
| 12 V                    |            |            |             | C: 1.3KOhm  |
|                         |            |            |             | D: 1.8KOhm  |



### ✓ Evaluation Board Layout Linear Artwork, Inc. 886-2-2912-5816 www.line GND VOUT 0 GND SV GA8512 Ev ✓ Evaluation Board Schematic TP1 Г J3 J2 L1 <u>U1</u> 4 IN sw R1 5 R2 R3 VOUT VIN OCSET sw C1 C2 C3 C4 C5 GND GND C6\_ \_C7 C8 D1 د EN FB J4 C9 J5 R4 R5 GND GND C10 TP2 Π

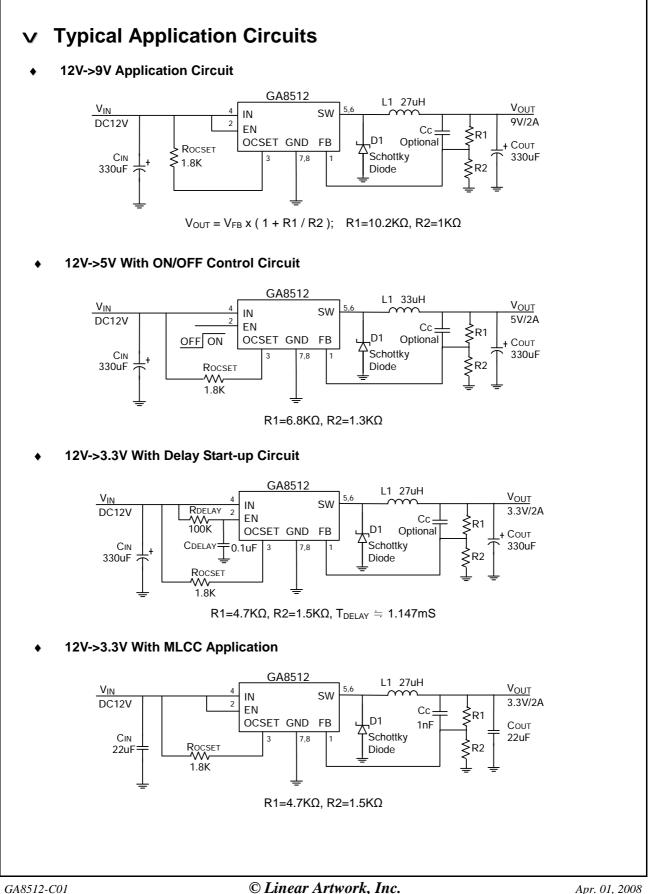


# ✓ Bill of Materials

 $V_{IN}$ =12V,  $V_{OUT}$ =3.3V,  $I_{OUT}$ =2A

| Designation  | Descriptions   | Manufacturer Part # | Manufacturer   | Manufacturer Website   |  |
|--------------|--|---------------------|----------------|------------------------|--|
| U1           | 300KHz, 2A Step-Down DC-DC Converter<br>SOP-8L Package | GA8512JGADJ         | Linear Artwork | www.linear-artwork.com |  |
| L1           | Choke 33uH, 3A, 0.05Ohm                                | 744132              | WE             | www.we-online.com      |  |
|              | Choke 33uH, 4A, 0.04Ohm,                               | TDH1420T-330K-N     | Chilisin       | www.chilisin.com.tw    |  |
| D1           | Schottky 30V, 2A, $0.4V_F$ , SMA Package               | D1FP3               | Shindengen     | www.shindengen.com     |  |
| C2,C7        | Low ESR E/C 330uF, 25V, 8x15mm                         | EKY-250EXX331MH15D  | NCC            | www.chemi-con.co.jp    |  |
|              | MLCC 0.1uF, 0805, X7R, 50V                             | CC0805KRX7R9BB104   | Yageo          | www.yageo.com          |  |
| C3,C8        | MLCC 0.1uF, 0805, X7R, 50V                             | UMK212BJ104KG       | Taiyo Yuden    | www.yuden.co.jp        |  |
|              | MLCC 0.1uF, 0603, B, 50V                               | C1608JB1H104K       | ток            | www.tdk.com            |  |
| C4,C5,C9,C10 | Optional Parts   |                     |                |                        |  |
| C1,C6        |  | No Connection       |                |                        |  |
| R3           | Chip Resistor, 4.7KOhm, 0805, ±1%                      | RC0805FR-074K7L     | Yageo          | www.yageo.com          |  |
| R4           | Chip Resistor, 1.8KOhm, 0805, ±1%                      | RC0805FR-071K8L     | Yageo          | www.yageo.com          |  |
| R5           | Chip Resistor, 1.5KOhm, 0805, ±1%                      | RC0805FR-071K5L     | Yageo          | www.yageo.com          |  |
| R1,R2        | Optional Parts   |                     |                |                        |  |
| J1           | Male Header 180° 3*1P 2.54mm                           |                     |                |                        |  |
| J2,J3,J4,J5  | Terminal Binding Post 1.6mm                            |                     |                |                        |  |
| TP1,TP2      | Male Header 180° 1P 2.54mm                             |                     |                |                        |  |

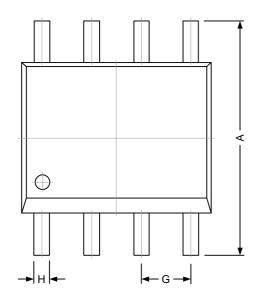




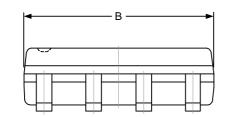


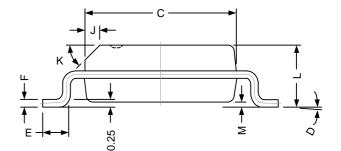
# ✓ Package Outline

SOP-8L



|      | DIMENSIONS |      |  |
|------|------------|------|--|
| REF. | Millimeter |      |  |
|      | Min.       | Max. |  |
| А    | 5.80       | 6.20 |  |
| В    | 4.80       | 5.00 |  |
| С    | 3.80       | 4.00 |  |
| D    | 0°         | 8°   |  |
| E    | 0.40       | 0.90 |  |
| F    | 0.19       | 0.25 |  |
| М    | 0.10       | 0.25 |  |
| Н    | 0.35       | 0.49 |  |
| L    | 1.35       | 1.75 |  |
| J    | 0.375 REF. |      |  |
| K    | 45°        |      |  |
| G    | 1.27 TYP.  |      |  |







#### NOTICE

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The information provided here is believed to be reliable and accurate; however Linear Artwork, Inc. makes no guarantee for any errors that appear in this document.

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Linear Artwork products are not designed or authorized for use as critical components in life support devices or systems without the express written approval of the president of Linear Artwork, Inc. As used herein:

1. Life support devices or systems are devices or systems which, (a) are intended for surgical implant into the body, or (b) support or sustain life, and (c) whose failure to perform when properly used in accordance with instructions for use provided in the labeling, can be reasonably expected to result in a significant injury of the user.

2. A critical component in any component of a life support device or system whose failure to perform can be reasonably expected to cause the failure of the life support device or system, or to affect its safety or effectiveness.

# Linear Artwork, Inc.

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