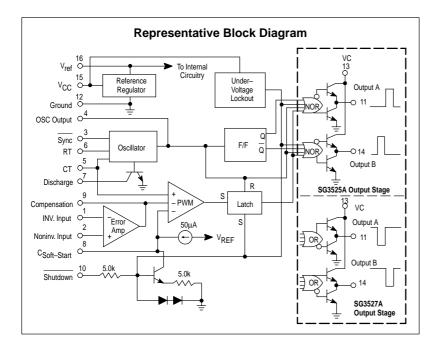




### Pulse Width Modulator Control Circuits

The SG3525A, SG3527A pulse width modulator control circuits offer improved performance and lower external parts count when implemented for controlling all types of switching power supplies. The on-chip +5.1 V reference is trimmed to  $\pm 1\%$  and the error amplifier has an input common-mode voltage range that includes the reference voltage, thus eliminating the need for external divider resistors. A sync input to the oscillator enables multiple units to be slaved or a single unit to be synchronized to an external system clock. A wide range of deadtime can be programmed by a single resistor connected between the CT and Discharge pins. These devices also feature built-in soft-start circuitry, requiring only an external timing capacitor. A shutdown pin controls both the soft-start circuitry and the output stages, providing instantaneous turn off through the PWM latch with pulsed shutdown, as well as soft-start recycle with longer shutdown commands. The under voltage lockout inhibits the outputs and the changing of the soft-start capacitor when VCC is below nominal. The output stages are totem-pole design capable of sinking and sourcing in excess of 200 mA. The output stage of the SG3525A features NOR logic resulting in a low output for an off-state while the SG3527A utilized OR logic which gives a high output when off.

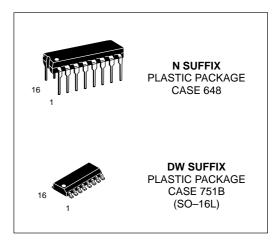
- 8.0 V to 35 V Operation
- 5.1 V ± 1.0% Trimmed Reference
- 100 Hz to 400 kHz Oscillator Range
- Separate Oscillator Sync Pin
- Adjustable Deadtime Control
- Input Undervoltage Lockout
- Latching PWM to Prevent Multiple Pulses
- Pulse-by-Pulse Shutdown
- Dual Source/Sink Outputs: ±400 mA Peak

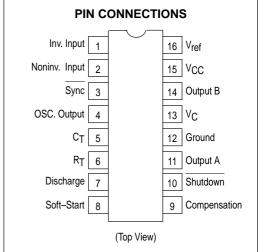


## SG3525A SG3527A

# PULSE WIDTH MODULATOR CONTROL CIRCUITS

SEMICONDUCTOR TECHNICAL DATA





### ORDERING INFORMATION

Device	Operating Temperature Range	Package
SG3525AN		Plastic DIP
SG3525ADW	$T_A = 0^\circ \text{ to } +70^\circ \text{C}$	SO-16L
SG3527AN		Plastic DIP



#### MAXIMUM RATINGS (Note 1)

Rating	Symbol	Value	Unit
Supply Voltage	Vcc	+40	Vdc
Collector Supply Voltage	٧c	+40	Vdc
Logic Inputs		-0.3 to +5.5	V
Analog Inputs		−0.3 to V <sub>CC</sub>	V
Output Current, Source or Sink	lo	±500	mA
Reference Output Current	I <sub>ref</sub>	50	mA
Oscillator Charging Current		5.0	mA
Power Dissipation (Plastic & Ceramic Package)  T <sub>A</sub> = +25°C (Note 2)  T <sub>C</sub> = +25°C (Note 3)	PD	1000 2000	mW
Thermal Resistance Junction-to-Air	$R_{\theta JA}$	100	°C/W
Thermal Resistance Junction-to-Case	$R_{\theta JC}$	60	°C/W
Operating Junction Temperature	TJ	+150	°C
Storage Temperature Range	T <sub>stg</sub>	-55 to +125	°C
Lead Temperature (Soldering, 10 seconds)	T <sub>Solder</sub>	+300	°C

**NOTES:** 1. Values beyond which damage may occur.

- 2. Derate at 10 mW/°C for ambient temperatures above +50°C.
- 3. Derate at 16 mW/°C for case temperatures above +25°C.

### RECOMMENDED OPERATING CONDITIONS

Characteristics	Symbol	Min	Max	Unit
Supply Voltage	Vcc	8.0	35	Vdc
Collector Supply Voltage	VC	4.5	35	Vdc
Output Sink/Source Current (Steady State) (Peak)	Ю	0 0	±100 ±400	mA
Reference Load Current	I <sub>ref</sub>	0	20	mA
Oscillator Frequency Range	fosc	0.1	400	kHz
Oscillator Timing Resistor	RT	2.0	150	kΩ
Oscillator Timing Capacitor	CT	0.001	0.2	μF
Deadtime Resistor Range	R <sub>D</sub>	0	500	Ω
Operating Ambient Temperature Range	TA	0	+70	°C

### **APPLICATION INFORMATION**

### Shutdown Options (See Block diagram, front page)

Since both the compensation and soft–start terminals (Pins 9 and 8) have current source pull–ups, either can readily accept a pull–down signal which only has to sink a maximum of 100  $\mu$ A to turn off the outputs. This is subject to the added requirement of discharging whatever external capacitance may be attached to these pins.

An alternate approach is the use of the shutdown circuitry of Pin 10 which has been improved to enhance the available shutdown options. Activating this circuit by applying a positive signal on Pin 10 performs two functions: the PWM

latch is immediately set providing the fastest turn–off signal to the outputs; and a 150  $\mu A$  current sink begins to discharge the external soft–start capacitor. If the shutdown command is short, the PWM signal is terminated without significant discharge of the soft–start capacitor, thus, allowing, for example, a convenient implementation of pulse–by–pulse current limiting. Holding Pin 10 high for a longer duration, however, will ultimately discharge this external capacitor, recycling slow turn–on upon release.

Pin 10 should not be left floating as noise pickup could conceivably interrupt normal operation.



 $\textbf{ELECTRICAL CHARACTERISTICS} \ (V_{CC} = +20 \ \text{Vdc}, \ T_{A} = T_{low} \ \text{to} \ T_{high} \ [\text{Note 4}], \ unless \ otherwise \ noted.)$ 

RENCE SECTION  rence Output Voltage ( $T_J = +25^{\circ}C$ )  Regulation ( $+8.0 \text{ V} \le \text{V}_{CC} \le +35 \text{ V}$ )  Regulation ( $0 \text{ mA} \le \text{I}_L \le 20 \text{ mA}$ )	V <sub>ref</sub> Reg <sub>line</sub>	5.00	1		
Regulation (+8.0 V ≤ V <sub>CC</sub> ≤ +35 V)		5.00	1		
	Regline		5.10	5.20	Vdc
Regulation (0 mA $\leq$ I <sub>L</sub> $\leq$ 20 mA)		-	10	20	mV
- · · · · · - · · - · · · · · · · · · ·	Reg <sub>load</sub>	_	20	50	mV
perature Stability	ΔV <sub>ref</sub> /ΔT	-	20	_	mV
Output Variation cludes Line and Load Regulation over Temperature	$\Delta V_{ref}$	4.95	-	5.25	Vdc
t Circuit Current ref = 0 V, T <sub>J</sub> = +25°C)	I <sub>SC</sub>	-	80	100	mA
ut Noise Voltage (10 Hz ≤ f ≤ 10 kHz, T <sub>J</sub> = +25°C)	Vn	-	40	200	μV <sub>rms</sub>
Term Stability (T <sub>J</sub> = +125°C) (Note 5)	S	_	20	50	mV/khr
LATOR SECTION (Note 6, unless otherwise noted.)			1		
Accuracy (T <sub>J</sub> = +25°C)		_	±2.0	±6.0	%
uency Stability with Voltage 3.0 $V \le V_{CC} \le +35 V$ )	$\frac{\Delta f_{OSC}}{D_{VCC}}$	-	±1.0	±2.0	%
uency Stability with Temperature	$\frac{\Delta f_{OSC}}{D}$	-	±0.3	-	%
num Frequency (R <sub>T</sub> = 150 kΩ, C <sub>T</sub> = 0.2 μF)	fmin	-	50	_	Hz
mum Frequency (R <sub>T</sub> = 2.0 kΩ, C <sub>T</sub> = 1.0 nF)	f <sub>max</sub>	400	_	_	kHz
ent Mirror (I <sub>RT</sub> = 2.0 mA)		1.7	2.0	2.2	mA
Amplitude		3.0	3.5	_	V
« Width (T <sub>J</sub> = +25°C)		0.3	0.5	1.0	μs
Threshold		1.2	2.0	2.8	V
Input Current (Sync Voltage = +3.5 V)		_	1.0	2.5	mA
PR AMPLIFIER SECTION (V <sub>CM</sub> = +5.1 V)			1	l	
Offset Voltage	V <sub>IO</sub>	-	2.0	10	mV
Bias Current	I <sub>IB</sub>	-	1.0	10	μА
Offset Current	ΙΙΟ	_	_	1.0	μА
Open Loop Gain (R <sub>L</sub> ≥ 10 MΩ)	Avol	60	75	-	dB
Level Output Voltage	VOL	-	0.2	0.5	V
Level Output Voltage	VOH	3.8	5.6	_	V
mon Mode Rejection Ratio (+1.5 V ≤ V <sub>CM</sub> ≤ +5.2 V)	CMRR	60	75	_	dB
er Supply Rejection Ratio (+8.0 V ≤ V <sub>CC</sub> ≤ +35 V)	PSRR	50	60	_	dB
COMPARATOR SECTION			•		
num Duty Cycle	DC <sub>min</sub>	-	_	0	%
mum Duty Cycle	DC <sub>max</sub>	45	49	-	%
Threshold, Zero Duty Cycle (Note 6)	V <sub>th</sub>	0.6	0.9	-	V
Threshold, Maximum Duty Cycle (Note 6)	V <sub>th</sub>	-	3.3	3.6	V
Bias Current	I <sub>IB</sub>	-	0.05	1.0	μА

NOTES: 4. T<sub>IOW</sub> = 0° for SG3525A, 3527A T<sub>high</sub> = +70°C for SG3525A, 3527A

5. Since long term stability cannot be measured on each device before shipment, this specification is an engineering estimate of average stability from lot to lot.

<sup>6.</sup> Tested at  $f_{OSC}$  = 40 kHz (RT = 3.6 k $\Omega$ , CT = 0.01  $\mu$ F, RD = 0 $\Omega$ ).



### **ELECTRICAL CHARACTERISTICS (Continued)**

Characteristics	Symbol	Min	Тур	Max	Unit
SOFT-START SECTION					
Soft–Start Current (V <sub>Shutdown</sub> = 0 V)		25	50	80	μΑ
Soft–Start Voltage (V <sub>shutdown</sub> = 2.0 V)		_	0.4	0.6	V
Shutdown Input Current (V <sub>shutdown</sub> = 2.5 V)		_	0.4	1.0	mA
<b>OUTPUT DRIVERS</b> (Each Output, V <sub>CC</sub> = +20 V)					
Output Low Level (I <sub>sink</sub> = 20 mA) (I <sub>sink</sub> = 100 mA)	VOL	_ _	0.2 1.0	0.4 2.0	V
Output High Level (I <sub>source</sub> = 20 mA) (I <sub>source</sub> = 100 mA)	VOH	18 17	19 18	_ _	V
Under Voltage Lockout (V8 and V9 = High)	V <sub>UL</sub>	6.0	7.0	8.0	V
Collector Leakage, V <sub>C</sub> = +35 V (Note 7)	I <sub>C</sub> (leak)	-	_	200	μΑ
Rise Time ( $C_L = 1.0 \text{ nF}, T_J = 25^{\circ}\text{C}$ )	t <sub>r</sub>	-	100	600	ns
Fall Time (C <sub>L</sub> = 1.0 nF, T <sub>J</sub> = 25°C)	t <sub>f</sub>	-	50	300	ns
Shutdown Delay ( $V_{DS} = +3.0 \text{ V}$ , $C_S = 0$ , $T_J = +25^{\circ}\text{C}$ )	t <sub>ds</sub>	-	0.2	0.5	μs
Supply Current (V <sub>CC</sub> = +35 V)	Icc	-	14	20	mA

NOTE: 7. Applies to SG3525A only, due to polarity of output pulses.

### **Lab Test Fixture**

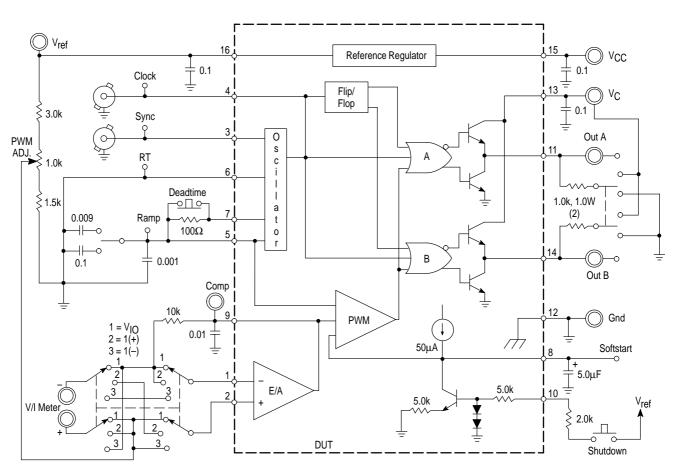




Figure 1. Oscillator Charge Time versus RT

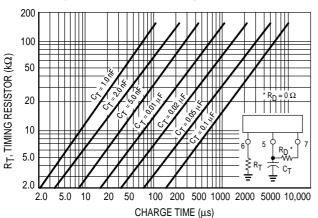


Figure 2. Oscillator Discharge Time versus RD

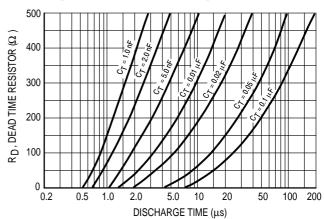


Figure 3. Error Amplifier Open Loop Frequency Response

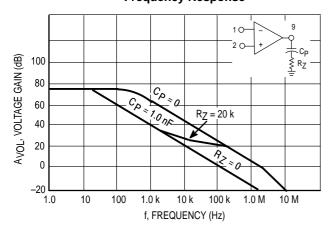


Figure 4. Output Saturation Characteristics (SG3525A)

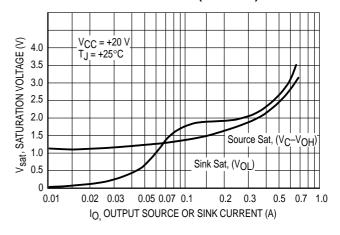


Figure 5. Oscillator Schematic (SG3525A)

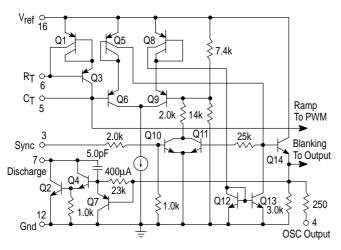


Figure 6. Error Amplifier Schematic (SG3525A)

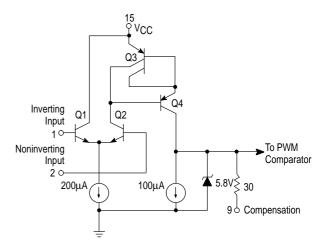




Figure 7. SG3525A Output Circuit

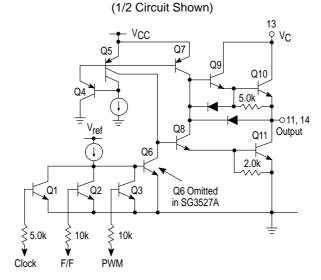
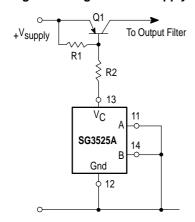
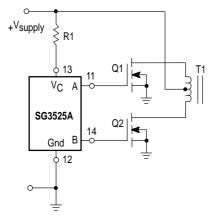


Figure 8. Single-Ended Supply



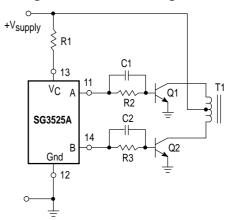
For single–ended supplies, the driver outputs are grounded. The V<sub>C</sub> terminal is switched to ground by the totem–pole source transistors on alternate oscillator cycles.

Figure 10. Driving Power FETS



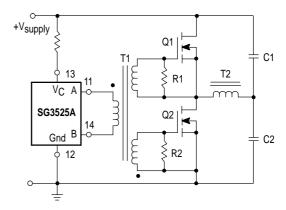
The low source impedance of the output drivers provides rapid charging of power FET input capacitance while minimizing external components.

Figure 9. Push-Pull Configuration



In conventional push–pull bipolar designs, forward base drive is controlled by R1–R3. Rapid turn–off times for the power devices are achieved with speed–up capacitors C1 and C2.

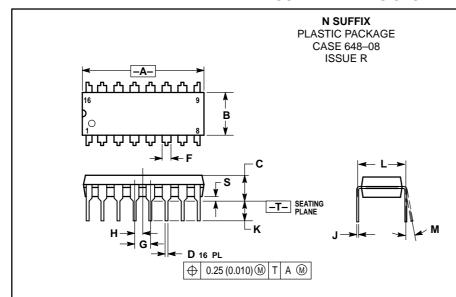
Figure 11. Driving Transformers in a Half-Bridge Configuration



Low power transformers can be driven directly by the SG3525A. Automatic reset occurs during deadtime, when both ends of the primary winding are switched to ground.

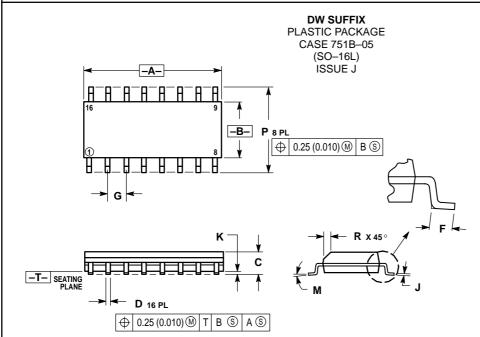


### SG3525A SG3527A **OUTLINE DIMENSIONS**



- NOTES:
  1. DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982.
  2. CONTROLLING DIMENSION: INCH.
  3. DIMENSION L TO CENTER OF LEADS WHEN FORMED PARALLEL.
  4. DIMENSION B DOES NOT INCLUDE MOLD FLASH.
  5. ROLINDED CORNERS OPTIONAL.

ŀ	ROUNDED CORNERS OPTIONAL.							
		INC	HES	MILLIN	IETERS			
	DIM	MIN	MAX	MIN	MAX			
	Α	0.740	0.770	18.80	19.55			
ı	В	0.250	0.270	6.35	6.85			
	C	0.145	0.175	3.69	4.44			
	D	0.015	0.021	0.39	0.53			
ı	F	0.040	0.70	1.02	1.77			
I	G	0.100 BSC		2.54	BSC			
ı	Н	0.050	BSC	1.27	BSC			
	J	0.008	0.015	0.21	0.38			
ı	K	0.110	0.130	2.80	3.30			
	L	0.295	0.305	7.50	7.74			
	М	0°	10 °	0°	10 °			
	S	0.020	0.040	0.51	1.01			



#### NOTES:

- DIMENSIONING AND TOLERANCING PER ANSI Y14.5M, 1982.
- ANSI 174-3M, 1982.
  CONTROLLING DIMENSION: MILLIMETER.
  DIMENSIONS A AND B DO NOT INCLUDE
  MOLD PROTRUSION.
  MAXIMUM MOLD PROTRUSION 0.15 (0.006)
  PER SIDE.
- PER SIDE.
  DIMENSION D DOES NOT INCLUDE DAMBAR
  PROTRUSION. ALLOWABLE DAMBAR
  PROTRUSION SHALL BE 0.127 (0.005) TOTAL
  IN EXCESS OF THE D DIMENSION AT
  MAXIMUM MATERIAL CONDITION.

	MILLIN	IETERS	INC	HES
DIM	MIN	MAX	MIN	MAX
Α	9.80	10.00	0.386	0.393
В	3.80	4.00	0.150	0.157
С	1.35	1.75	0.054	0.068
D	0.35	0.49	0.014	0.019
F	0.40	1.25	0.016	0.049
G	1.27	BSC	0.050 BSC	
J	0.19	0.25	0.008	0.009
K	0.10	0.25	0.004	0.009
M	0°	7°	0°	7°
Р	5.80	6.20	0.229	0.244
R	0.25	0.50	0.010	0.019



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