

Virtual Prototyping of Power Supply Designs

A Practical Guide to Using Circuit Simulation to Reduce Design Cycle Time

APEC 2010

Professional Education Seminar

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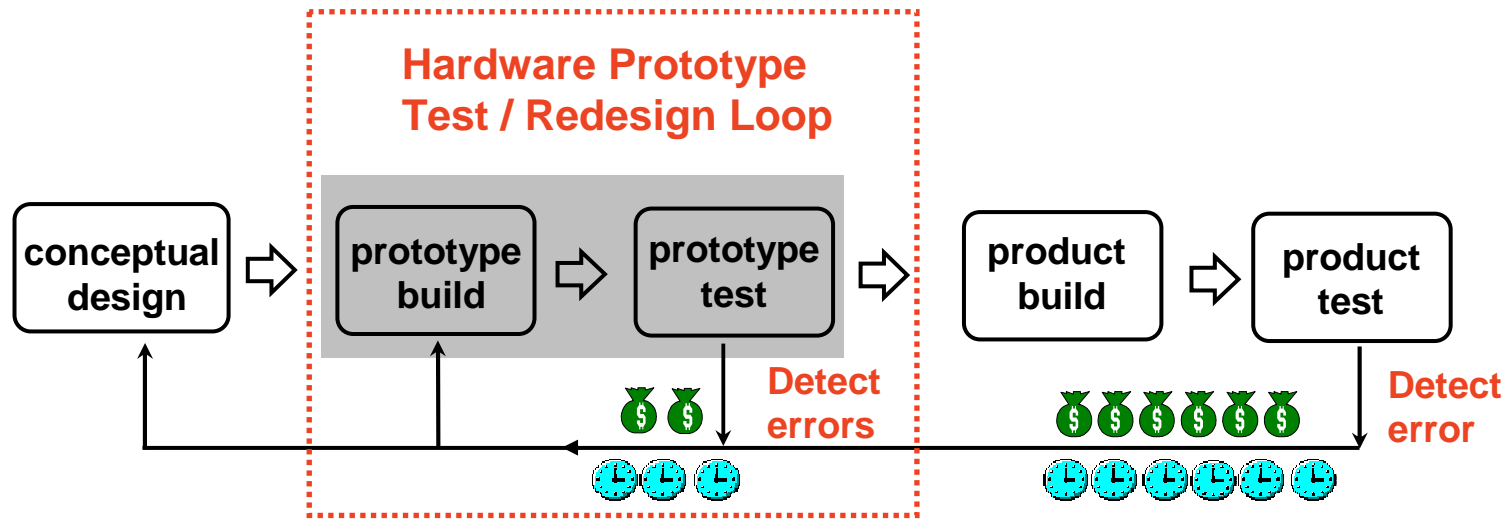
SIMPLIS Technologies



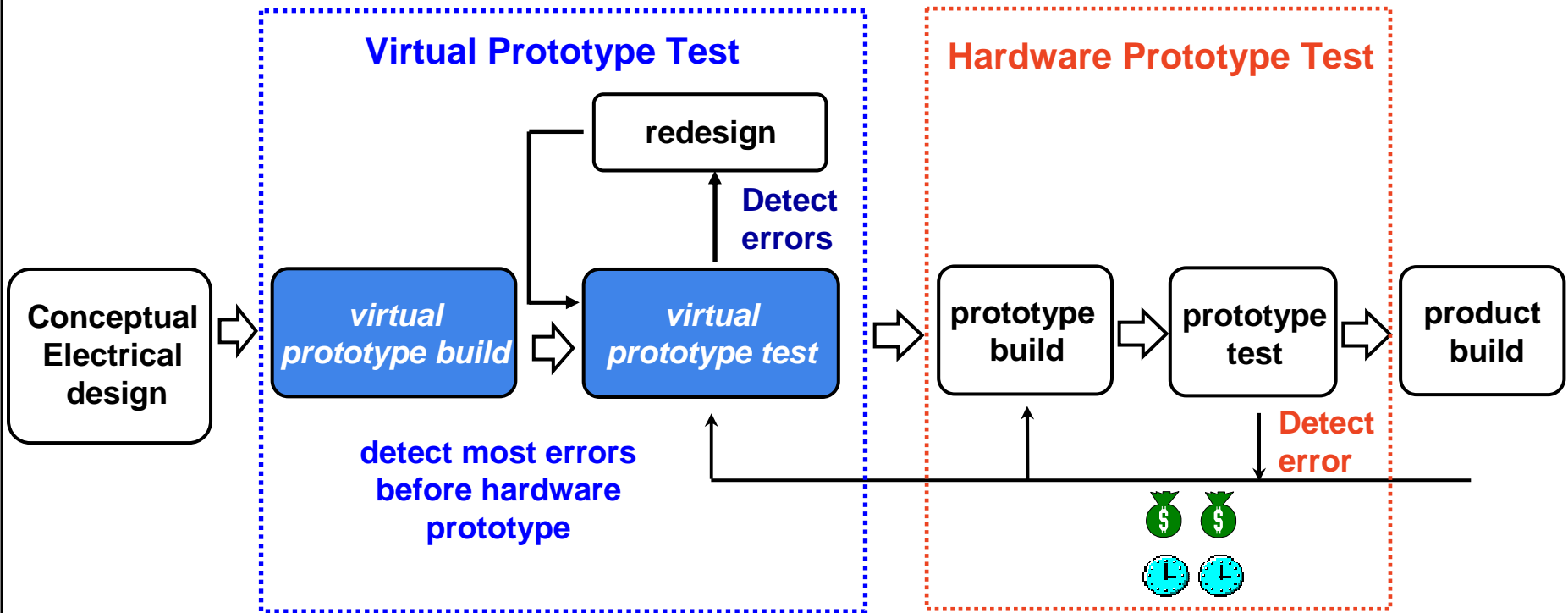
Simulation Software for Power Electronics

Component Design • Circuit Design • System Design

Hardware-Focused Product Development Procedure



Development Process with Virtual Prototype emphasis



Over 50% of all electrical design errors
can be detected by Virtual Prototyping Process
No other single design improvement can
achieve more than 2% design error reduction

Virtual Prototyping of Power Supply Designs

- Cost of Design Changes increasing
 - Design Changes delay time to profitable manufacture
 - All Design Changes consume valuable New Product delivery capacity
- Cost of Hardware Iterations increasing
 - Time to market requirements are shrinking
 - As size of power supplies shrink, \$\$ cost of additional hardware iterations increases
- Cost of correcting Design Errors increases dramatically the later they are discovered in the process

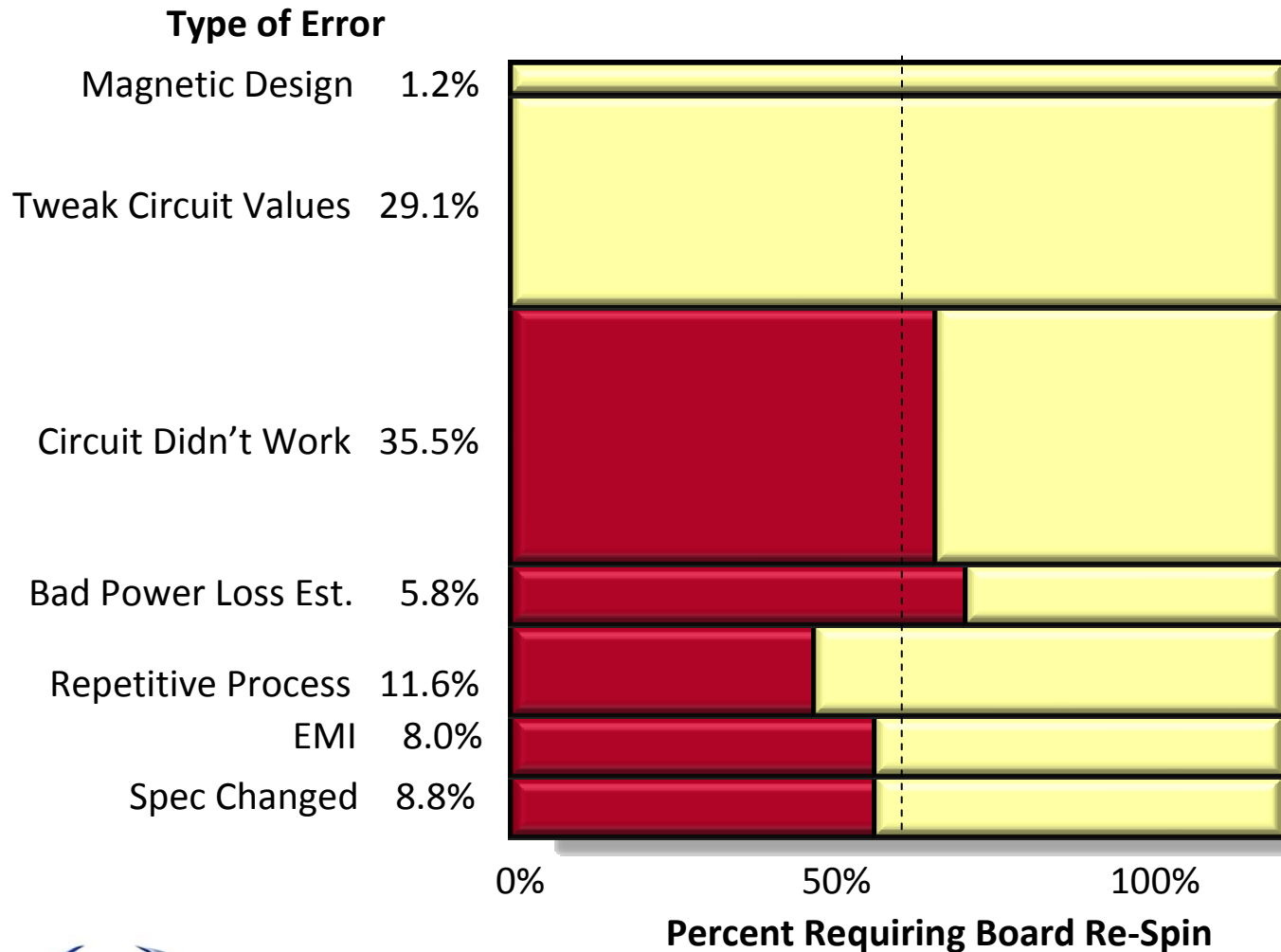
Virtual Prototyping of Power Supply Designs

- Electrical Design Error
 - Design fails to meet design requirements necessitating a design **change** after first hardware prototype
- Design “Failure”
 - Electrical Design fails to meet design requirements necessitating an **additional hardware iteration**

Power Supply Electrical Design Errors

- The following data is the result of in-depth studies of five large design organizations at three major manufacturers of custom and standard power supplies.
- All engineering change orders during the study period (6 to 9 months) were evaluated to determine the nature of the change, whether or not it resulted in a PCB spin, and whether or not it could have been detected with simulation.

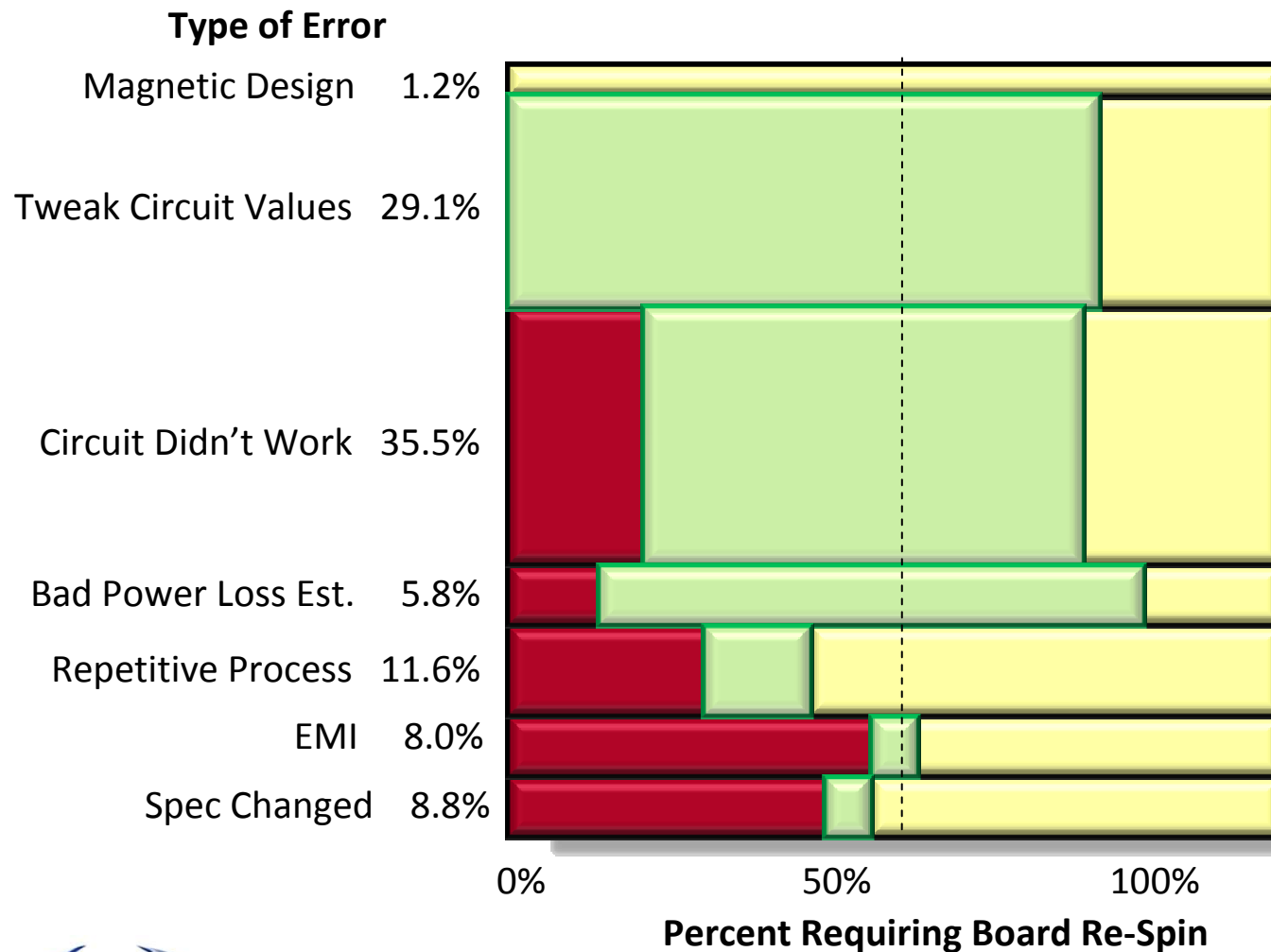
Survey of PS Electrical Design Errors



34% of all design errors in the study required a new PCB spin.



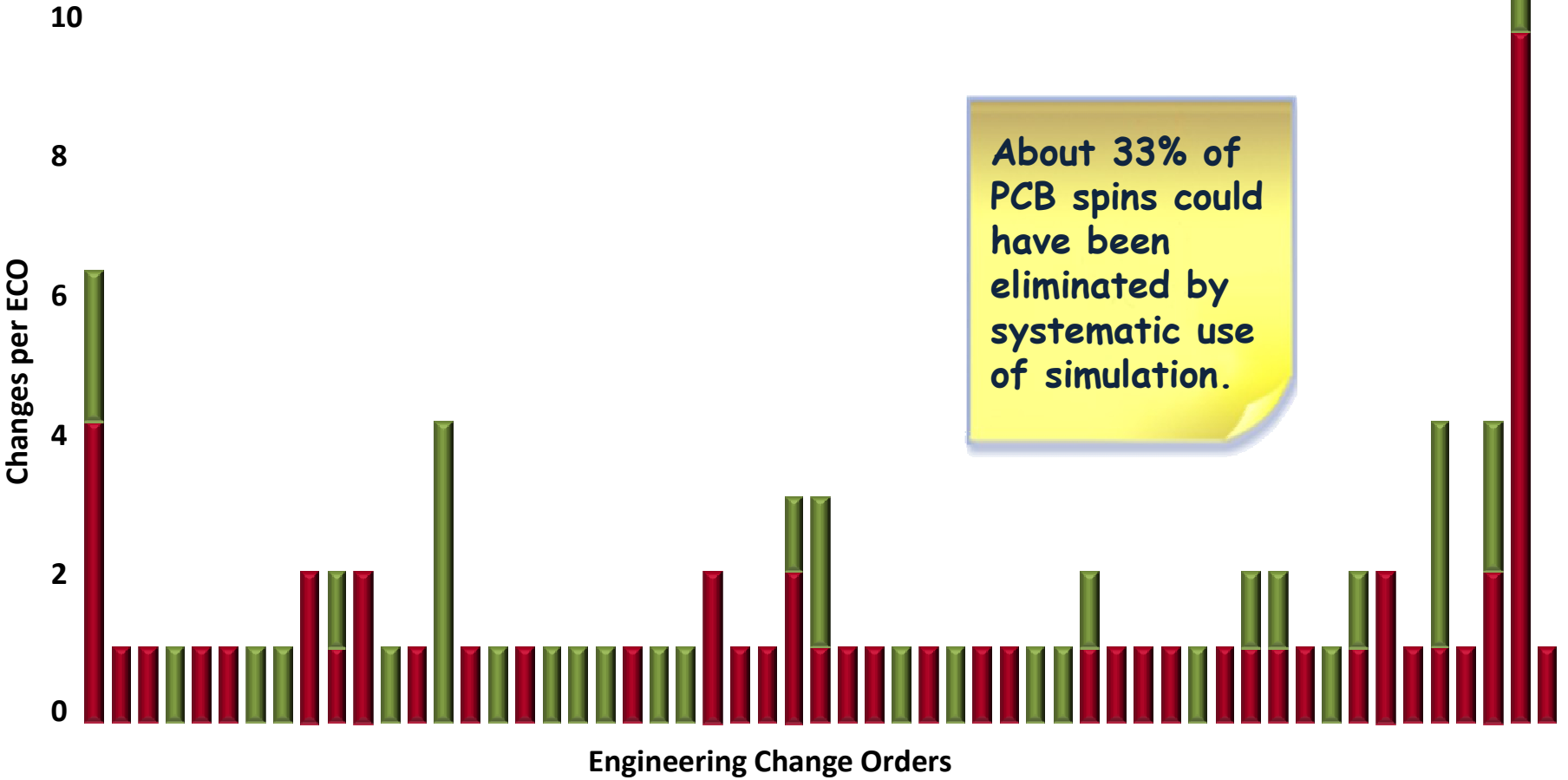
Errors Detectable by Simulation



SIMPLIS could detect 51% of all errors and 56% of errors that required a board spin.



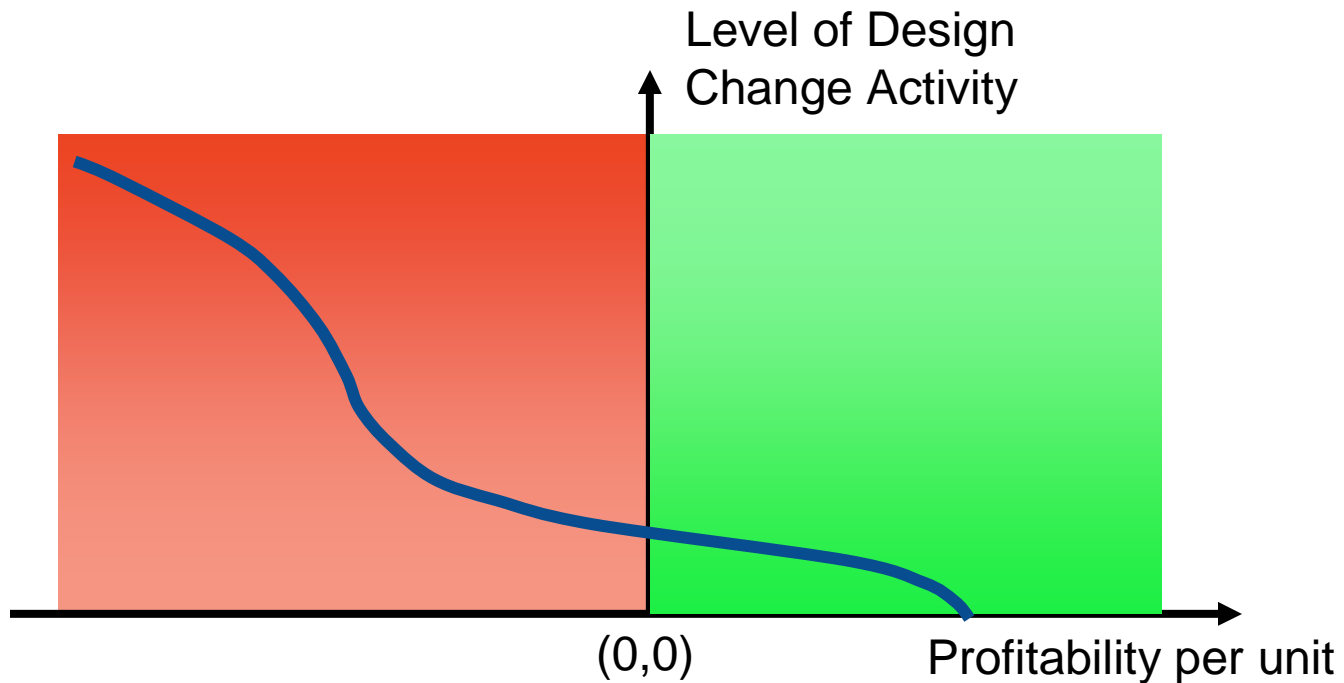
Detectable Changes Per ECO



Virtual Prototyping of Power Supply Designs

- Virtual Prototyping Objective
 - Reduce number of latent design errors that are left to be discovered in prototype hardware
 - Reduce number of hardware iterations required to meet design requirements
 - Reduce time before design can be profitably manufactured
 - **Get design into profitable manufacture as soon as possible**

Virtual Prototyping Objective



As a rolling stone gathers no moss,
so a churning design gathers no profits

Virtual Prototyping of Power Supply Designs

Virtual Prototypes will not replace Hardware Prototypes in any reasonable planning horizon, so why bother?

- Benefits of reducing hardware iterations
 - Reduce time to profitable design
 - Reduce development cost
 - Increase effective development capacity
- No other single process improvement comes within an order of magnitude of this level of benefit

Survey -- Time to valuable simulation results

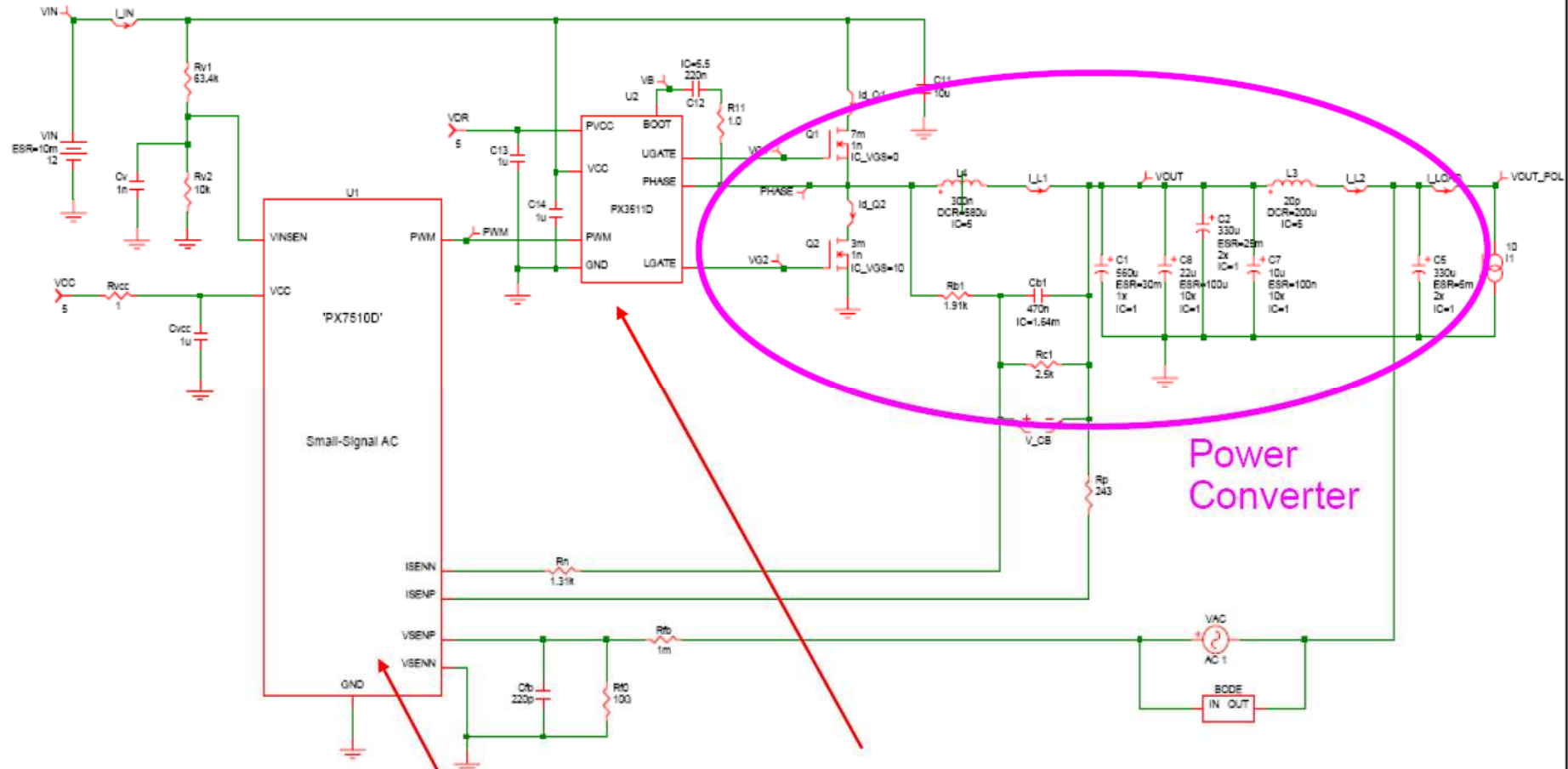
- If you could identify 50% of your latent design errors via simulation before 1st prototype, would you spend
 - 5 minutes
 - 5 hours
 - 5 days
 - 5 weeks
 - 5 monthson simulation?

Virtual Prototyping – why now?

- Costs of failure rising sharply
 - \$\$
 - Time
- Costs of simulation have fallen
 - \$\$
 - Time
 - *Time to valuable simulation results has fallen below critical threshold in many applications*

Time-Domain Simulation Model

SIMPLIS Simulation Circuit & IC Model



Power Converter

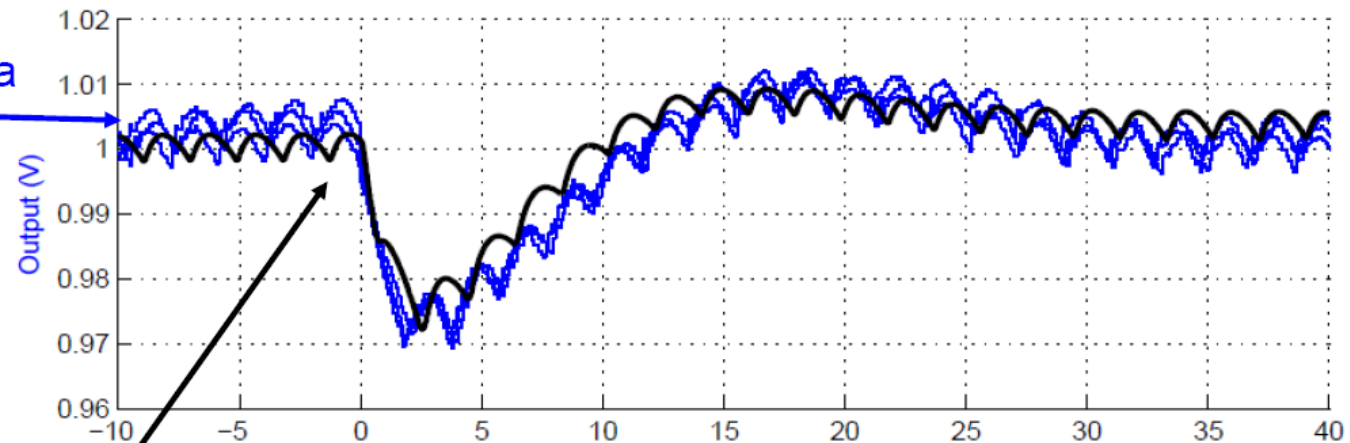
PX3511D Gate Driver

PX7510D IC Controller Model



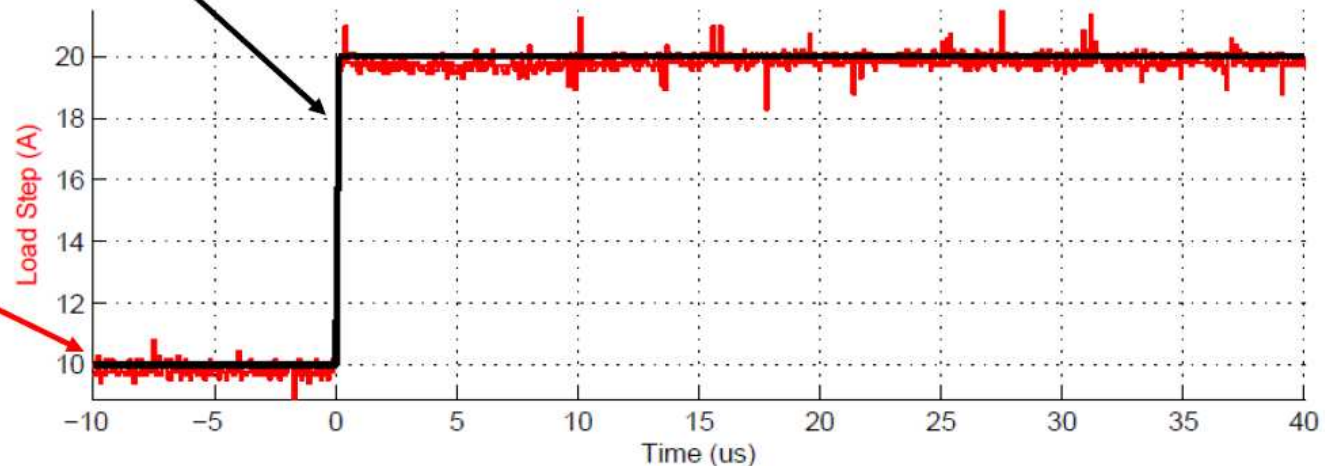
Time-Domain Simulation vs. Experimental Results

Output Voltage
Imported Scope Data
3 Traces



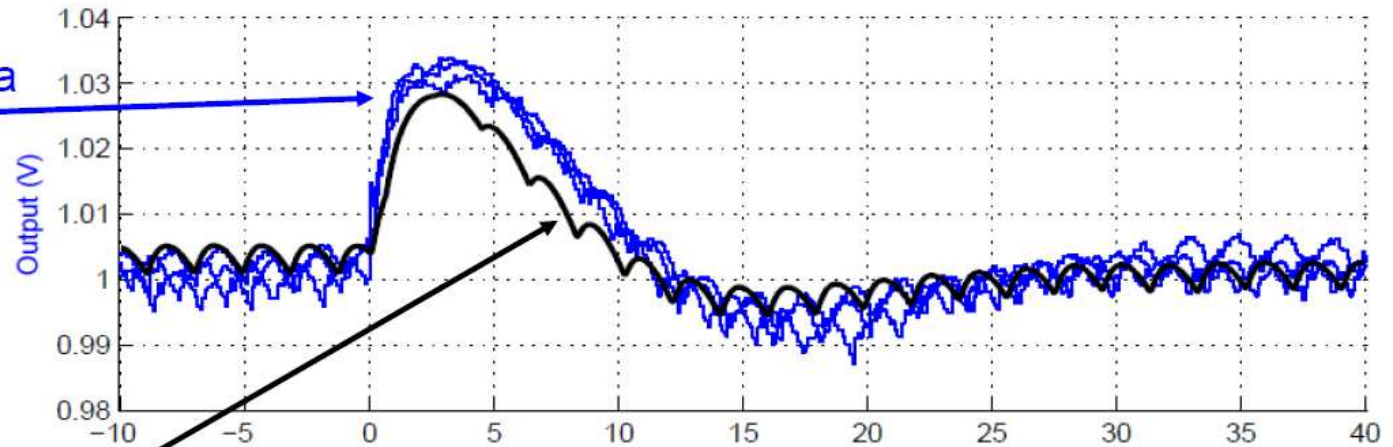
SIMPLIS™
Simulation Model

10 A to 20 A
Load Step
A 10 A Step
with a 10 A
Static Load



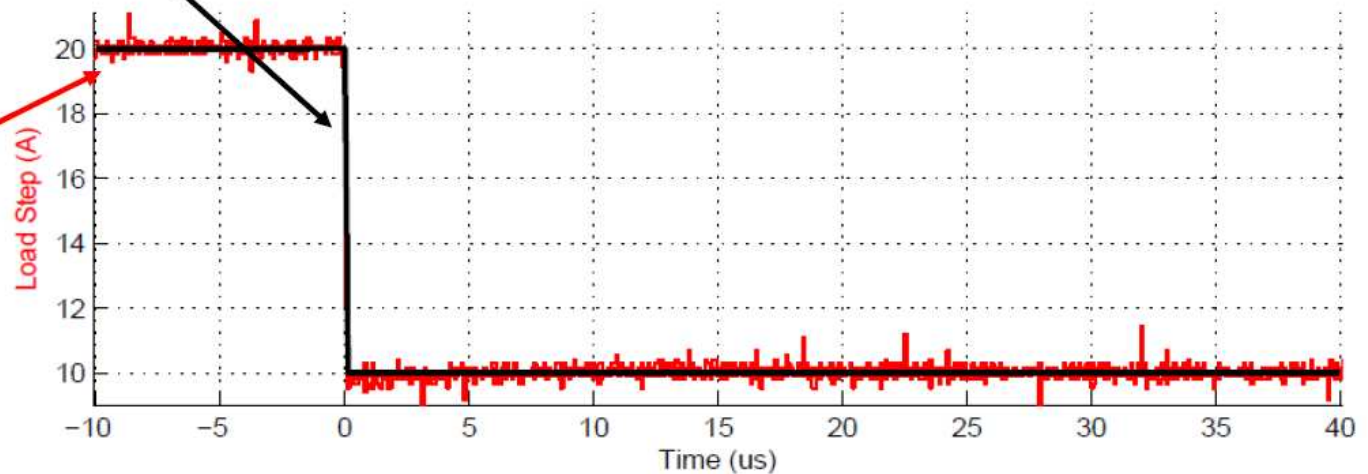
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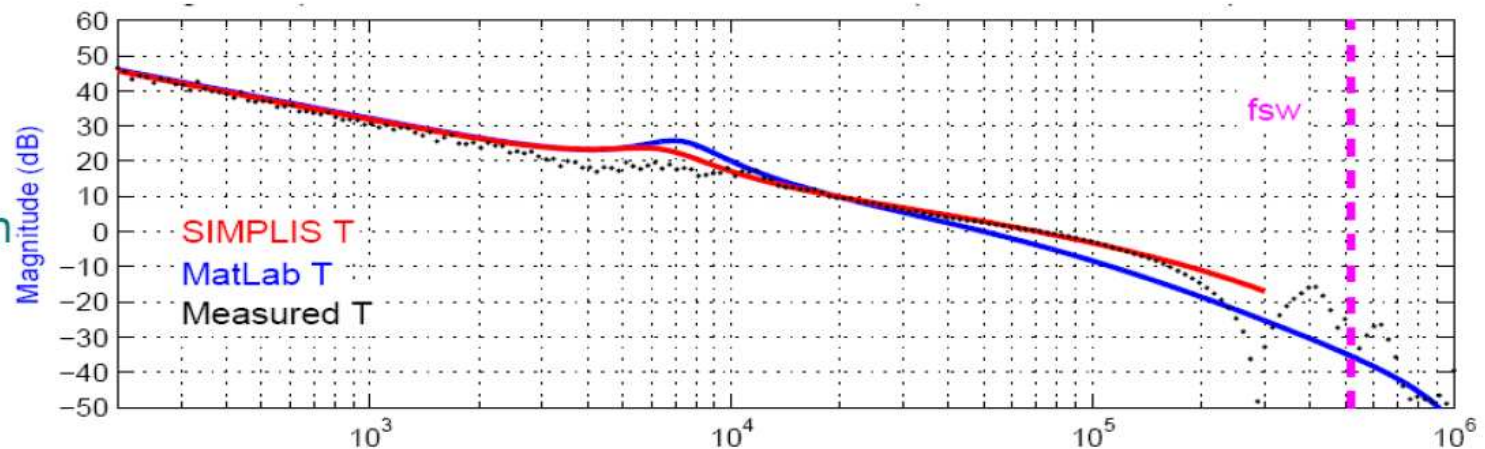
SIMPLIS™
Simulation Model

20 A to 10 A
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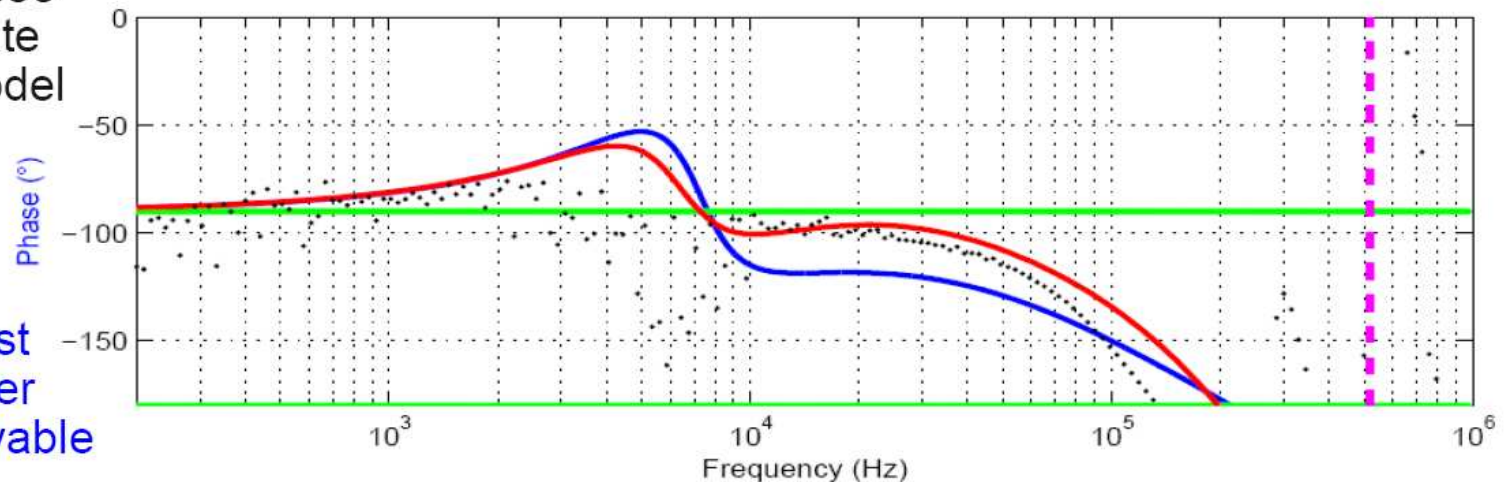


Frequency-Domain Comparison: Complex Zeroes

This is a more aggressive design

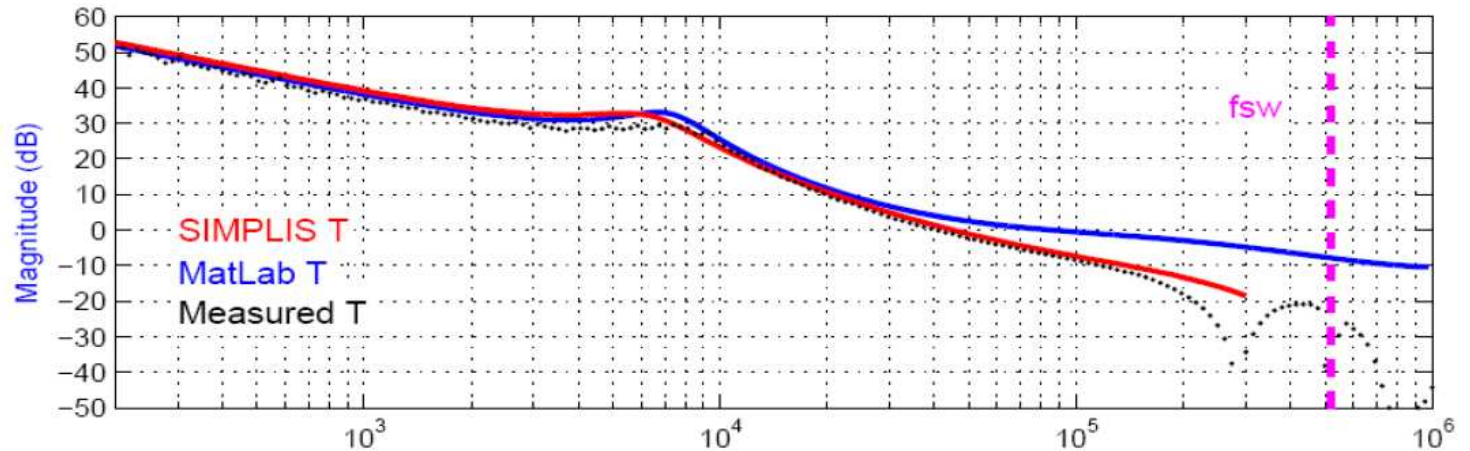


The MatLab model shown here uses a more accurate digital loop model



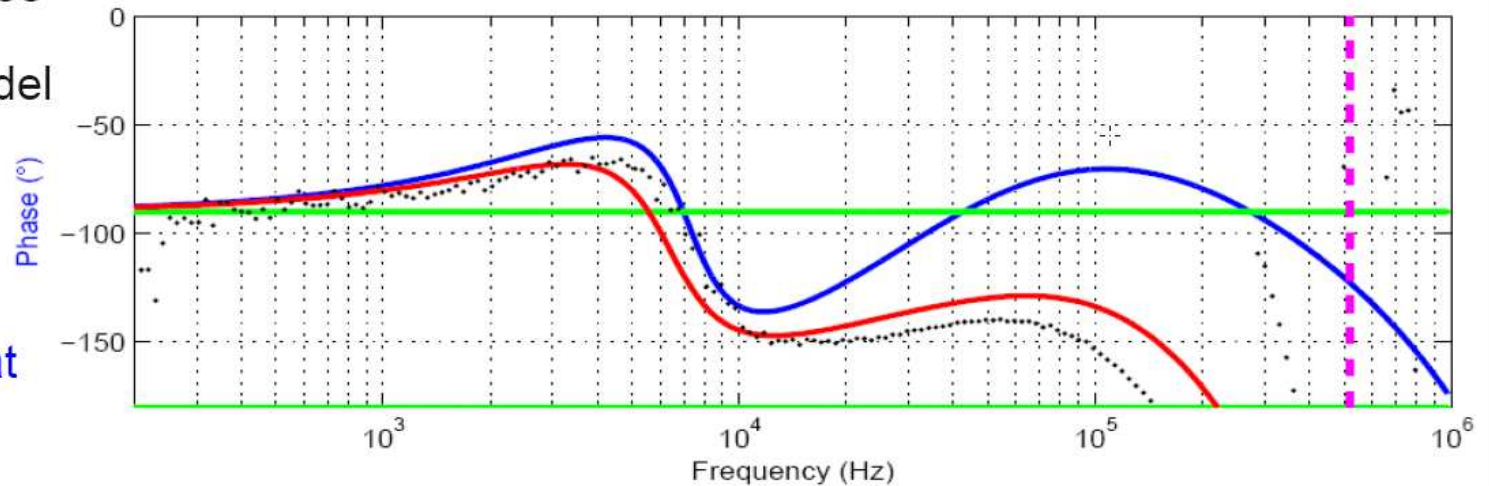
More phase boost throughout, higher crossover achievable

Frequency-Domain Comparison: Real Zeroes



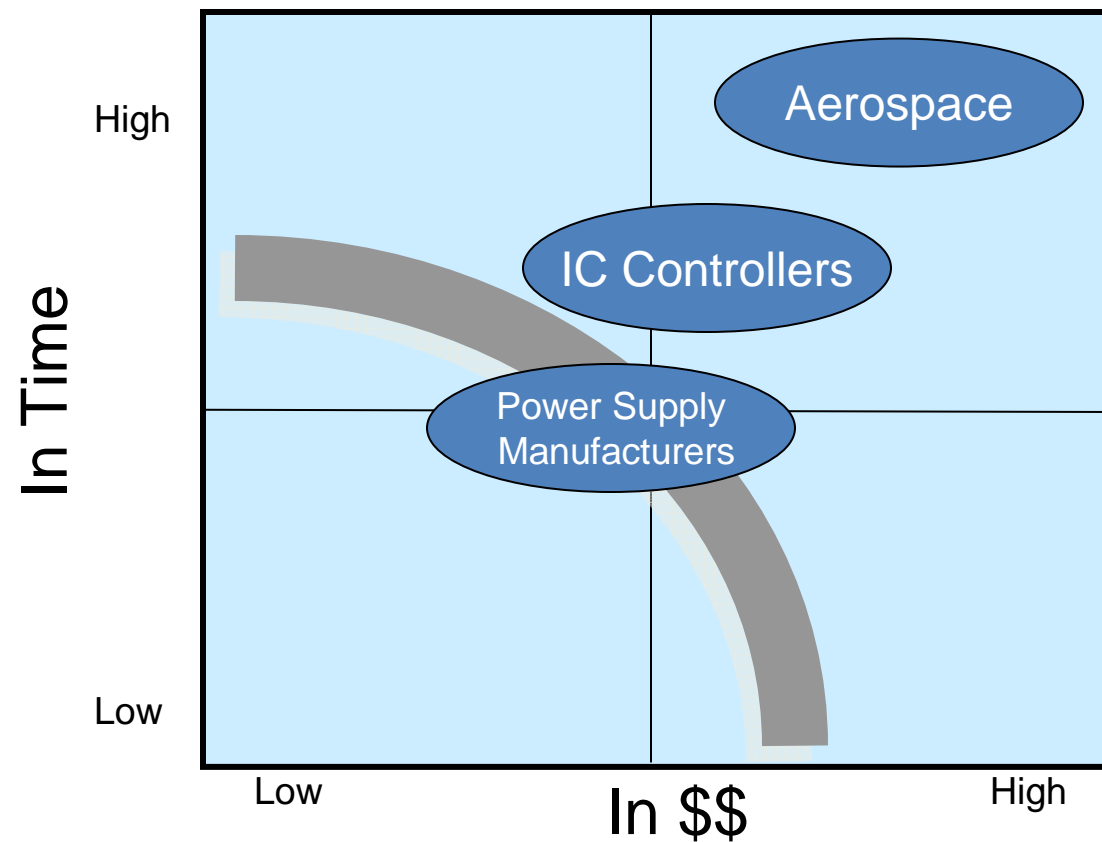
The MatLab model shown here uses a simplified digital loop model

Both the gain and phase are less accurate at the higher frequencies



Pain Threshold – when does Virtual Prototyping make sense?

Cost of Failure / Cost of sim results



Virtual Prototyping of Power Supply Designs

- Seminar Objective:
 - Provide practical guidance on how to use circuit simulation to detect more Design Errors sooner before they get committed to next hardware iteration
 - Virtual Prototyping
 - Illustrate current capabilities
 - Outline critical success factors
 - Discuss future directions

Different Analysis Types – Definitions

- Periodic Operating Point Analysis
- AC Analysis
- Transient Analysis

Periodic Operating Point (POP) Analysis – What is it?

- POP Analysis finds the steady-state Limit Cycle or the Periodic Operating Point of a periodically switching system
- POP Analysis works on full nonlinear switching time-domain model of circuit
- POP Analysis is typically much faster than running a long time-domain transient

Periodic Operating Point (POP) Analysis – How it works

- Takes snapshot of all inductor currents and capacitor voltages at beginning of a conversion cycle
- Simulates in time domain one conversion cycle
- Takes another snapshot of all inductor currents and capacitor voltages at beginning of next conversion cycle
- Looks at the normalized difference of all capacitor voltages and inductor currents and tries to find a set of initial conditions that will drive this difference to zero
- Will stop when difference diminishes to $\sim 10^{-9} \%$
 - This is miniscule when compared to a Spice rel tol of 10^{-3}



D.24.5

Why Periodic Operating Point (POP) Analysis can fail (in order of frequency)

- Circuit is not stable
- Initial conditions are too far away from steady-state limit cycle
- POP Trigger is not connected to a proper node so that a trigger signal is generated once every complete conversion cycle
- POP analysis settings constrain the analysis so that
 - Max Period is less than conversion period
 - Max Period is much too large
 - Number of POP iterations is too small

POP Analysis enables AC analysis

- Because POP error is so small, we can inject a very small AC signal into a feedback loop and measure a valid small signal AC response – ***in the time domain*** – with very high accuracy
- Level of injected AC signal is automatically controlled to keep AC response of nonlinear circuit in its “linear” small signal region
- AC analysis is performed on full nonlinear time-domain switching model – ***no averaged model required***

Virtual Prototyping of Power Supply Designs

- We will look at Virtual Prototyping Process
 - From 3 Perspectives:
 - Power Supply Designer **90 min**
 - Power Management IC Architect **40 min**
 - Power System Designer **15 min**

Since all three do power supply design, we will spend ~ 50% our time in that area

Keys to making Virtual Prototyping Practical

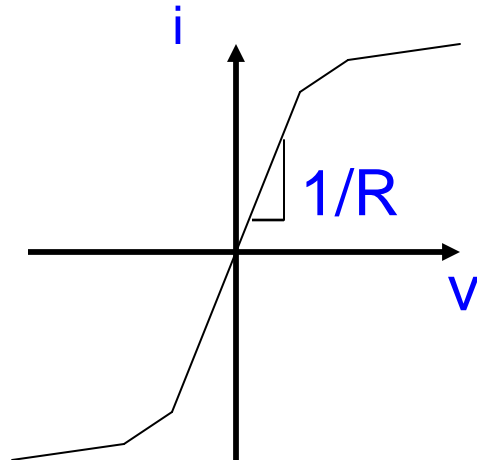
- Piecewise Linear (PWL) Modeling & Simulation
 - Enables required speed and accuracy
- Clear & Focused Simulation Strategy
 - Always clear about ***simulation objective***
 - Includes quantities to be measured and required accuracy
 - Aware of required ***level of device modeling*** to achieve simulation objectives
 - **This is where engineers are most likely to fail to achieve benefits of Virtual Prototyping**

Piecewise Linear Modeling and Simulation

- Simulation Speed ~ 10 – 50 X faster than Spice
- Convergence is qualitatively better than Spice for switching power supplies
- Simulation Speed and Convergence performance dramatically increase the practical scope of power supply designs that can benefit from Virtual Prototyping
- To achieve required accuracy, multi-level modeling is managed according to simulation objective

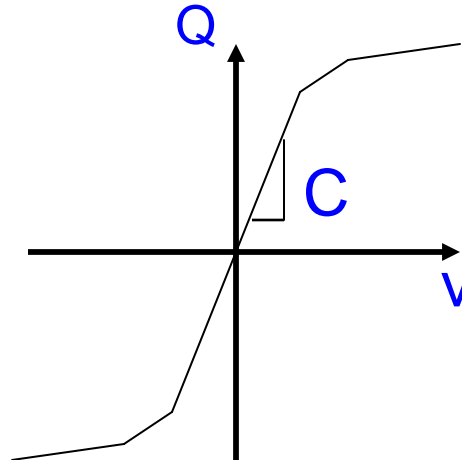
Piecewise Linear Components

Resistors



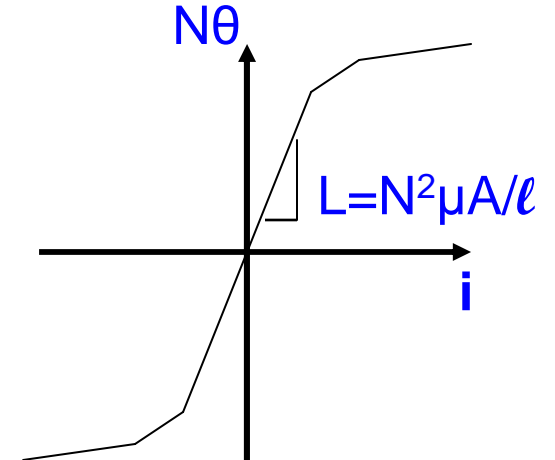
x-value \rightarrow Voltage
y-value \rightarrow Current

Capacitors



x-value \rightarrow Voltage
y-value \rightarrow Charge

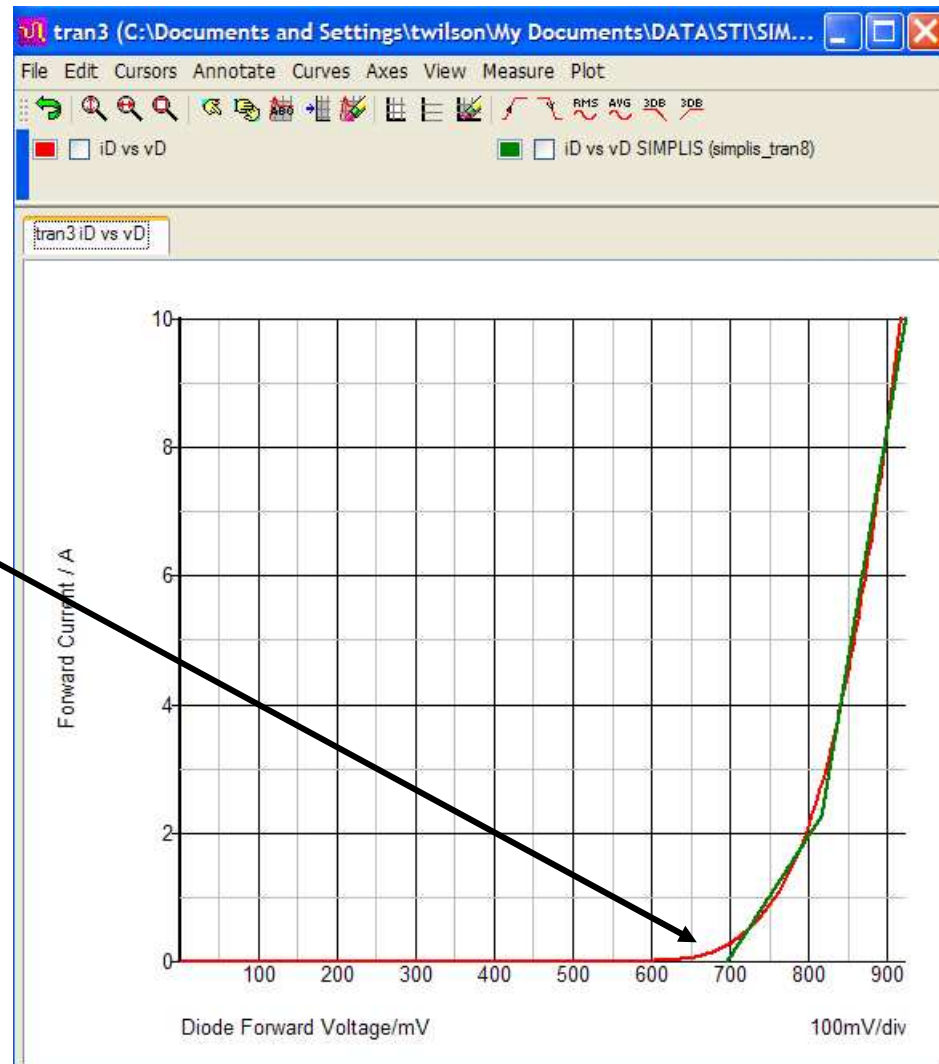
Inductors



x-value \rightarrow Current
y-value \rightarrow Flux Linkages

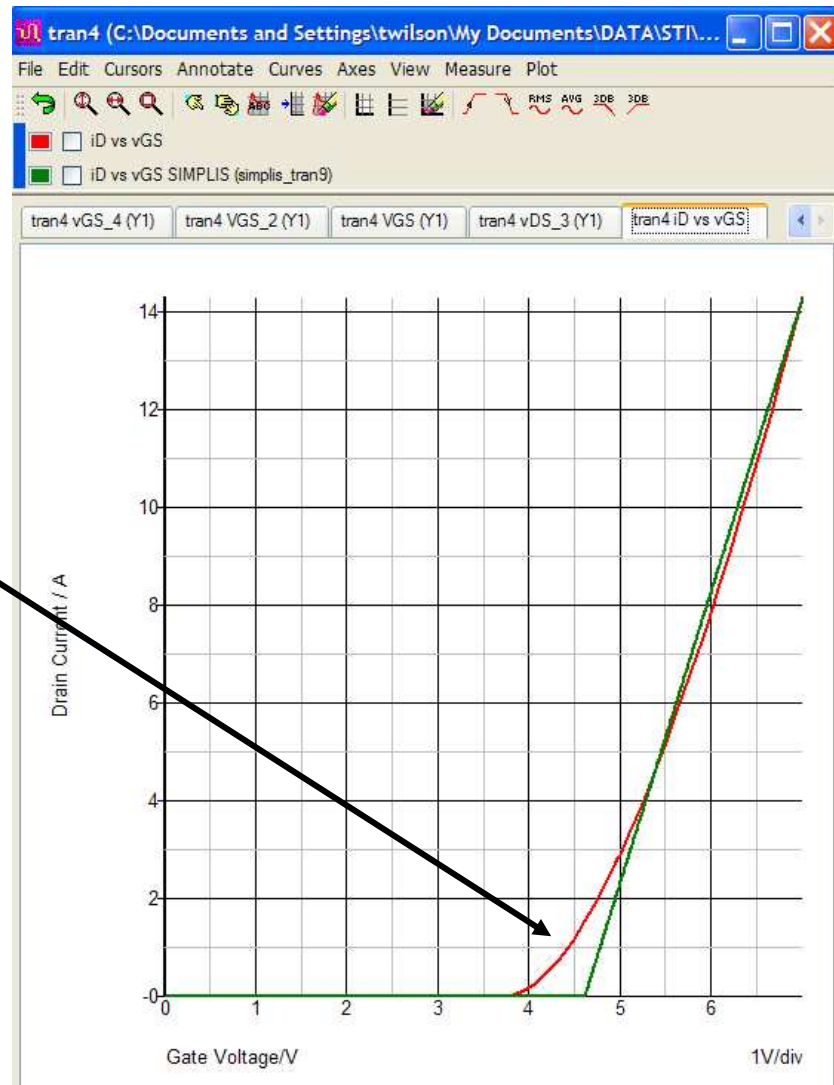
Diode PWL Model

- Three-segment SIMPLIS diode model (green)
- Compared to Spice model (red)
- Fit optimized over 4A – 8A range

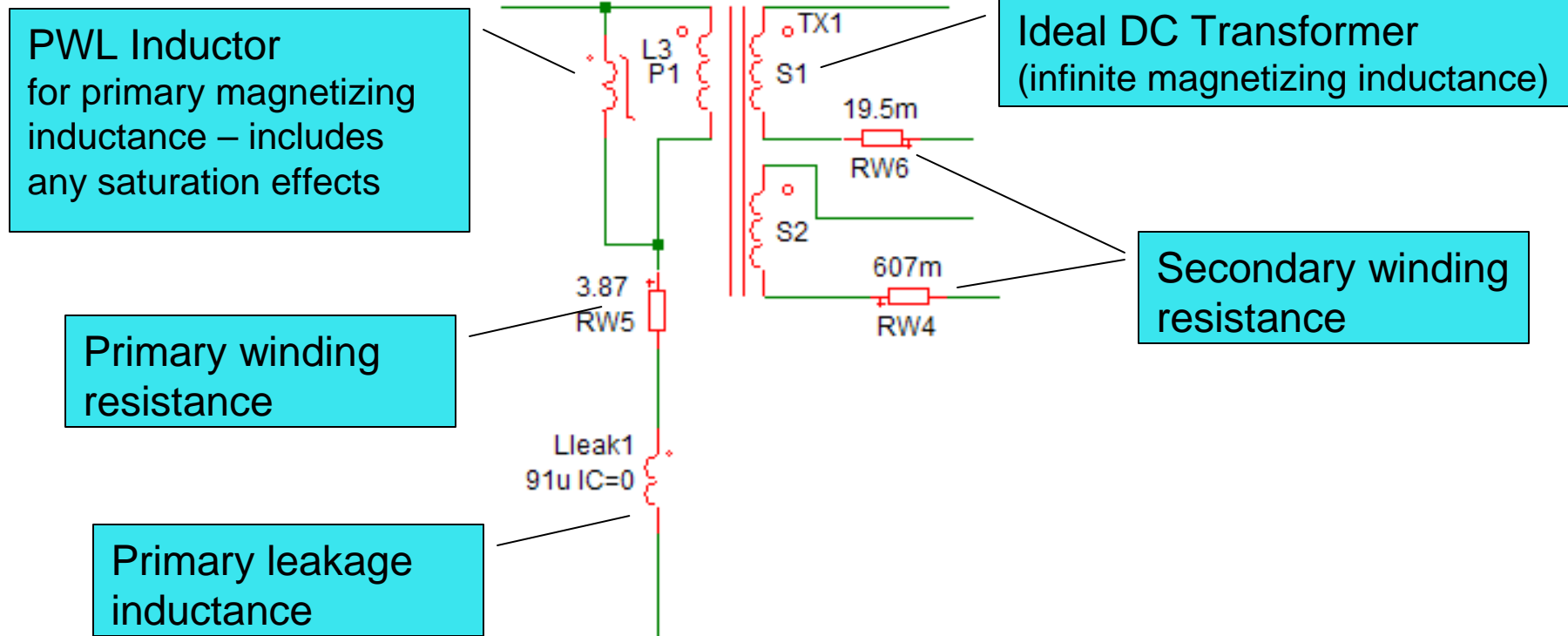


FET PWL Model

- Two-segment SIMPLIS i_D vs. v_{GS} (green)
- Compared to Spice model (red)
- Fit optimized over 33% - 100% of I_{max}

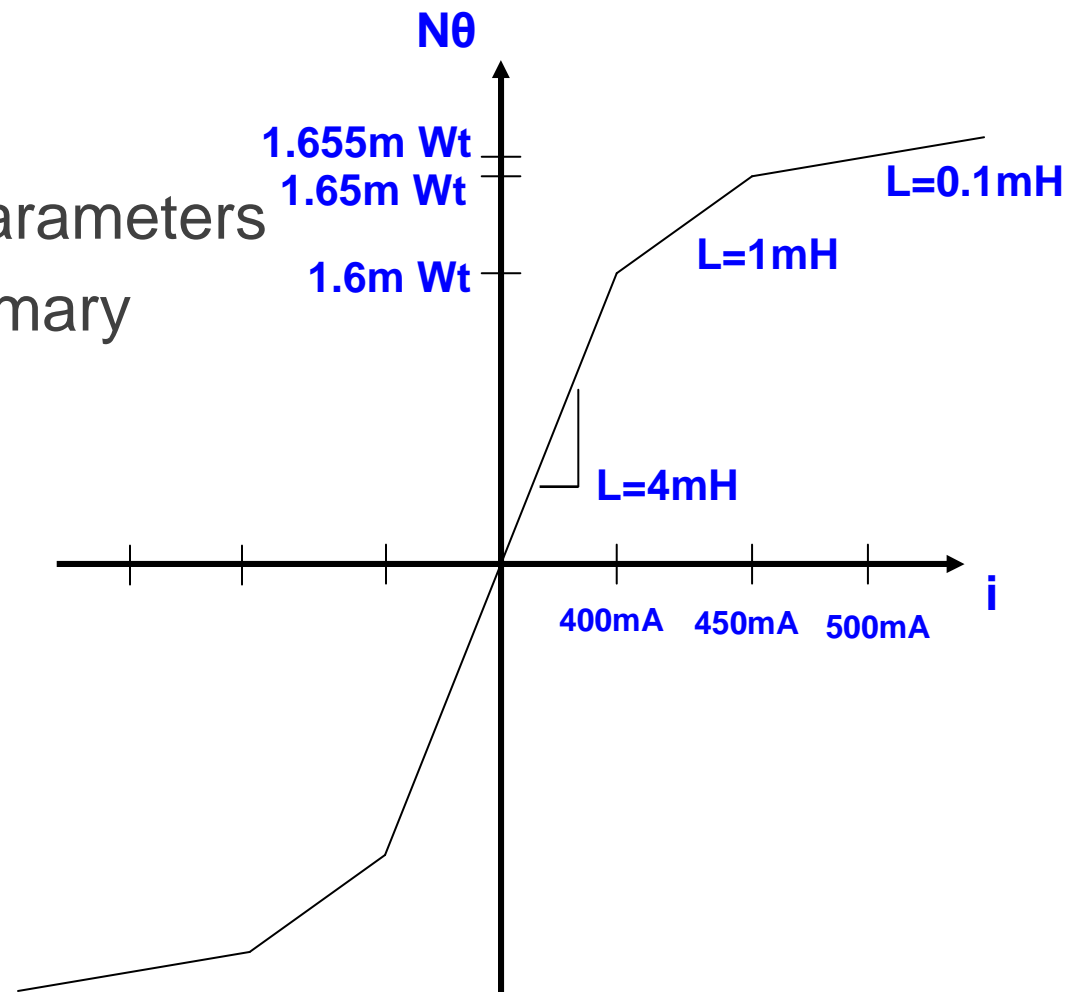


PWL Transformer model



Saturable Inductor (PWL Inductor)

- Use the following parameters for the saturable primary inductance
- Run simulation.
- Confirm expected saturation at about 400mA



Model Accuracy

- **Accuracy of Physics:** the Physics behind the equations that describe semiconductors
 - Spice - very accurate
 - SIMPLIS – piecewise linear behavioral approximations
- **Accuracy of Parameters:** the value of the constants used in the model
 - Spice – mere mortals cannot typically create their own Spice models
 - SIMPLIS – models are based on data sheet info and can be created by average user in ~20 minutes
- **Accuracy of solution of circuit equations:**
 - Spice – in order to get practical speed, Spice must accept more numerical error (RelTol) per computational step
 - SIMPLIS – takes advantage of piecewise linear system to get extremely accurate numerical solutions of circuit equations

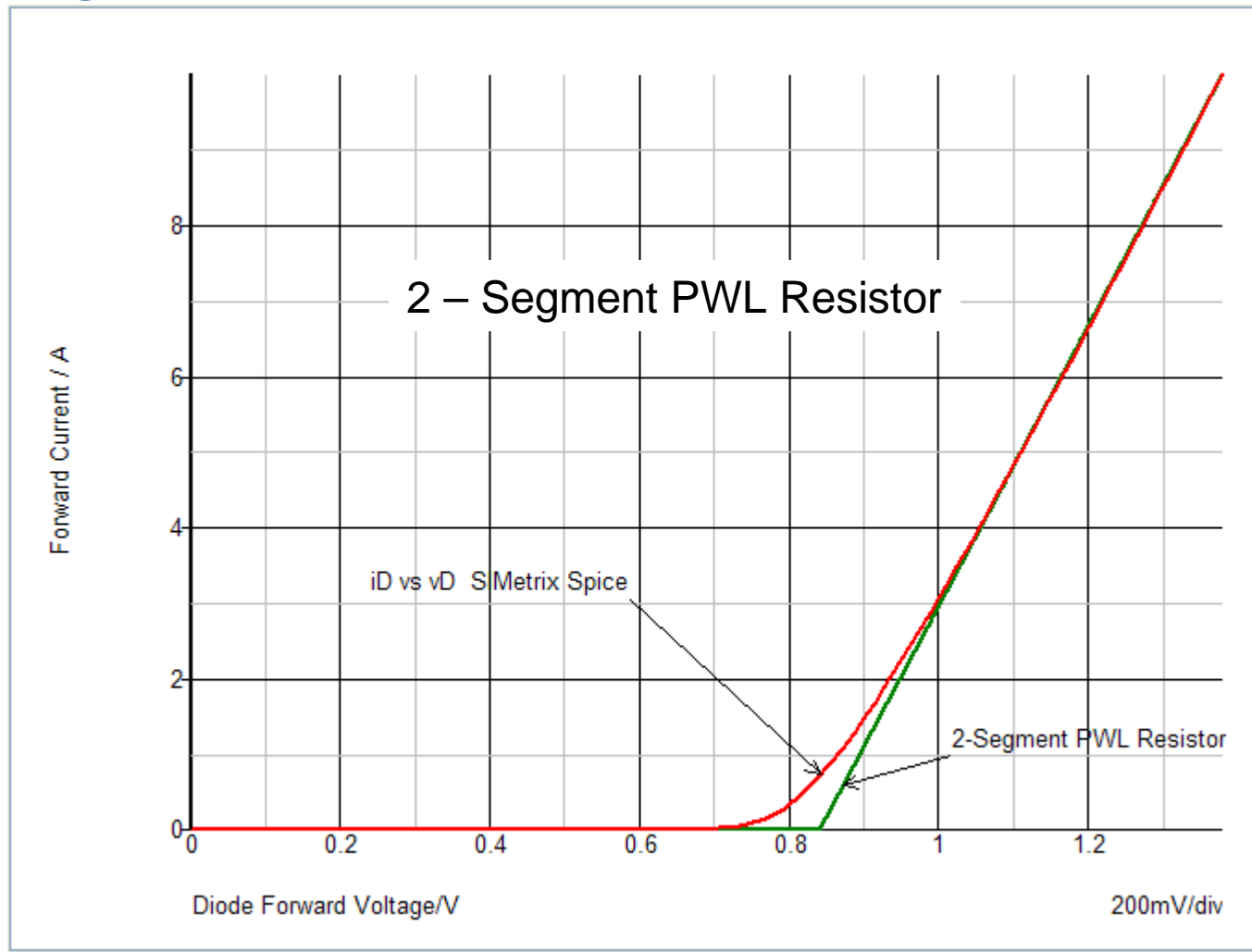
Simulation Accuracy vs. Simulation Time

- What is necessary to achieve required accuracy within reasonable simulation times?
 - PWL modeling and simulation -- Speed
 - Multi-level modeling – Accuracy
 - Clear Simulation Objectives

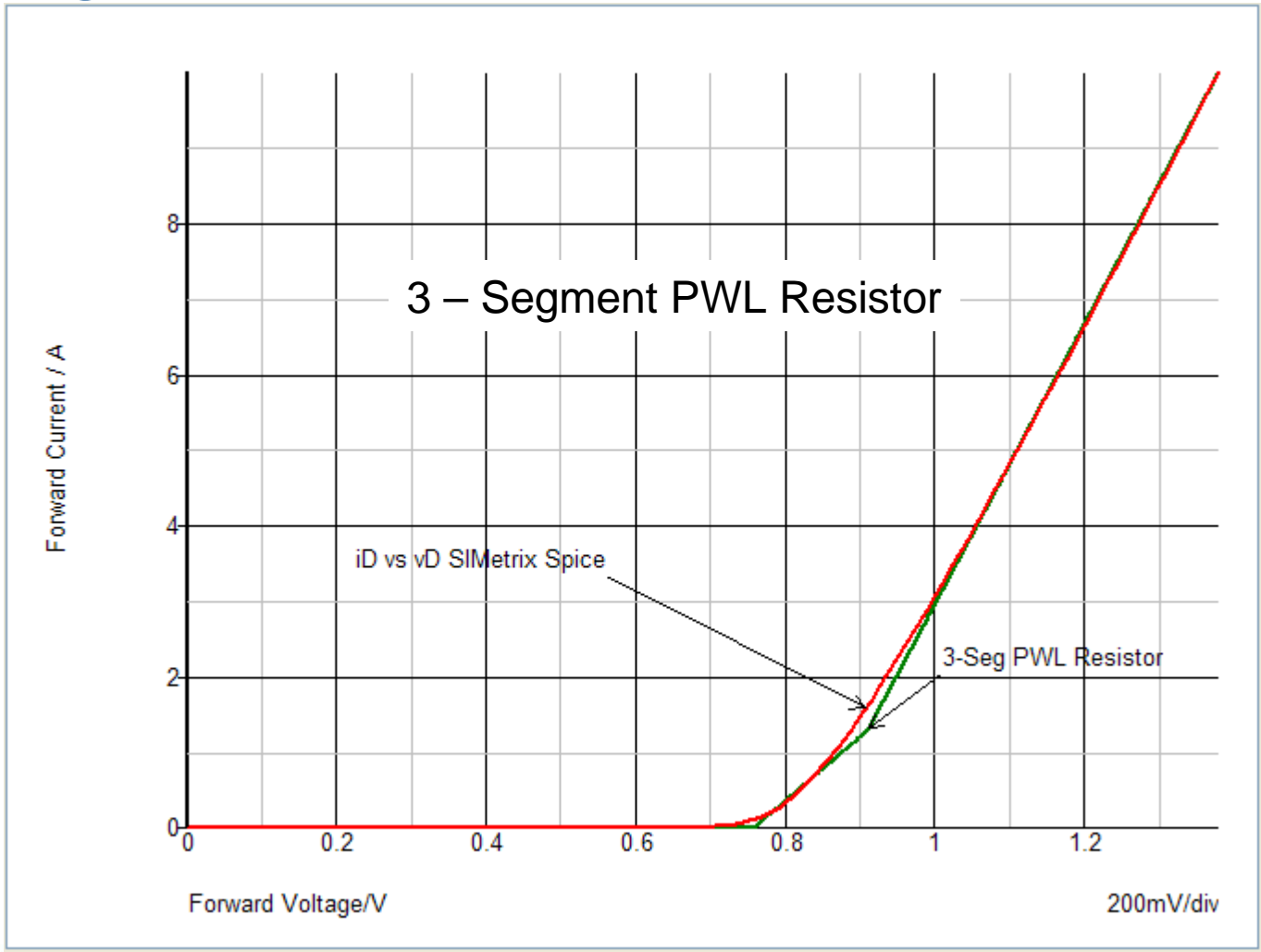
Examples of Multi-level Modeling

- Diode Rectifiers – two or three segment model
- Output Capacitors – add ESR, add ESL
- MOSFETs – with and without switching losses
- Transformer – with and without saturation

Modeling Diodes with PWL Resistors

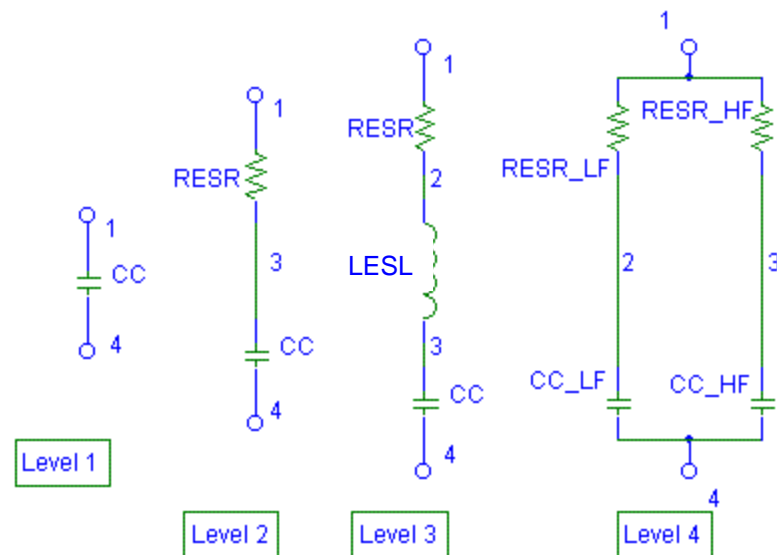


Modeling Diodes with PWL Resistors



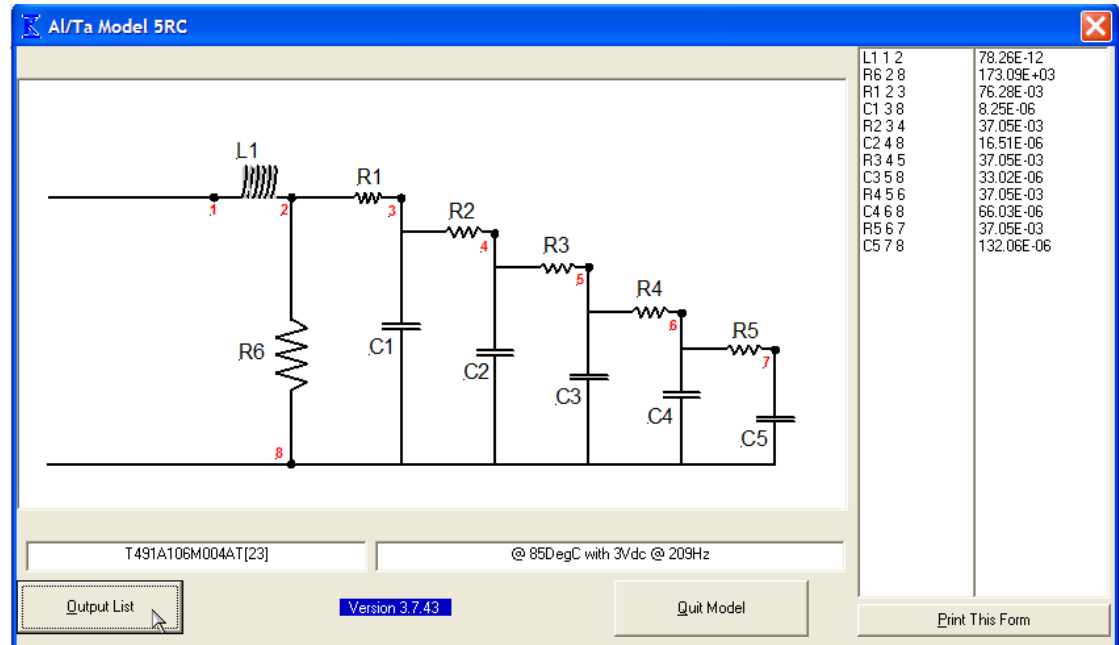
Multi-level modeling

- Select appropriate level of model complexity to optimize simulation accuracy and speed
- Include device parasitics where critical to simulation objectives
 - Example: Output Capacitor
 - Start up
 - Level 2
 - Stability analysis
 - Level 4 or 2
 - High di/dt load transient
 - Level 3



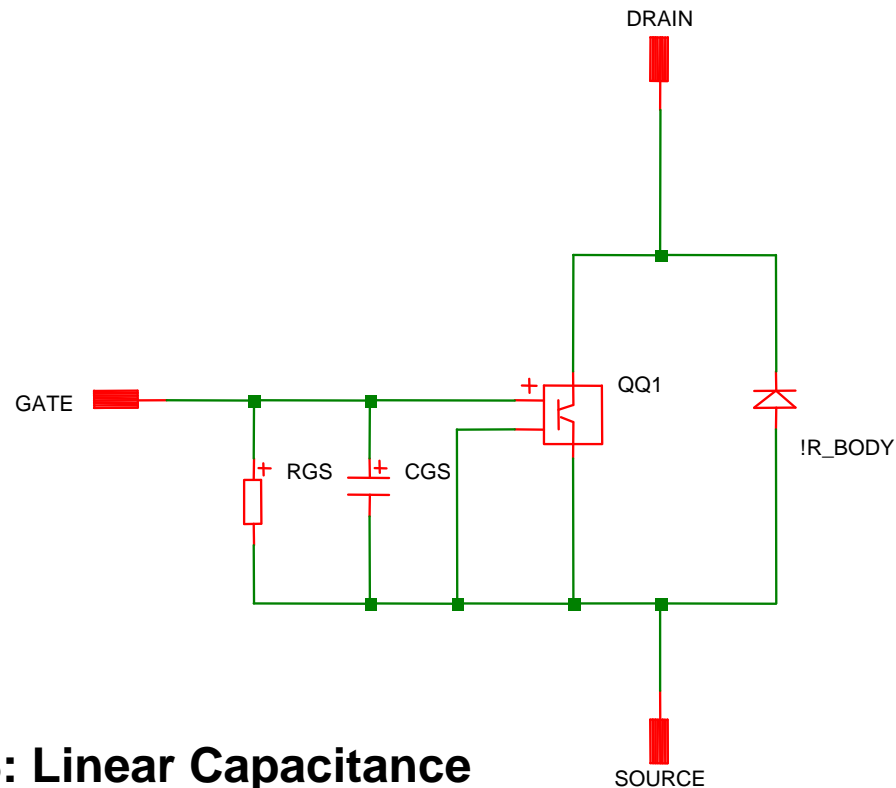
Kemet Capacitor Model Generator

- Adjusts Capacitor models for
 - DC bias
 - Temp
 - Number of Caps in parallel



- <http://www.simplistech.com/downloads>
- <http://www.kemet.com/kemet/web/homepage/kechome.nsf/weben/kemsoftSIMPLIS>

Modeling Level 1 N-channel MOSFET

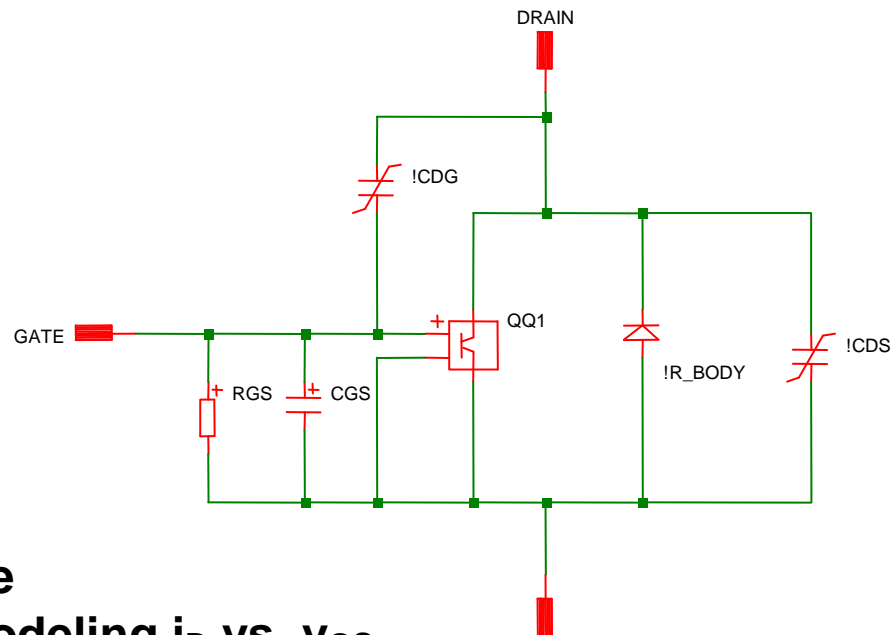


CGS: Linear Capacitance

QQ1: Switch with On & Off Resistance

!R_BODY: Body diode modeled by PWL Resistor

Modeling Level 3 N-channel MOSFET



CGS: Linear Capacitance

**QQ1: SIMPLIS Switch modeling i_D vs. v_{GS}
proportional to $(v_{GS} - V_{TO})$**

!R_BODY: Body diode modeled by PWL Resistor

!CDG : PWL capacitance

!CDS : PWL capacitance

Add B vs. time waveform to transformer model

PWL Resistor

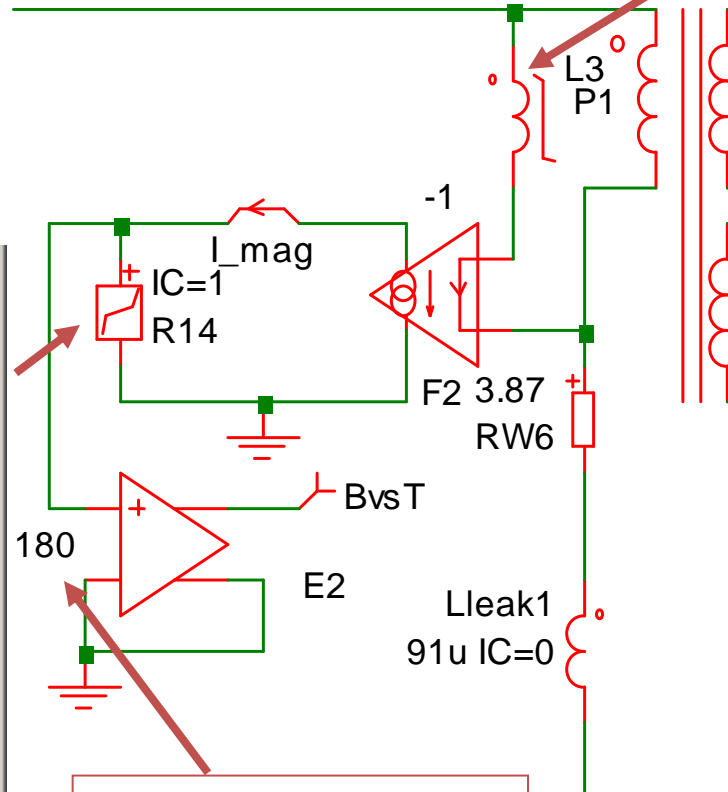
x – voltage=Weber-turns
y – magnetizing current

Define PWL Device

	X-Value	Y-Value
1	-1.655m	-0.5
2	-1.65m	-0.45
3	-1.6m	-0.4
4	1.6m	0.4
5	1.65m	0.45
6	1.655m	0.5
7		

"Insert" inserts a row or rows
"Delete" deletes selected rows

Ok Paste Cancel



$$\text{Gain} = 1 / (NA)$$

N = primary turns

A = core area in m^2

Define PWL Device

	X-Value	Y-Value
1	-0.50	-1.655m
2	-0.45	-1.65m
3	-0.40	-1.6m
4	0.40	1.6m
5	0.45	1.65m
6	0.50	1.655m
7		

"Insert" inserts a row or rows
"Delete" deletes selected rows

Ok Paste Cancel

PWL Inductor

x – magnetizing current
y – Weber-turns

Core Loss Model

$$P = \alpha V [(\Delta B m / (2t_{ON}) n) t_{ON} / T_s + (\Delta B m / (2t_{OFF1}) n) t_{OFF1} / T_s]$$

where

t_{ON} is the interval when switch is on and flux density B is increasing;

t_{OFF1} is the interval when switch is off and flux density is decreasing;

t_{OFF2} is the zero-voltage time, the interval when switch is off and flux density is not changing;

T_s is the switching period, which is the sum of t_{ON} , t_{OFF1} , and t_{OFF2} ;

V is the volume of the core.

α , m and n are constants for each core material, based on *square wave excitation*

- “**A Method for Inductor Core Loss Estimation in Power Factor Correction Applications**”
Jinjun Liu, Thomas G. Wilson, Jr., Ronald C. Wong, Ron Wunderlich, and Fred C. Lee, APEC 2002

Benefits of PWL modeling and simulation

- Much faster time-domain transient simulations
- Ability to find Steady-State limit cycle much faster than long transient simulation
- Ability to do AC analysis on a circuit that is in Steady State time domain operation
 - No average model required
- Speed and Accuracy levels can be achieved with proper attention to
 - multi-level modeling
 - clear simulation objectives

Select Modeling Level based on Simulation Objective

- Example: 3-Phase Synchronous Buck
 - What modeling levels are required for **Bode Plot** ?
 - What modeling levels are required for **Step Load** transient with moderate di/dt ?
- Issue:
 - Include switching losses of Sync FETs ?
 - Compare simulation times and results

Select Modeling Level based on Simulation Objective

- Example: Self Oscillating Flyback
 - What modeling levels are required for **Bode Plot** ?
- Issue:
 - With self oscillating converter, the **switching frequency is reduced by non-zero switching transitions**.
 - Do these losses materially affect Bode Plot?

Simulation Objective = AC Analysis - Bode Plot

- Sync Buck sim times ***without*** Switching losses
 - POP - 6 s
 - AC - 3 s
 - Step Load Tran - 13 s
- Sync Buck sim times ***with*** Switching losses
 - POP - 56 s
 - AC - 13 s
 - Step Load Tran - 103 s

Nearly a **10x** increase in simulation time for **zero** benefit

Modeling Level vs. Simulation Objective and Device Type

Simulation Objective \ Device Type	Output Diode Rectifier	Output Capacitor (Electrolytic)	Output Capacitor (Ceramic)	Output Inductor	MOSFET Power Switch	
Bode Plot (Steady-State, AC analysis)						
Step Load Transient – moderate di/dt (Steady-State, Transient analysis)						
Step Load Transient – high di/dt (Steady-State, Transient analysis)						
Line and Load Regulation (Steady-State analysis)						

Modeling Level vs. Simulation Objective and Device Type

Simulation Objective \ Device Type	Output Diode Rectifier	Output Capacitor (Electrolytic)	Output Capacitor (Ceramic)	Output Inductor	MOSFET Power Switch	
Bode Plot (Steady-State, AC analysis)	2-seg	Lev 2	Lev 1	Linear Lossy	Lev 1	
Step Load Transient – moderate di/dt (Steady-State, Transient analysis)	2-seg	Lev 2	Lev 1	Linear Lossy	Lev 1	
Step Load Transient – high di/dt (Steady-State, Transient analysis)	2-seg	Lev 3	Lev 1	Linear Lossy	Lev 1	
Line and Load Regulation (Steady-State analysis)	3-seg*	Lev 2	Lev 1	Linear Lossy	Lev 1	

Simulation Accuracy vs. Simulation Time

- What is necessary to achieve required accuracy within reasonable simulation times?
 - PWL modeling and simulation
 - Multi-level modeling
 - **Clear Simulation Objectives**

Clear & Focused Simulation Strategy

- Two major benefits of being clear and focused
 - You can go farther
 - You can get there much faster

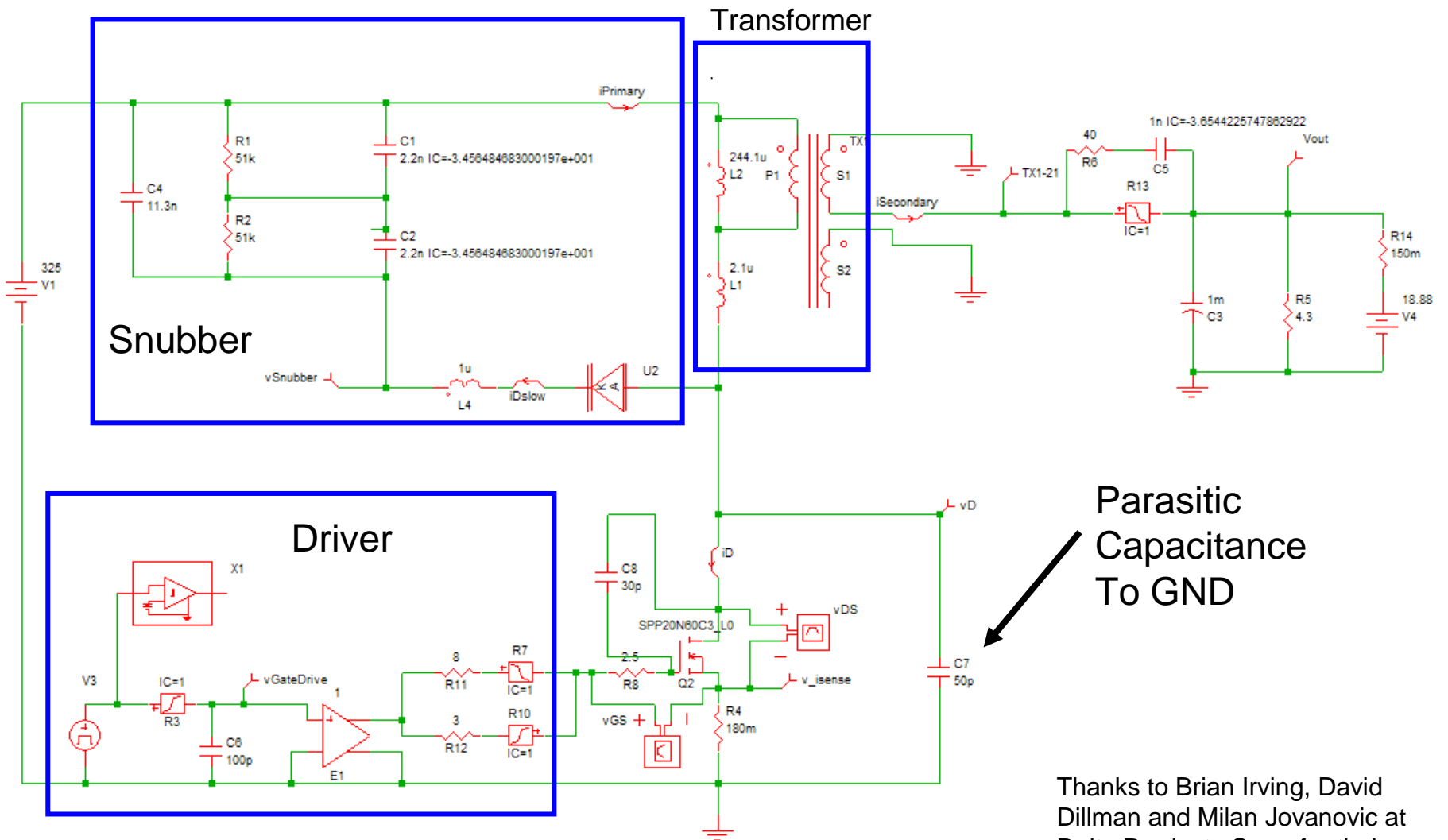
Clear & Focused Simulation Strategy

- Example: Flyback for Adapter
 - What modeling levels are required for device stress and loss measurements?
- Specifically
 - What is needed to get good power loss estimates?
 - Given that switching loss measurements are more challenging than measuring loop response behavior

Switching Losses

- Switching losses are very sensitive to
 - Device parasitic elements
 - Layout parasitic elements
- Device parasitics can be characterized in advance
- For maximum benefit, virtual prototyping is done **before** a layout exists
 - So there are inherent uncertainties in this effort
- This area of simulation is less mature than simulation of closed loop performance
- Even so, *the initial estimate of switching losses plays a central role in the development process*

Switching Losses – Flyback for Adapter



Parasitic Capacitance To GND

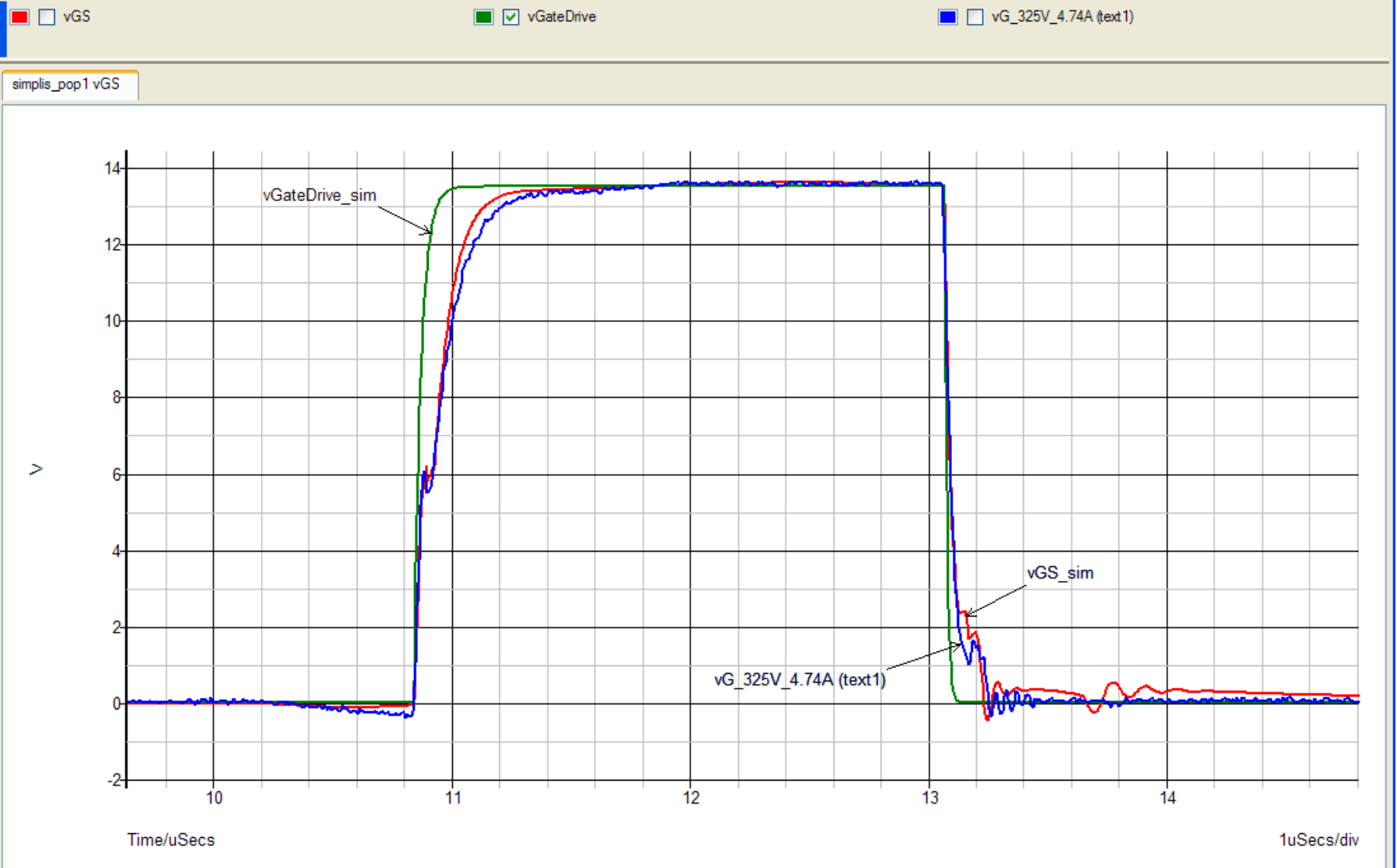
Thanks to Brian Irving, David Dillman and Milan Jovanovic at Delta Products Corp. for their support in this effort

Switching Losses – Flyback for Adapter

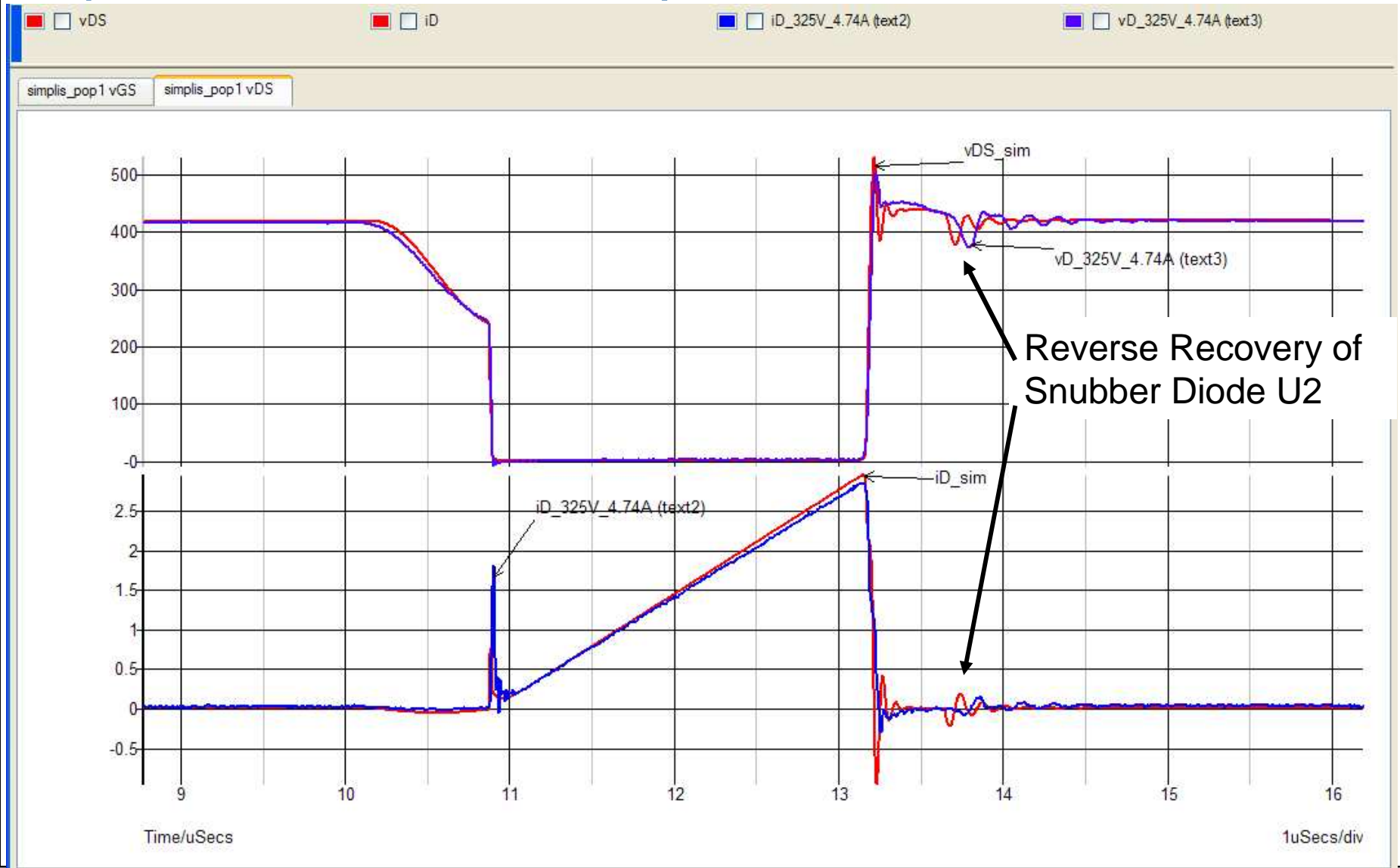
- Run simulation test circuit open loop in Steady State
- Adjust Driver, FET and Snubber Diode models to match measured waveforms at $V_{in} = 325V$, $V_{out} = 18.88V$ and Full Load $I_{out} = 4.74A$
- Then compare simulated waveforms and measured waveforms at different line and load conditions with “identical” gate drive signals

Gate Voltage v_{GS}

($V_{in} = 325V$, $I_{out} = 4.74A$)

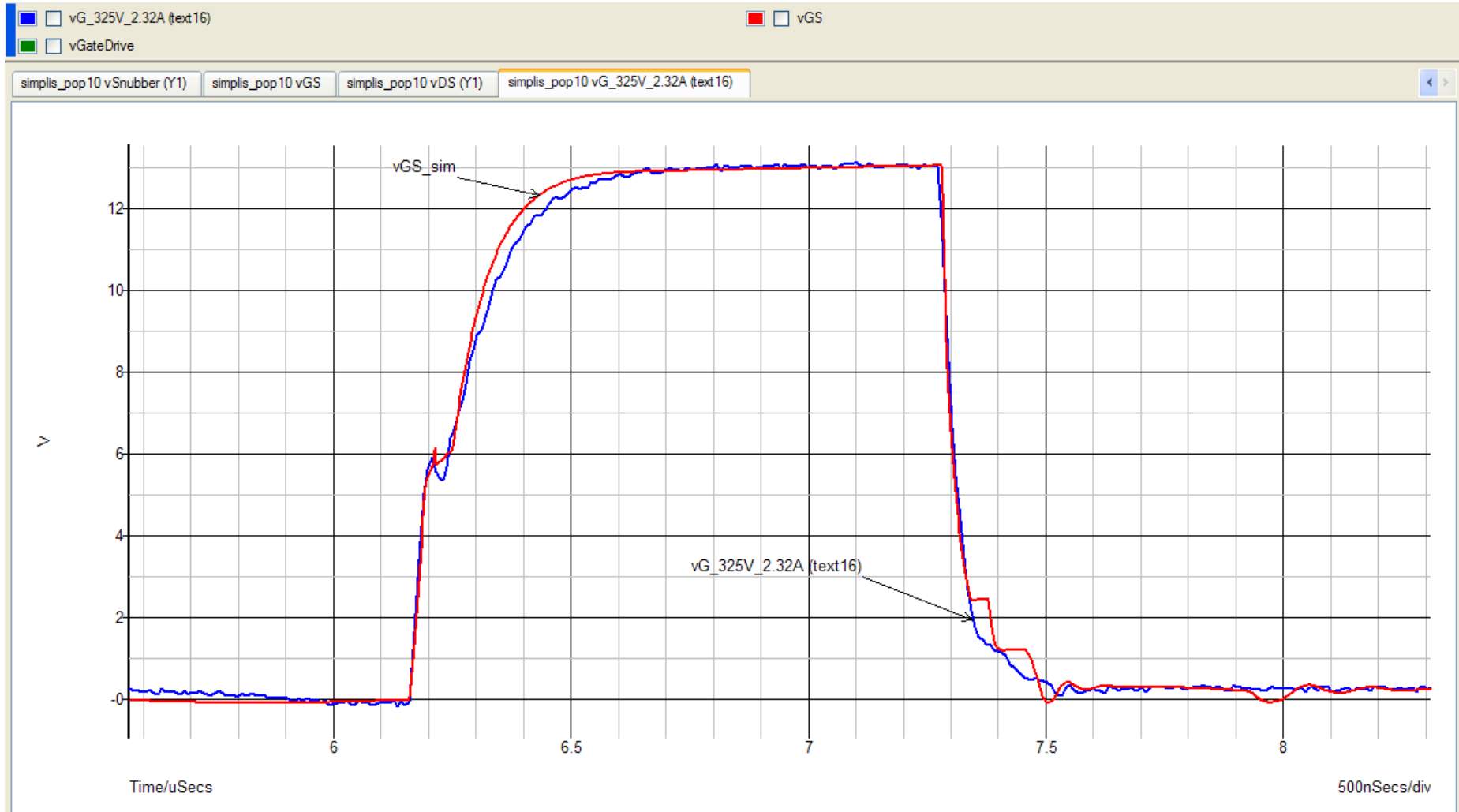


Drain Voltage v_{DS} and Drain Current i_D ($V_{in} = 325V$, $I_{out} = 4.74A$)



Gate Voltage v_{GS}

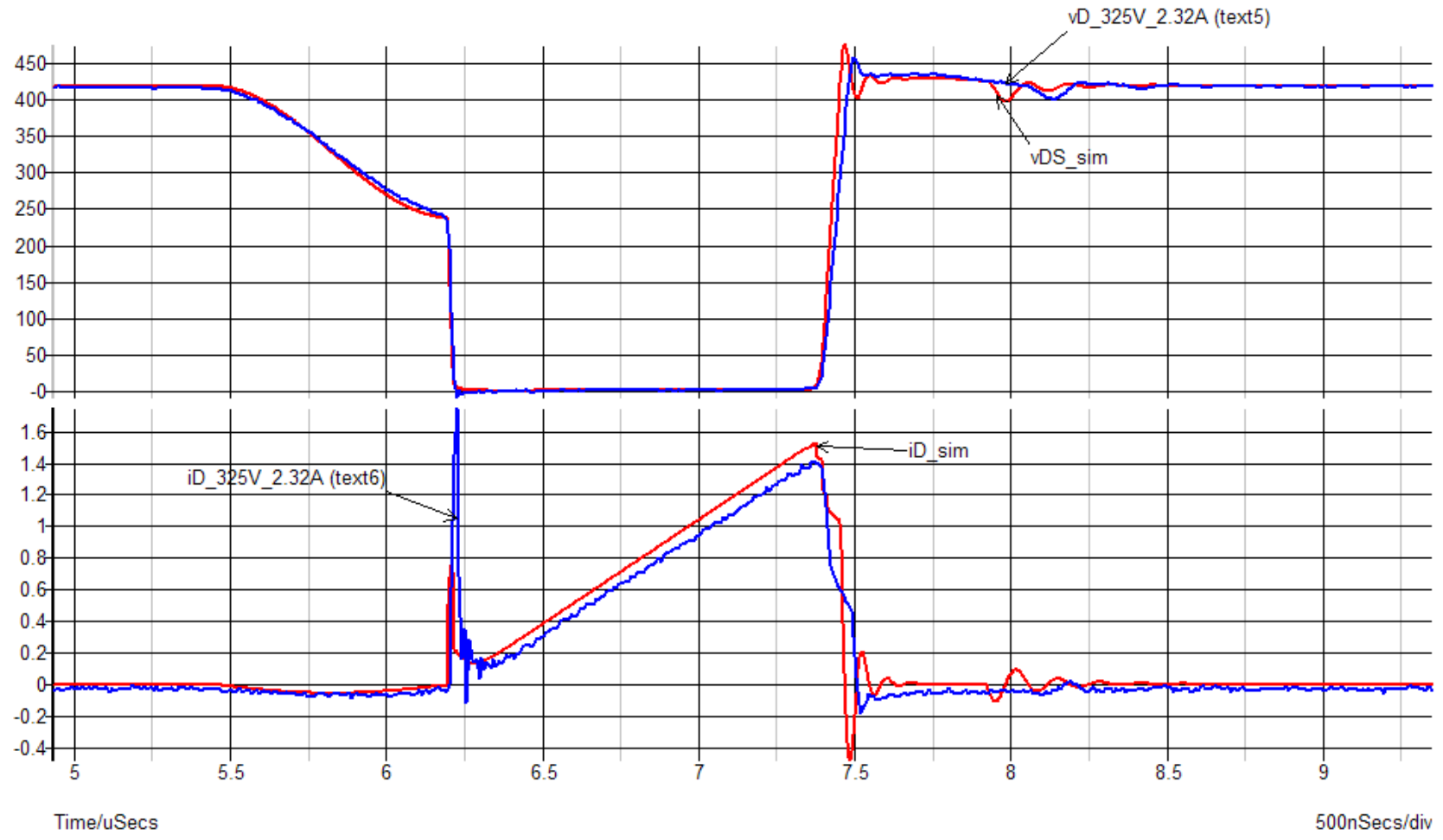
($V_{in} = 325V$, $I_{out} = 2.32A$)



Drain Voltage v_{DS} and Drain Current i_D ($V_{in} = 325V$, $I_{out} = 2.32A$)

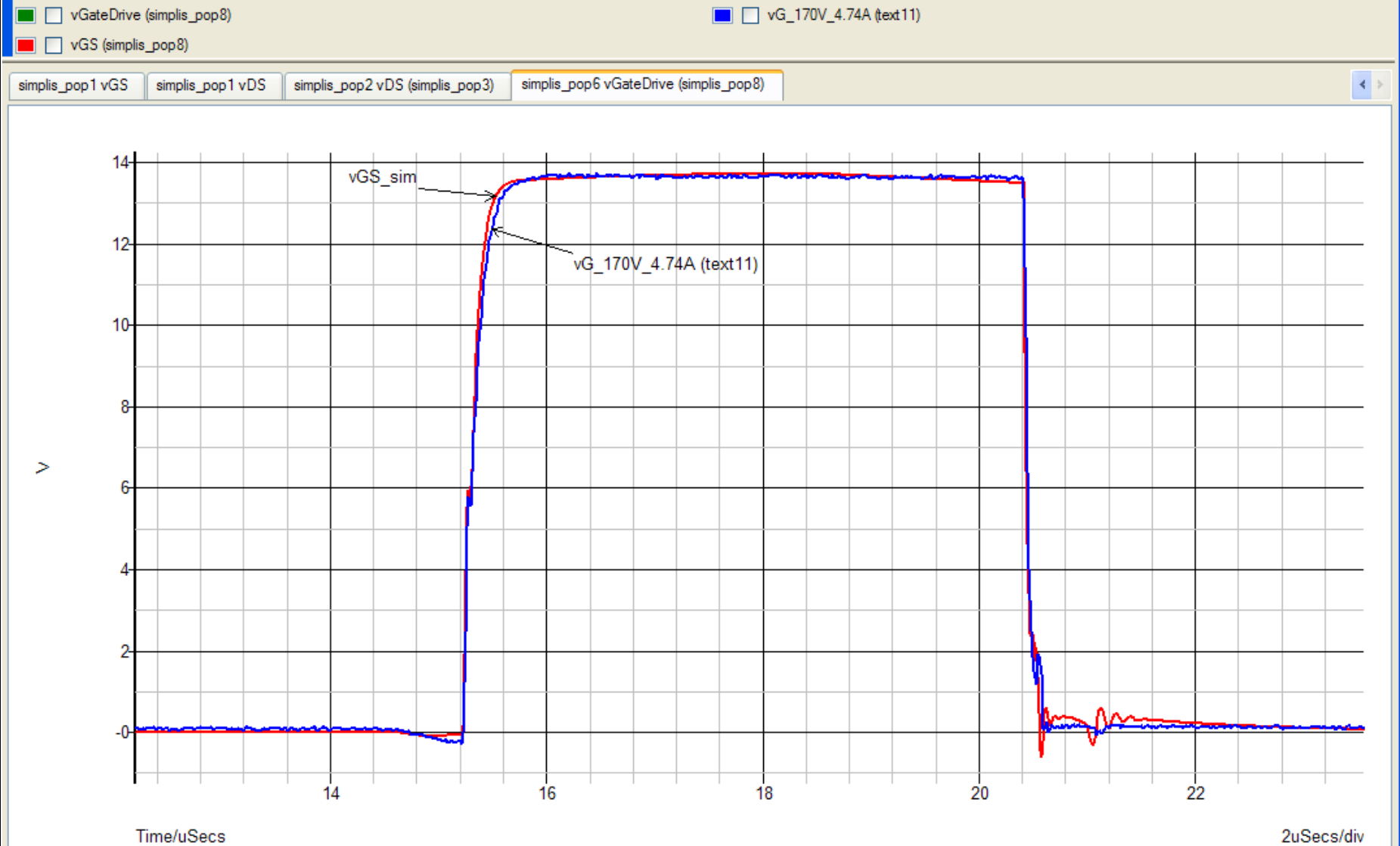
vDS (simplis_pop3) iD (simplis_pop3) vD_325V_2.32A (text5) iD_325V_2.32A (text6)

simplis_pop1 vGS simplis_pop1 vDS **simplis_pop2 vDS (simplis_pop3)**



Gate Voltage v_{GS}

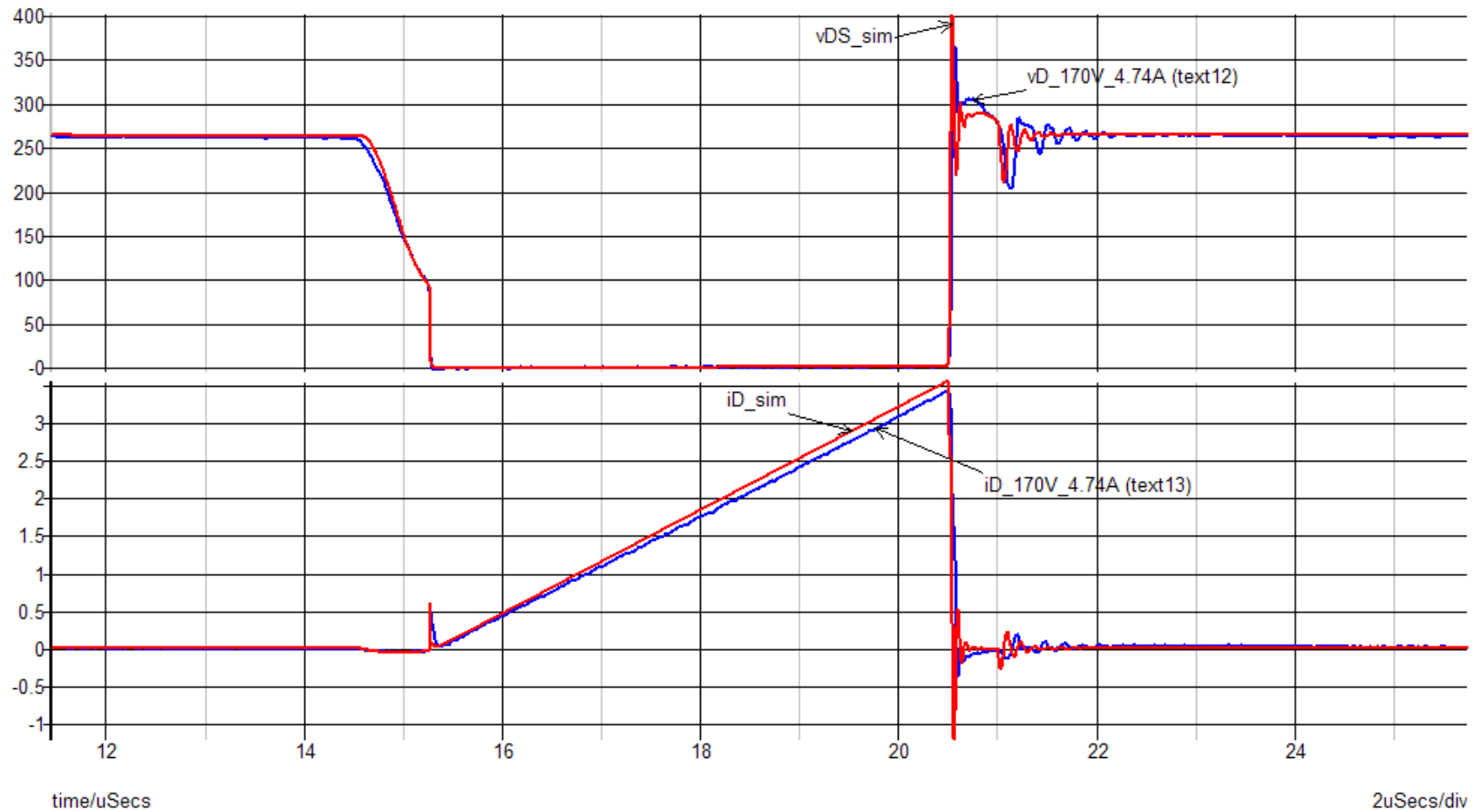
($V_{in} = 170V$, $I_{out} = 4.74A$)



Drain Voltage v_{DS} and Drain Current i_D ($V_{in} = 170V$, $I_{out} = 4.74A$)

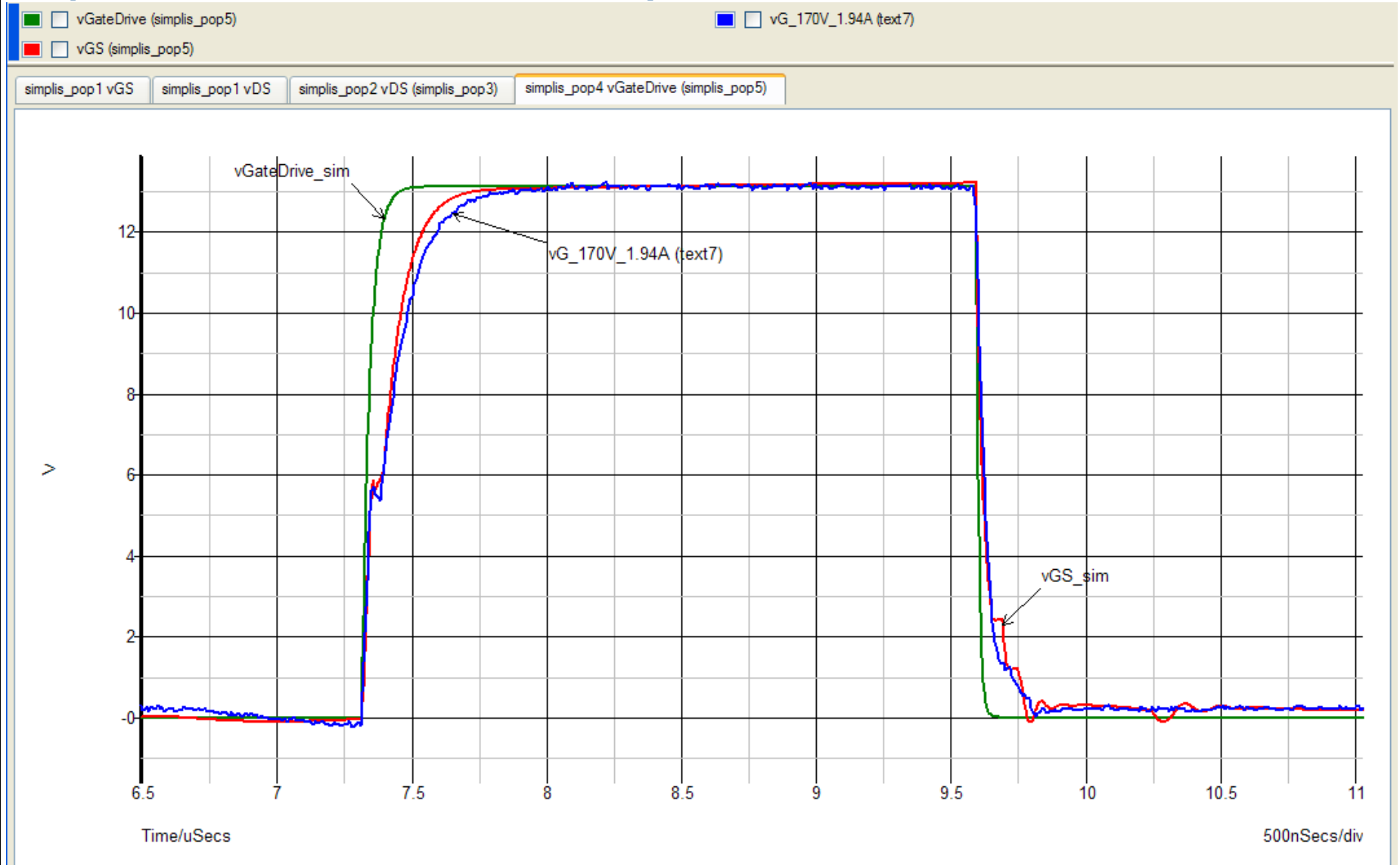
iD_170V_4.74A (text13) iD (simplis_pop8)
 vD_170V_4.74A (text12) vDS (simplis_pop8)

simplis_pop1 vGS simplis_pop1 vDS simplis_pop2 vDS (simplis_pop3) simplis_pop6 iD_170V_4.74A (text13)



Gate Voltage v_{GS}

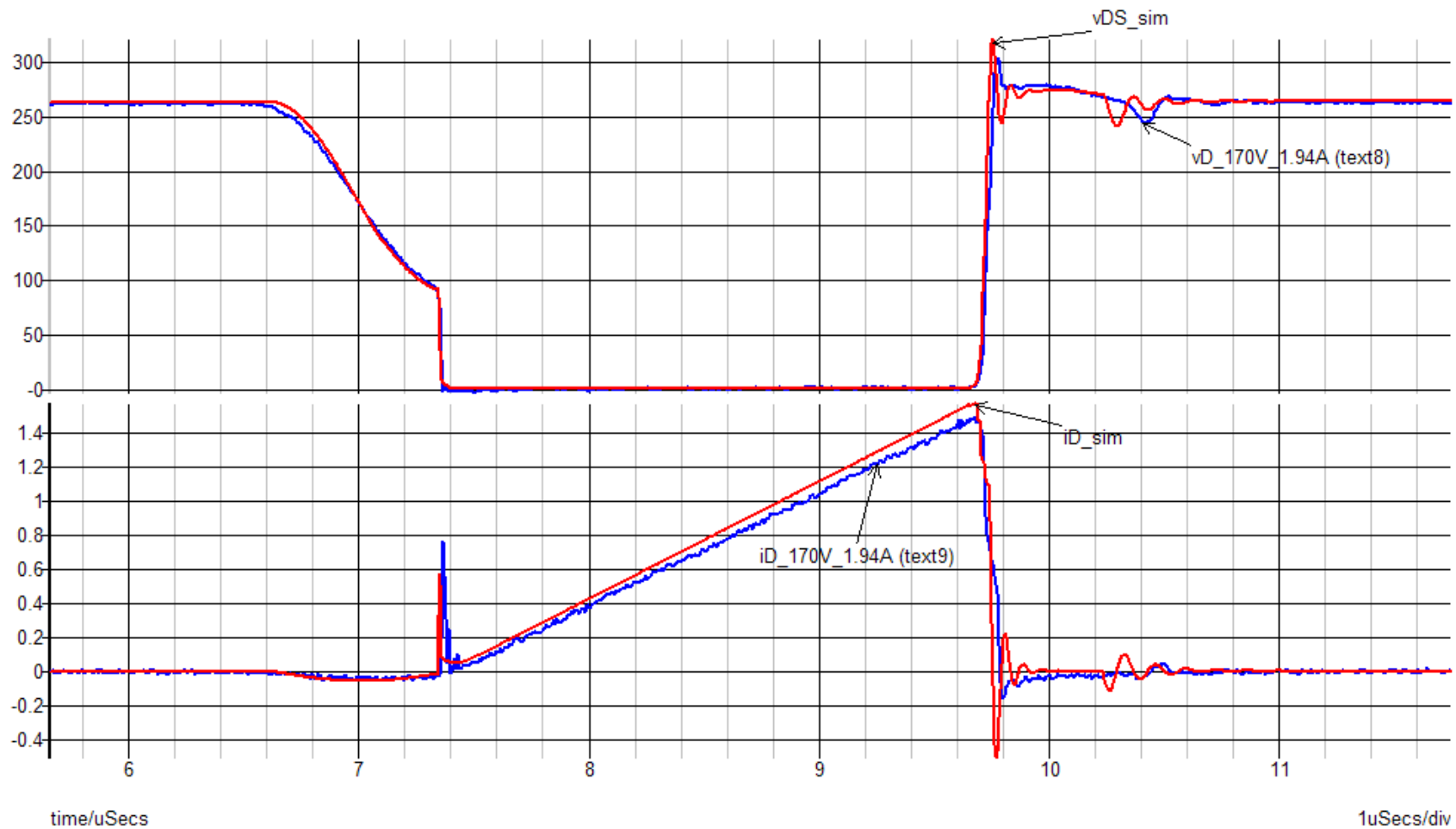
($V_{in} = 170V$, $I_{out} = 1.94A$)



Drain Voltage v_{DS} and Drain Current i_D ($V_{in} = 170V$, $I_{out} = 1.94A$)

- $i_{D_170V_1.94A}$ (text9)
- $v_{D_170V_1.94A}$ (text8)
- i_D (simplis_pop5)
- v_{DS} (simplis_pop5)

simplis_pop1 vGS simplis_pop1 vDS simplis_pop2 vDS (simplis_pop3) **simplis_pop4 $i_{D_170V_1.94A}$ (text9)**



Switching Losses (1)

- Can get very good matching between simulated and measured waveforms
 - We are capturing the important aspects of FET waveforms pretty well
 - With reasonable measurements of silicon device parasitics
 - With reasonable estimates of
 - layout parasitics
 - magnetic device parasitics

Switching Losses (2)

- Challenging to get sufficiently accurate ***measurements*** of vDS and iD to measure switching losses directly
- Would like better models for reverse recovery
 - First need better characterization data for devices
- Unknown layout parasitic can be estimated if have experience with similar packaging

Switching Losses (3)

Having said all that

- Simulation can do a better and faster job than most hand analysis of estimating:
 - Switching losses before first hardware build
 - Sensitivity of losses to various layout and device parasitics

Modeling Level vs. Simulation Objective and Device Type

Simulation Objective \ Device Type	Output Diode Rectifier	Output Capacitor (Electrolytic)	Output Capacitor (Ceramic)	Output Inductor	MOSFET Power Switch	
Switching Losses (FET) (Steady-State)						
Start up Transient (Transient analysis)						
Short Circuit (Steady-State, Transient analysis)						
Short Circuit & Recovery (Steady-State, Transient analysis)						

Modeling Level vs. Simulation Objective and Device Type

Simulation Objective \ Device Type	Output Diode Rectifier	Output Capacitor (Electrolytic)	Output Capacitor (Ceramic)	Output Inductor	MOSFET Power Switch	
Switching Losses (FET) (Steady-State)	3-seg	Lev 2	Lev 1	Linear Lossy	Lev 3	
Start up Transient (Transient analysis)	2-seg	Lev 2	Lev 1	Linear Lossy	Lev 1	
Short Circuit (Steady-State, Transient analysis)				Lossy w Sat		
Short Circuit & Recovery (Steady-State, Transient analysis)				Lossy w Sat		

Clear & Focused Simulation Strategy

Critical Success Factor for Virtual Prototyping

- Establish the Matrix showing the appropriate Model Levels for each Simulation Objective
- Verify / Modify Matrix for each new class of circuit

Modeling Level vs. Simulation Objective and Device Type

- This Matrix showing the appropriate Modeling Level for each Device Type for each Simulation Objective is
 - Typically applicable over a broad class of converter topology – control law combinations
 - Easy to summarize and share with larger design team
 - Can save a lot of confusion and bring engineers new to power supply simulation up the learning curve much faster
 - Can save a lot of simulation time and still deliver required simulation accuracy

Time is the most precious resource (1)

- Speed is essential to test for all “known” electrical design errors in a reasonable time
- You won’t find design errors that you don’t look for
- A comprehensive Test Plan includes hundreds of simulation tests.
- Want to invest simulation time where it will do the most good
- Need a clear and focused Test Plan that executes your Simulation Strategy

Time is the most precious resource (2)

- During the course of design and design verification testing you will hit the “Simulate” button ~ thousand times
- Using higher complexity models than you need to achieve your simulation objectives just wastes your time

Modeling Level vs. Simulation Objective and Device Type

Simulation Objective \ Device Type	Output Diode Rectifier	Output Capacitor (Electrolytic)	Output Capacitor (Ceramic)	Output Inductor	MOSFET Power Switch	
Bode Plot (Steady-State, AC analysis)	2-seg	Lev 2	Lev 1	Linear Lossy	Lev 1	
Step Load Transient – moderate di/dt (Steady-State, Transient analysis)	2-seg	Lev 2	Lev 1	Linear Lossy	Lev 1	
Step Load Transient – high di/dt (Steady-State, Transient analysis)	2-seg	Lev 3	Lev 1	Linear Lossy	Lev 1	
Line and Load Regulation (Steady-State analysis)	3-seg*	Lev 2	Lev 1	Linear Lossy	Lev 1	

Observations

- Note that many of the Design Verification Tests that you will be doing start out in steady state
- It is often much faster to do more targeted simulations than fewer “Test Everything” simulations
- Some modeling strategies that work well for Spice are counter productive with SIMPLIS

Virtual Prototyping of Power Supply Designs

- Virtual Prototyping Process
 - From 3 Perspectives:
 - Power Supply Designer
 - **Power Management IC Architect**
 - Power System Designer

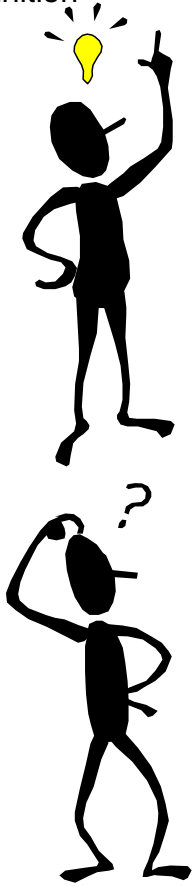
Controller IC-centric view of world where customers are Power Supply and Power System Designers

New Product Definition for Power Management ICs

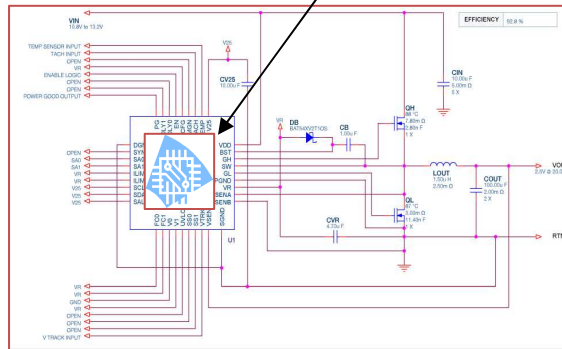
- Significant Process Trend
 - Use of SIMPLIS PWL simulation behavioral model to define new products
 - Create behavioral models that describe all critical features
 - Thoroughly test PWL behavioral model of proposed new product in system application circuit
 - Over whole anticipated application space
 - Compare results with customer system specs

Traditionally

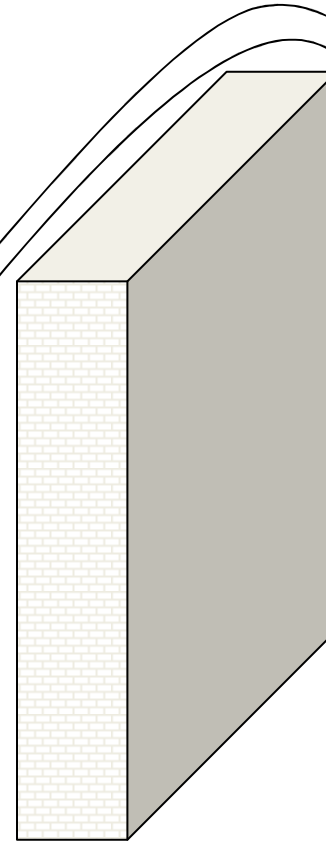
New Product Definition



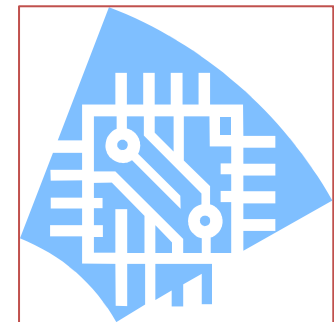
New Product Architect



Test & Verification



IC Designer



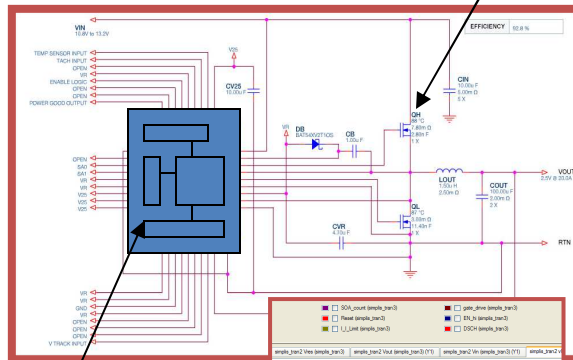
IC Design

With SIMPLIS PWL Virtual Prototype

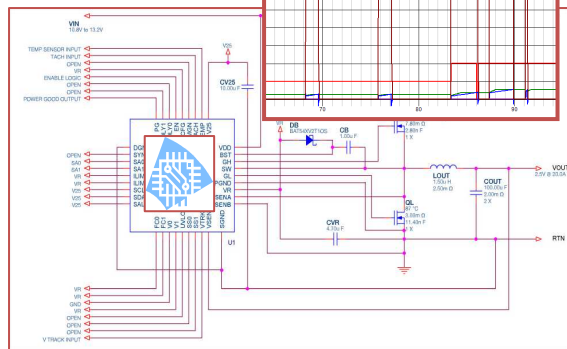
New Product Definition



New Product Architect
Application Schematic

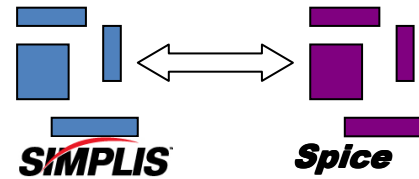


SIMPLIS IC Building blocks

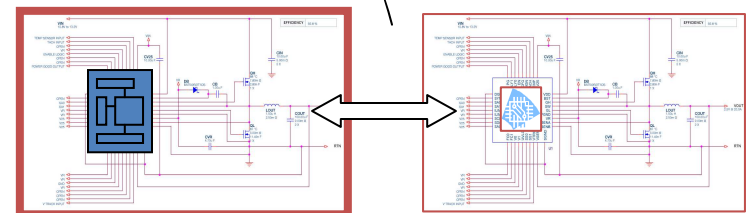


Test & Verification

IC Designer



IP Block Mapping



New Product Definition

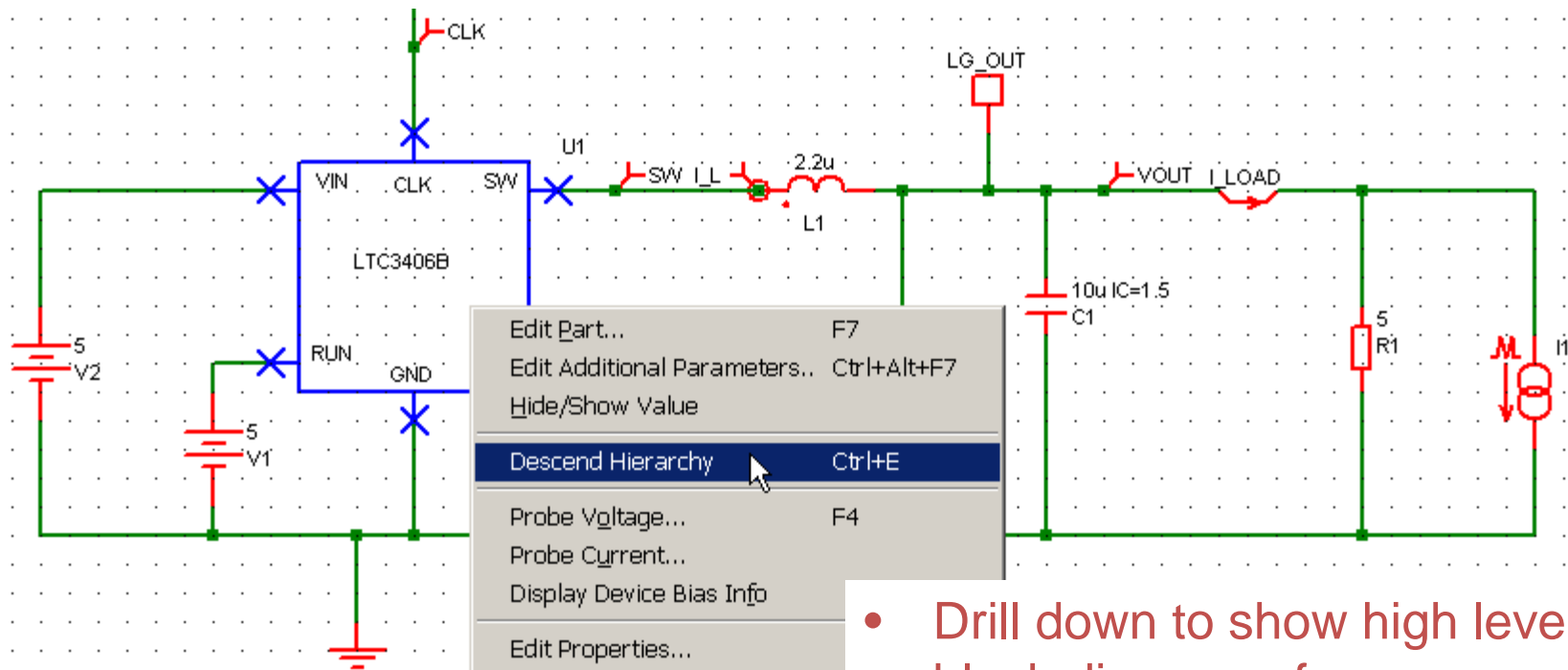
SIMPLIS PWL Behavioral Models

- Provides much crisper new product definition between System Engineer and IC Circuit Designer
- New Product Definition includes:
 - Clear relationship between IC spec and system level performance
 - Clear definition of Top level IC architecture
 - Quantitative specs (delays, waveforms, rise/fall times, bandwidth) of each input/output for each major element in Block Diagram
 - Clear architecture of critical blocks



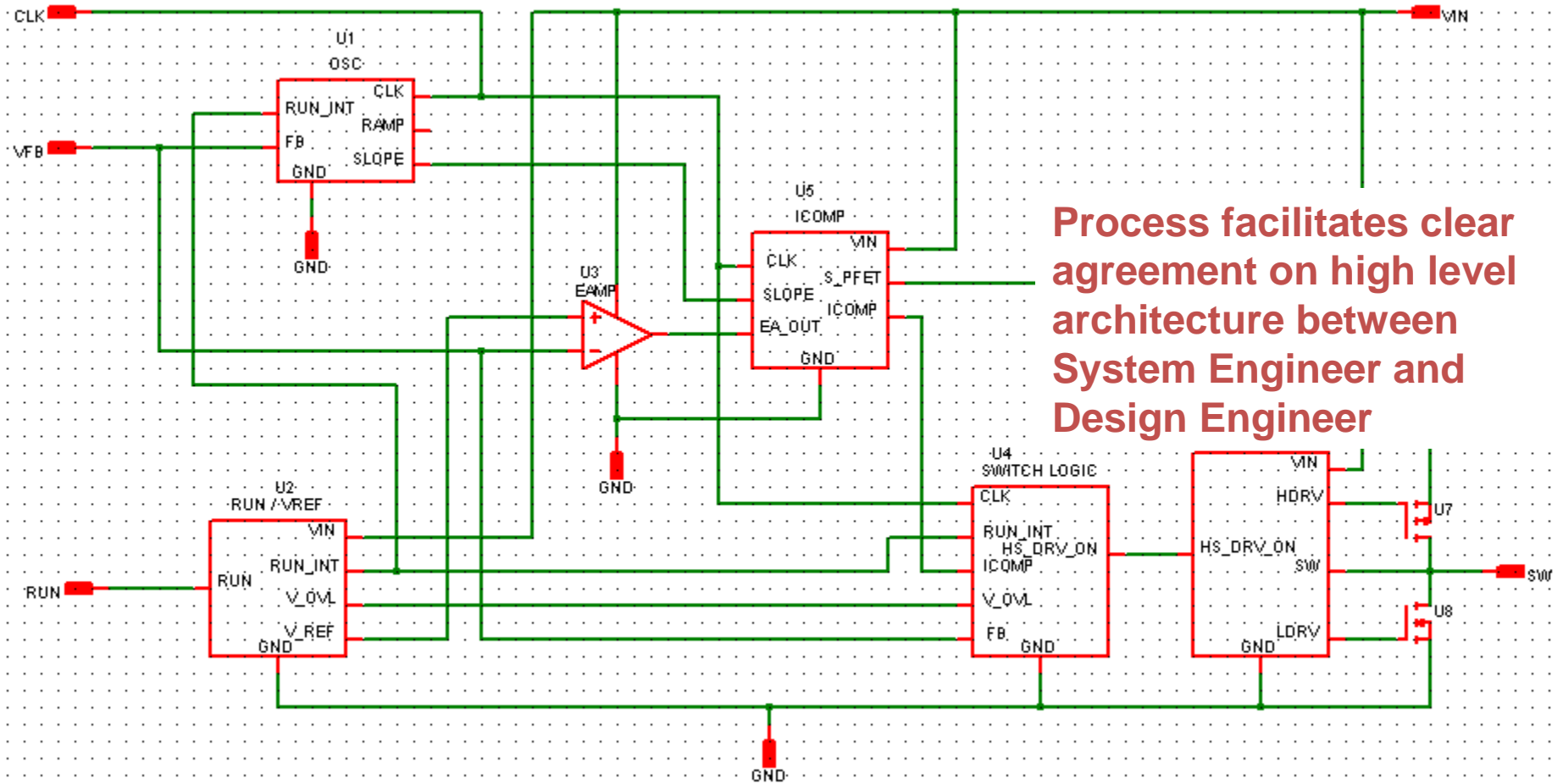
Use SIMPLIS models to define new product architecture at functional block level

- Proposed new product in the target application circuit



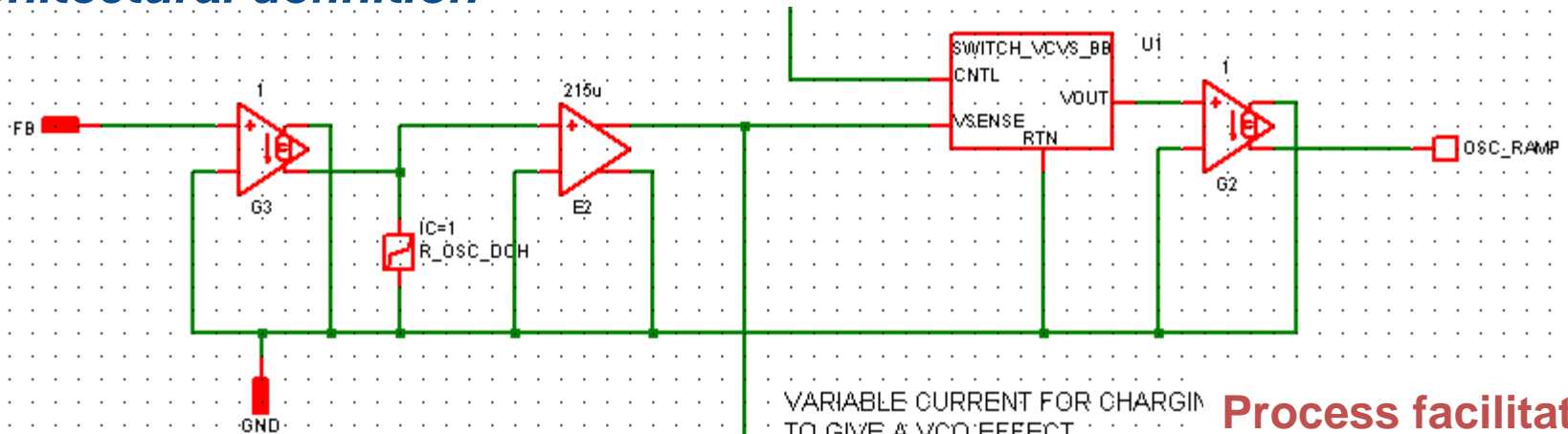
- Drill down to show high level block diagram of new proposed product architecture

High Level Block Diagram corresponds to desired IC architecture



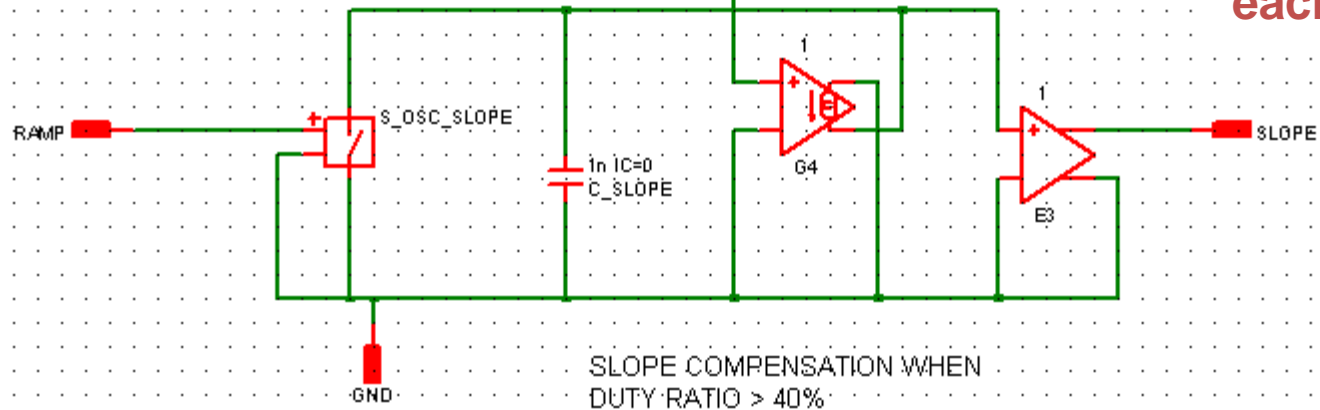
Process facilitates clear agreement on high level architecture between System Engineer and Design Engineer

Each Functional Block in the High Level Diagram contains its own Architectural definition



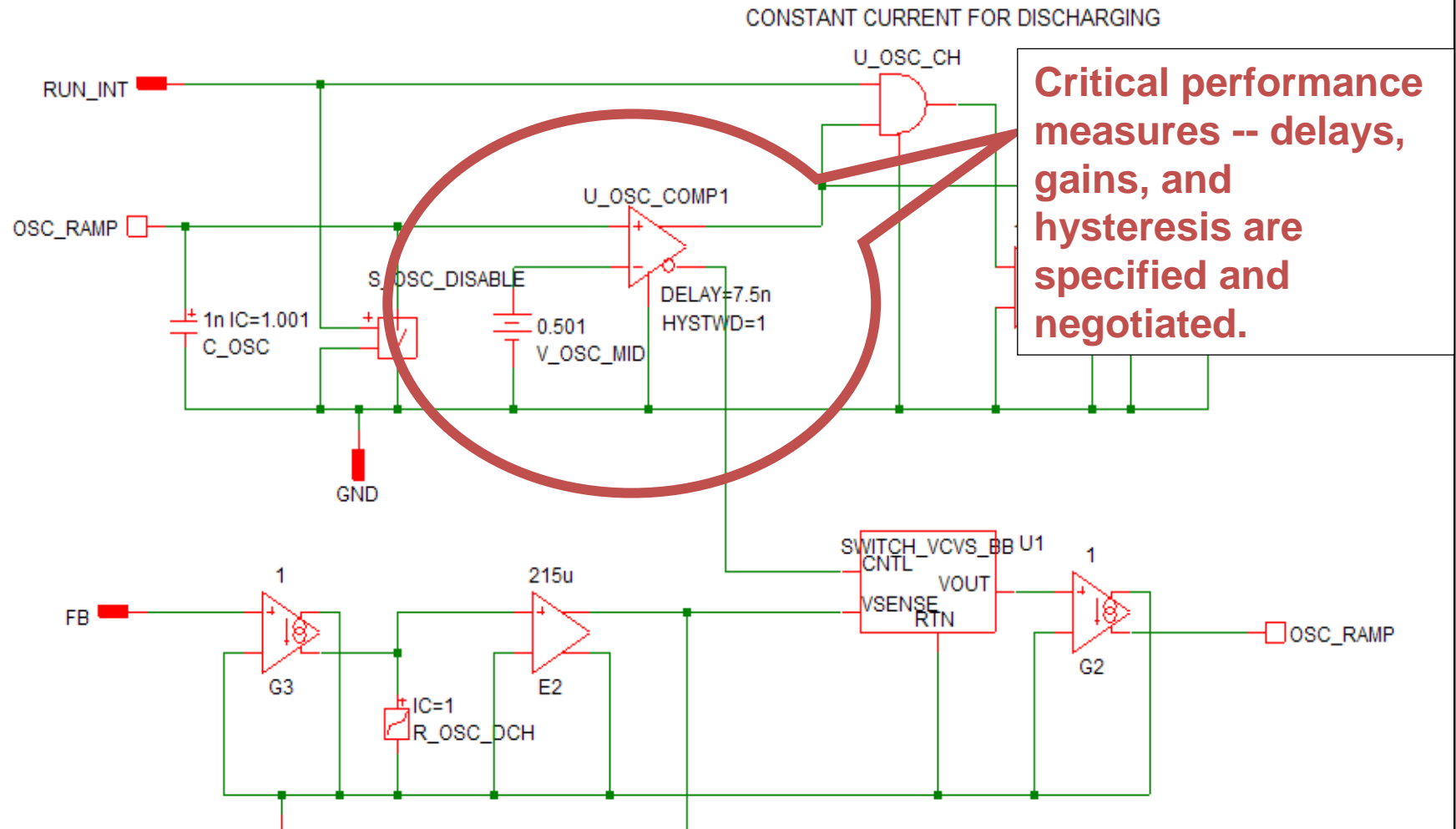
VARIABLE CURRENT FOR CHARGIN
TO GIVE A VCO EFFECT

Process facilitates
clear agreement
on architecture of
each major block

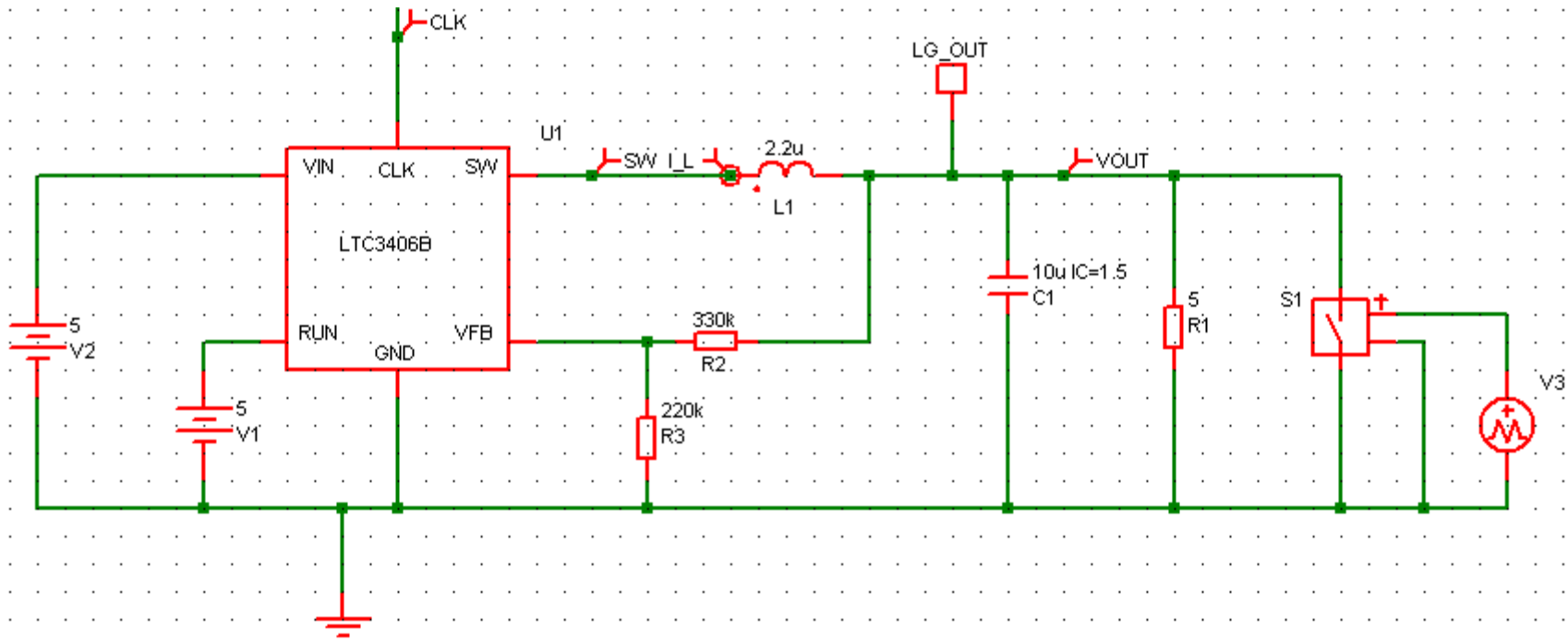


SLOPE COMPENSATION WHEN
DUTY-RATIO > 40%

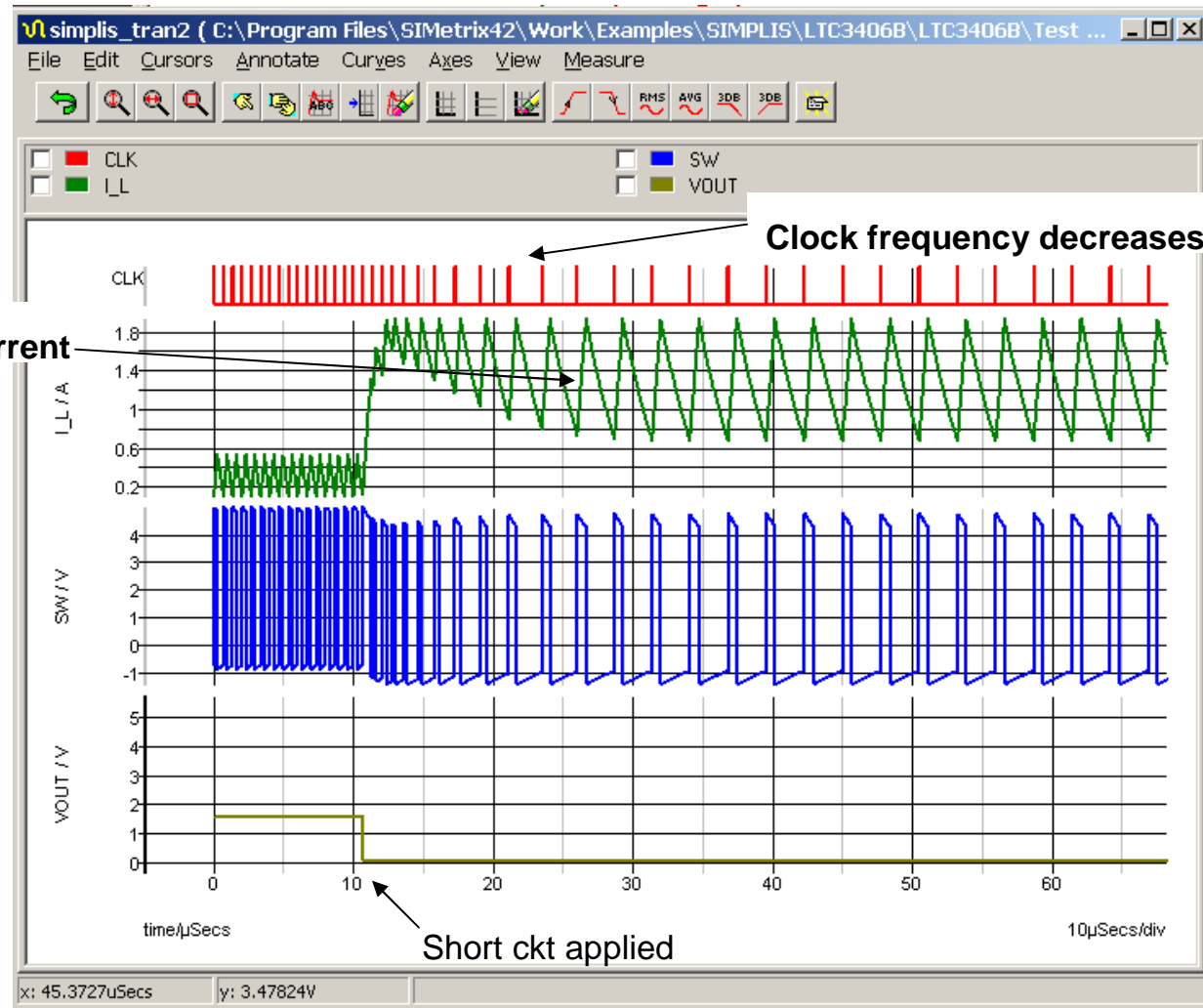
In each Block, Critical Gains, Delays and Hysteresis can be modeled to..



... explore how IC design parameters impact overall system performance of the final application



... under all application conditions, such as short circuit ...



Short circuit Inductor Current

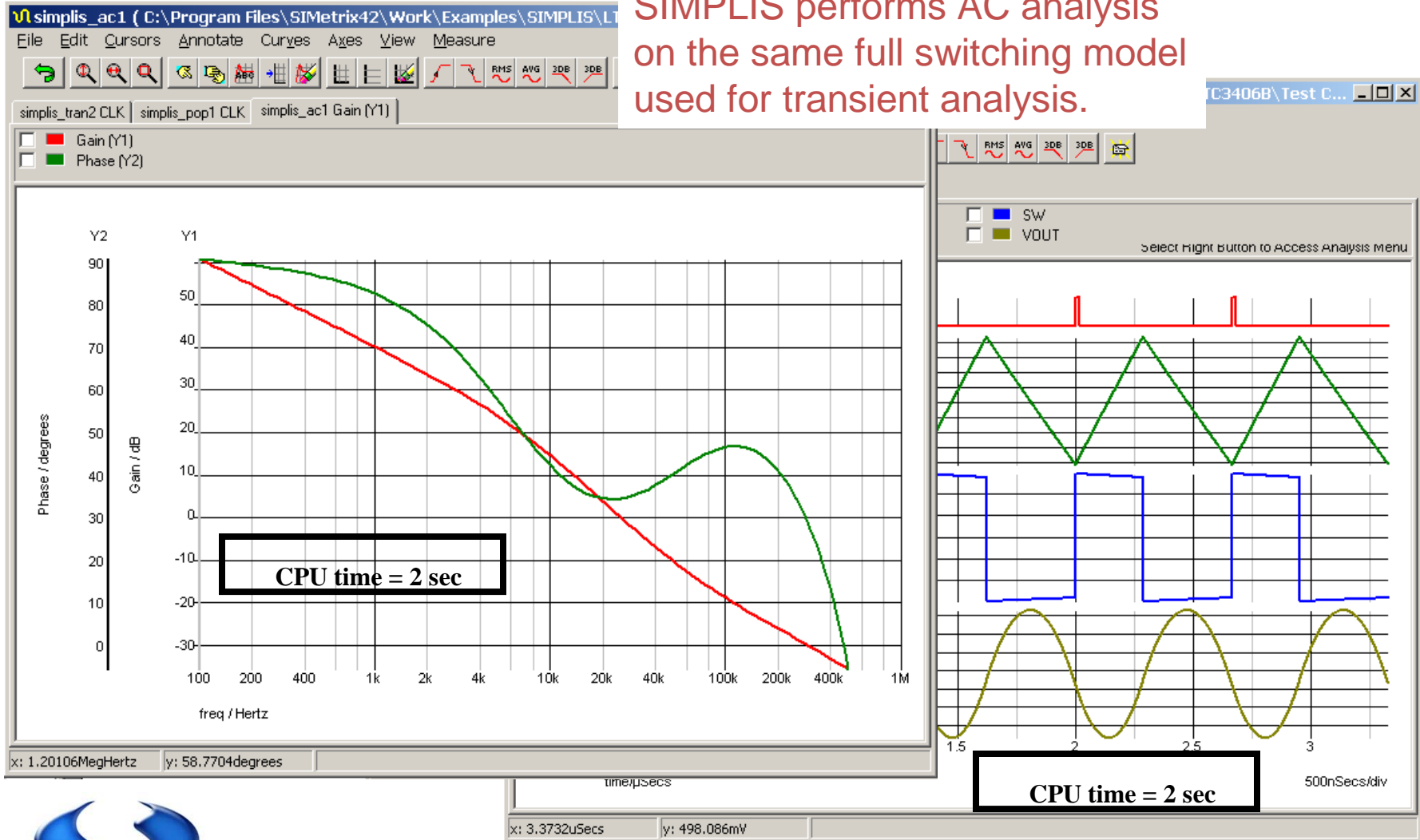
Clock frequency decreases

SIMPLIS is very fast
CPU time = 2 sec

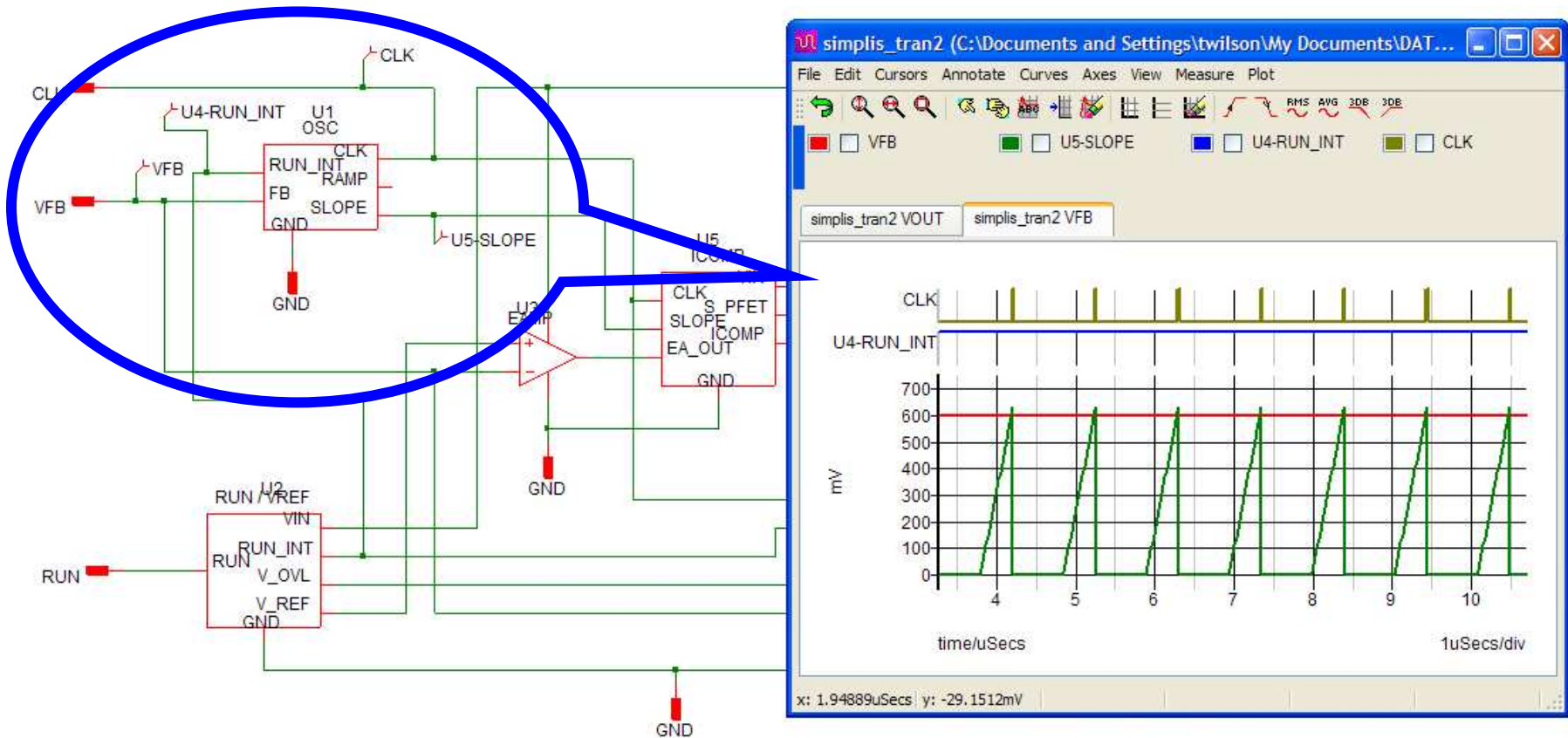


... and small signal stability.

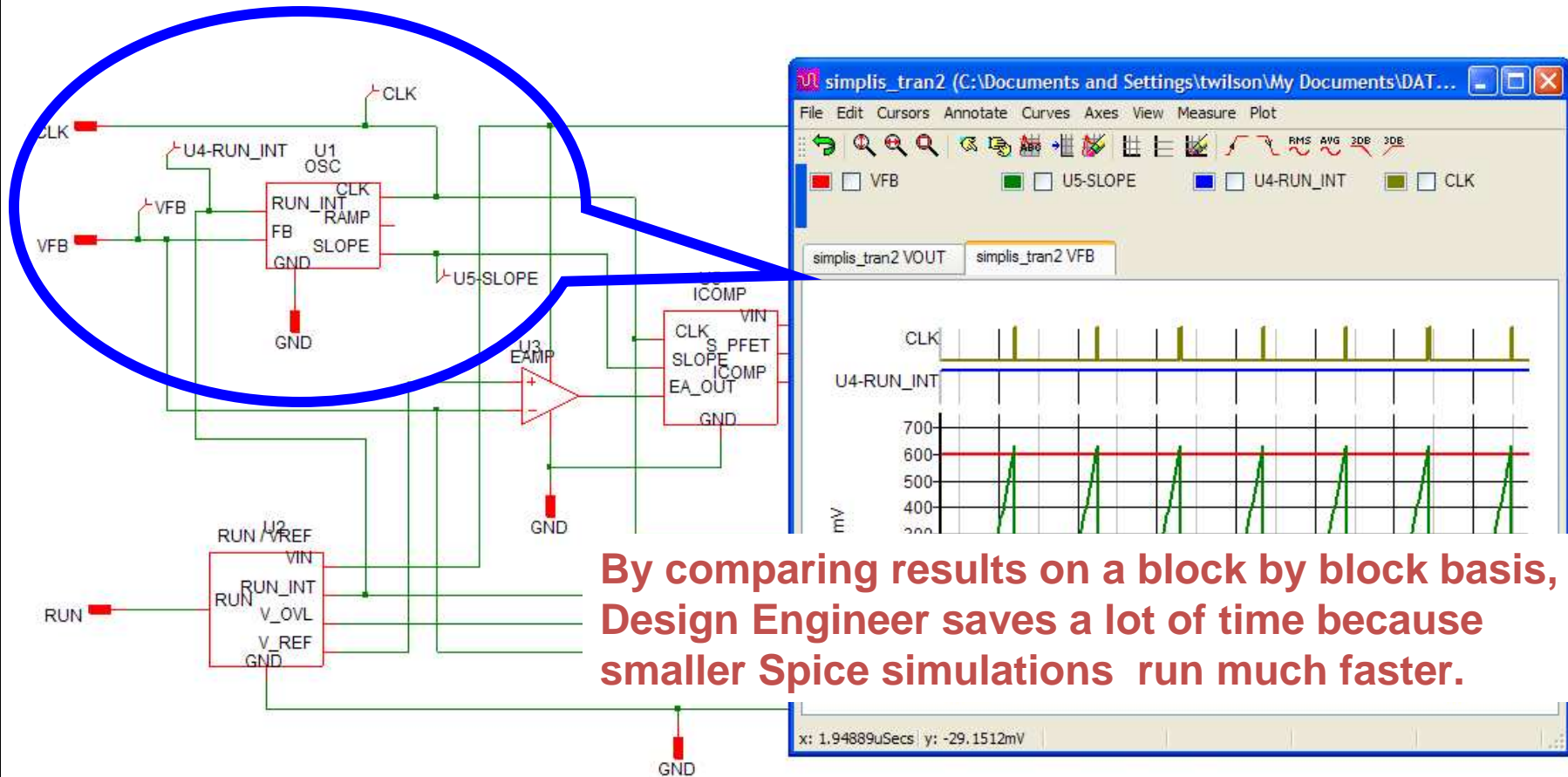
SIMPLIS performs AC analysis on the same full switching model used for transient analysis.



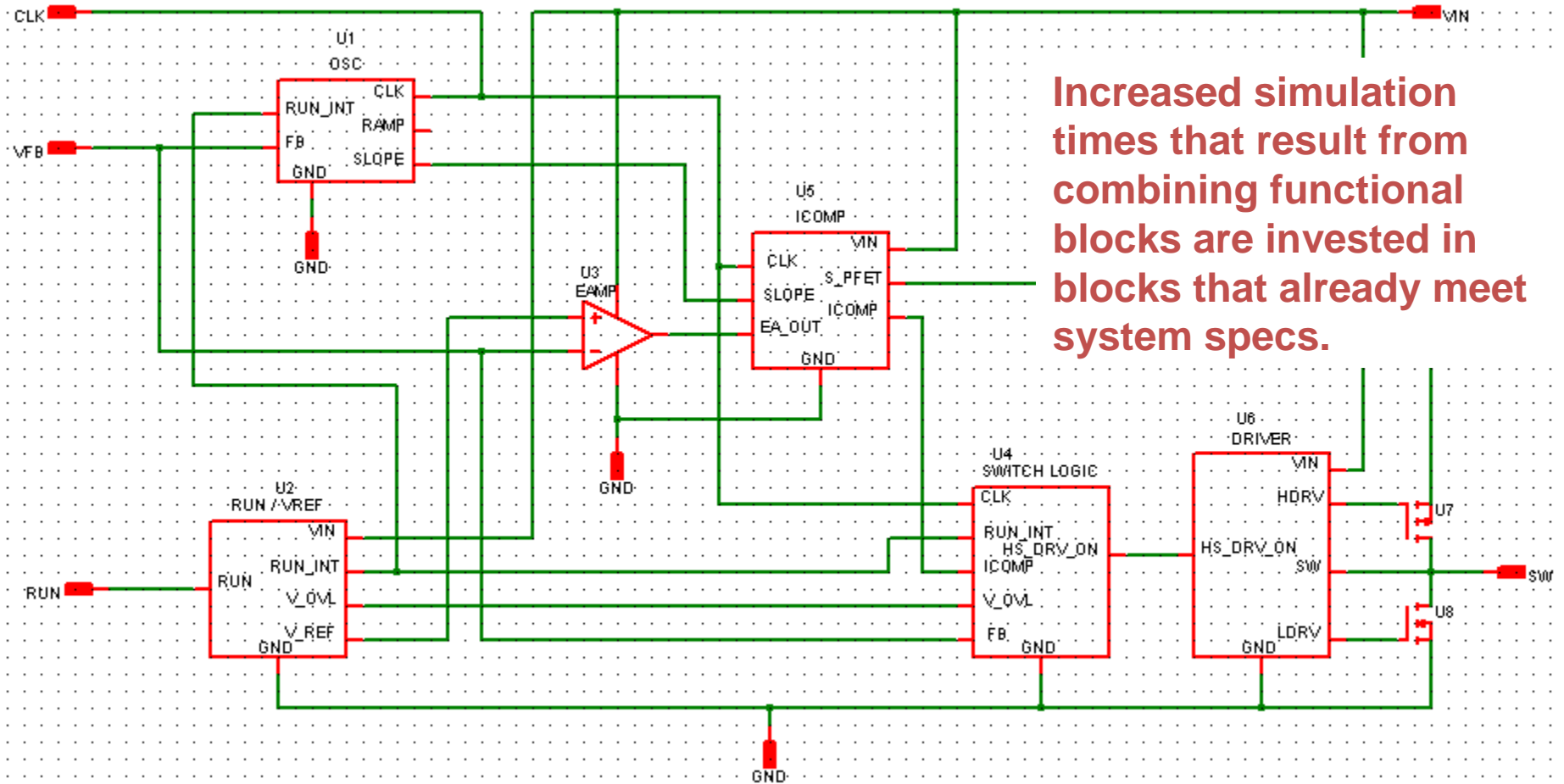
Clear I/O specs are generated for each Functional Block



Compare Spice vs. SIMPLIS results for each Functional Block



Combine Spice Blocks once they all meet individual Block specs



Increased simulation times that result from combining functional blocks are invested in blocks that already meet system specs.

New Product Definition

SIMPLIS PWL Behavioral Models

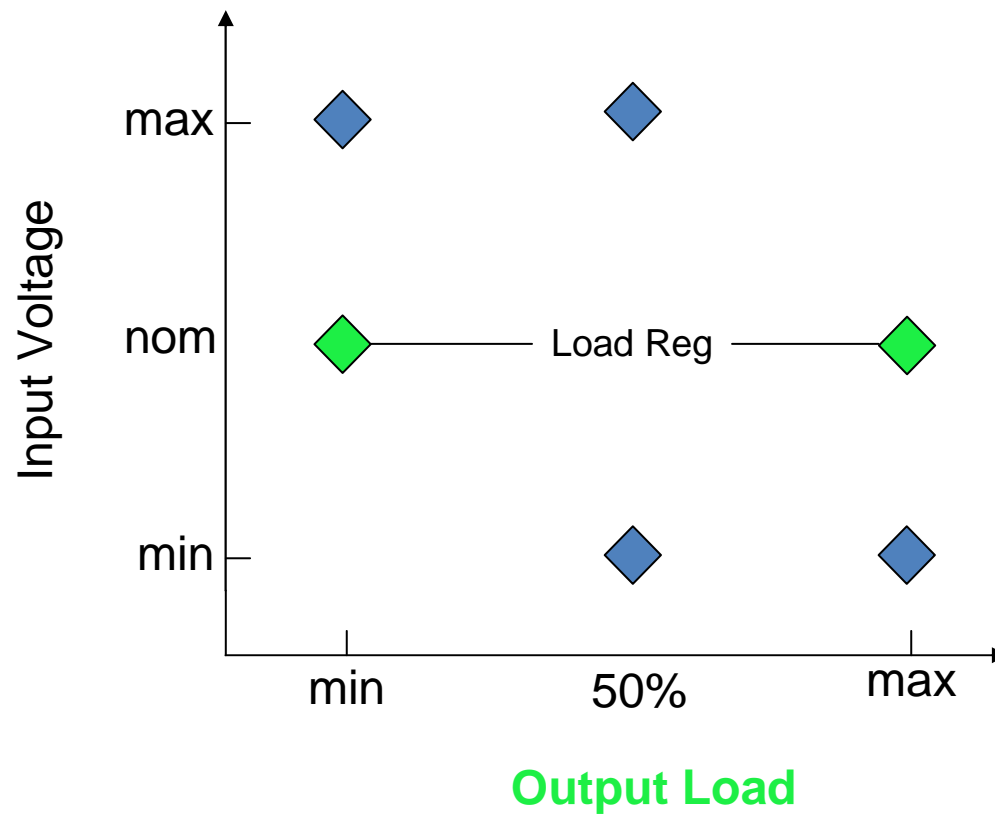
- Quantitative specs on block by block basis reduces “dark interval” between spec handoff and IC design results
 - Ability to quantitatively compare Spice and SIMPLIS results on block by block basis
 - gives much more confidence that design is going in desired direction
- Very focused partnership between System Engineer and Design Engineers
 - Each concentrates on their value-added activities
 - Deviations from plan become visible to all parties very early in process
 - Allows clear delineation of responsibilities



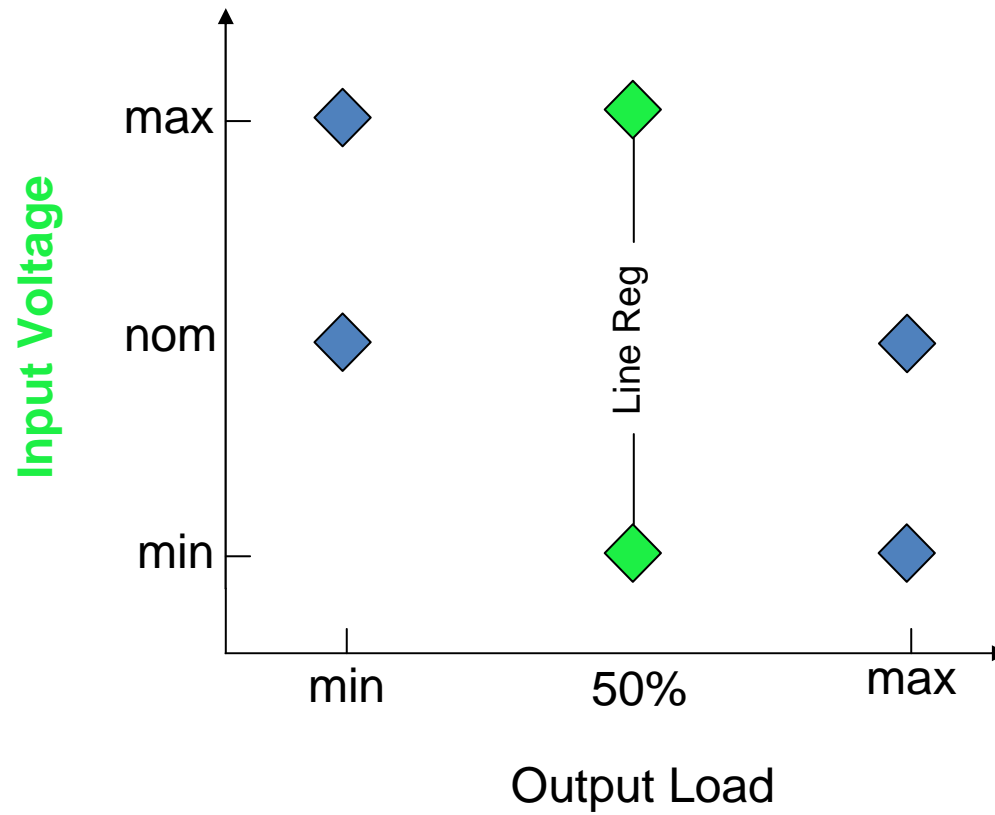
Virtual Prototyping -- some practical considerations

- To capture the full benefit of Virtual Prototyping, need to quickly verify New Product Definition performance over entire application space
- Example: Single Phase Synchronous Buck
 - What would a comprehensive Test Plan look like?*
 - How many tests per line and load range scenario?
 - How long would it take to complete?
 - What kind of results would be available?

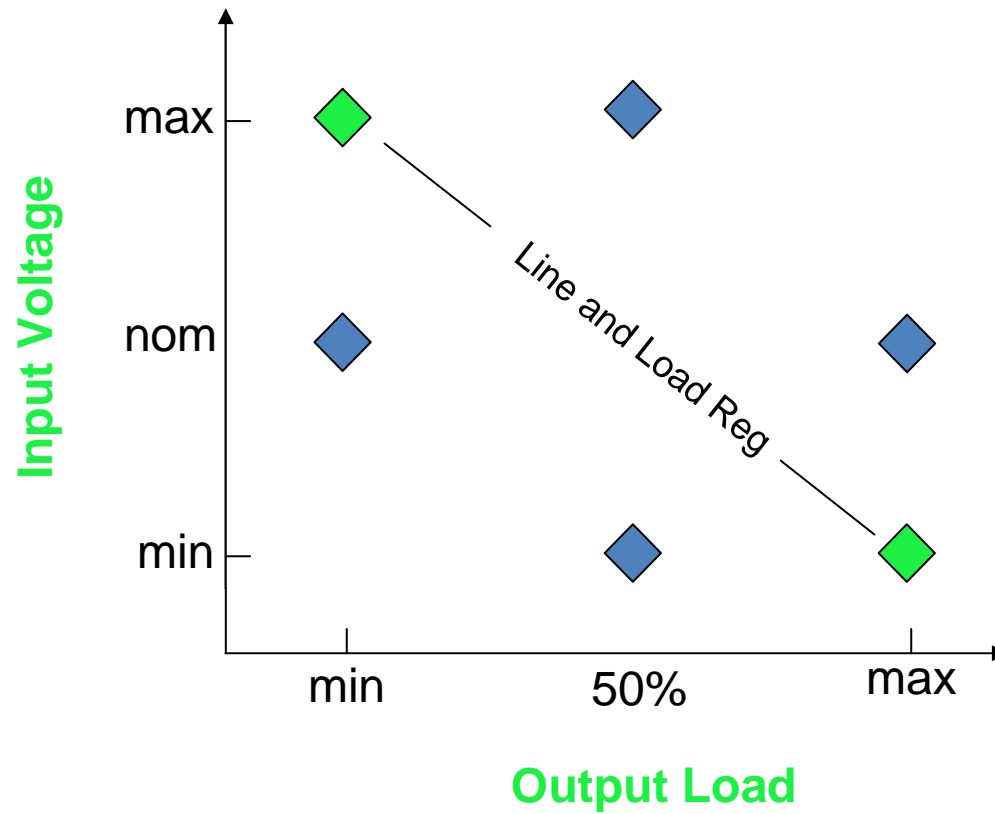
Load Regulation



Line Regulation



Line & Load Regulation



Virtual Prototyping -- some practical considerations

- To capture the full benefit of Virtual Prototyping, need to quickly verify New Product Definition performance over entire application space
- Example: Single Phase Synchronous Buck
 - What would a comprehensive Test Plan look like?
 - How many tests per line and load range scenario?
 - Our Sync Buck Test Plan has ~ 130 individual simulations
 - How long would it take to complete?
 - ~ 10 min
 - What kind of results would be available?

Virtual Prototyping -- some practical considerations

- By applying PWL analysis, Multi-level modeling, and clearly focused simulation objectives
 - Now able to obtain accurate performance results over full application space in reasonable time
- Each test still requires
 - Configuration & execution
 - Results analysis & comparison with specs
 - Summary Report with links to detailed results
- When test mechanics > simulation time, automation can add value

Challenges for Virtual Prototyping

- Testing for all “known” design issues generates mountains of sim results
 - Need help organizing and sifting through test results
 - Drinking from this fire hose is not an exercise for the faint of heart
- Making results visible to entire design team reduces chances that important test results are overlooked

Virtual Prototyping -- some practical considerations

- Example: Single Phase Synchronous Buck
 - How approach Sensitivity & Worst Case analysis?
 - How many simulations to complete?
 - How much time?
 - How does this compare with Monte Carlo?

ISL70001

- Designers have indentified approximately 58 circuit parameters that should be included in a comprehensive Worst Case analysis
- Sensitivity Analysis => (58 + 1) sims per Objective Function
- Worst Case Analysis => (2 + 1) sims per Objective Function

With ~10 Objective functions => 620 sims

Design Verification Testing

- As Virtual Prototypes become more central to development efforts
 - there will be a need for tools to support the engineer in finding the important information amid large volume of data that will be generated
 - Automated comparison of results with requirements
 - Top-down reports with results viewable by entire design team

Design Verification Testing for Digital Control

- Design Definition
 - Discrete time, but infinite resolution
- Design Verification
 - Discrete time and include quantizing effects

Virtual Prototyping of Power Supply Designs

- Virtual Prototyping Process
 - From 3 Perspectives:
 - Power Supply Designer
 - Power Management IC Architect
 - **Power System Designer**

Virtual Prototyping for System Engineers

- Approximately 50% of system engineers are involved with designing on-board synchronous buck regulators
 - Same issues as all power supply designers
- Another big effort is working with vendors who supply critical power system functions like AC-DC Front Ends, Adapters, DC-DC Modules, etc.
 - Design Verification is big part of this responsibility
 - Virtual Prototyping is playing an increasingly important role in Vendor relationship

Virtual Prototyping and Power Supply Vendor Relationships

- Increasingly, Virtual Prototyping is being used to verify Vendor designs earlier and earlier in the process
- Some Systems Houses are beginning to require Virtual Prototype results as part of the RFQ response
- Virtual Prototypes are assuming a more important role in the Vendor relationship

Virtual Prototyping for System Engineers

- More Systems Houses are using Virtual Prototypes to resolve Power System level issues
 - Currently, detailed switching models work well for one or two power stages
 - Simulators are not able to handle simulation of many power stages with full detailed models
 - Power System simulation (with full detailed models) is coming, but not here yet

Summary (1)

- Virtual Prototyping
 - is becoming an increasingly important part of new product development process
 - Power Supply Designers
 - IC Controller Architects
 - Power System Engineers
 - represents the biggest design process improvement opportunity for many organizations

Summary (2)

- Maximizing Virtual Prototyping effectiveness requires
 - a clear and focused simulation strategy
 - an explicit simulation objective for every simulation
 - a corresponding understanding of the appropriate modeling level required to achieve simulation objective in reasonable simulation time
 - a comprehensive Test Plan that explicitly looks for known potential design faults
 - an effective way to communicate simulation strategy and test plans to the entire design organization

Summary (3)

- Virtual Prototypes are very effective in capturing closed loop system behavior
- We are getting smarter about how to use Virtual Prototypes to address device stresses and losses
- New tools needed to help manage the bookkeeping challenges posed by comprehensive Virtual Prototyping

Thank you!

Download Circuits and Materials:

<http://simplistechnologies.com/downloads/apec2010>

